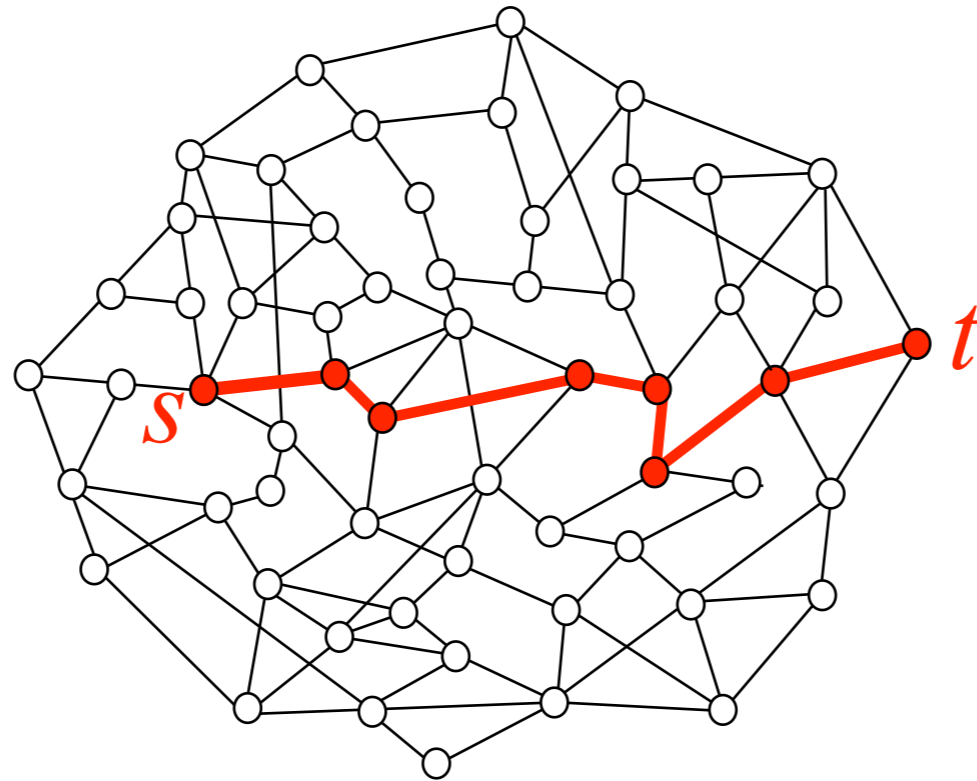


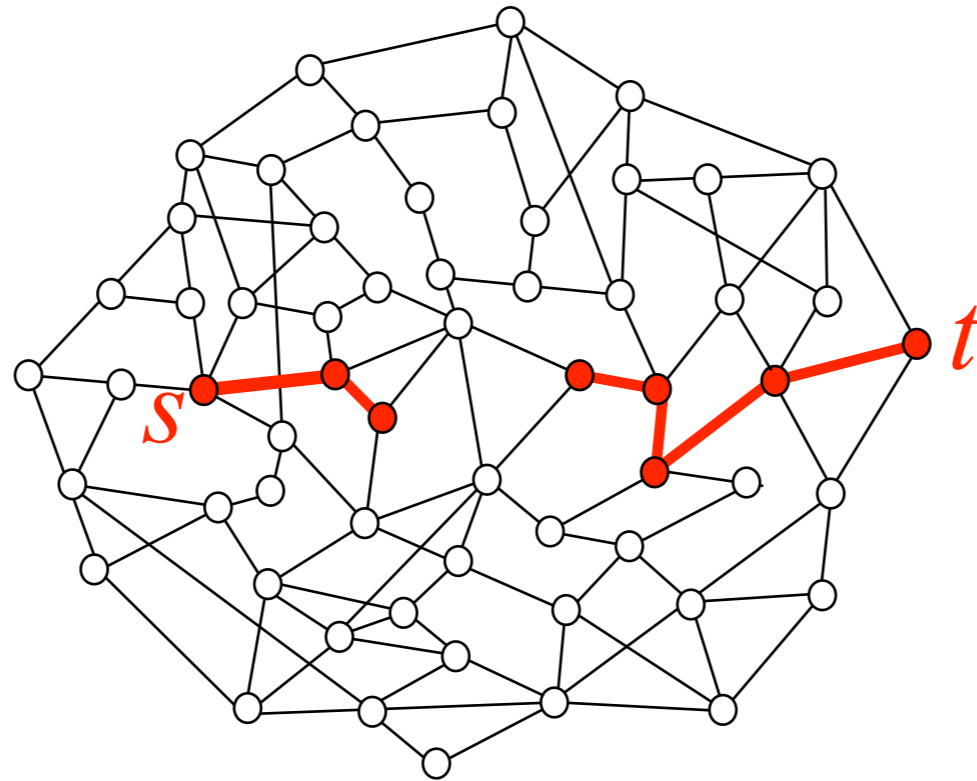
The Replacement Paths Problem



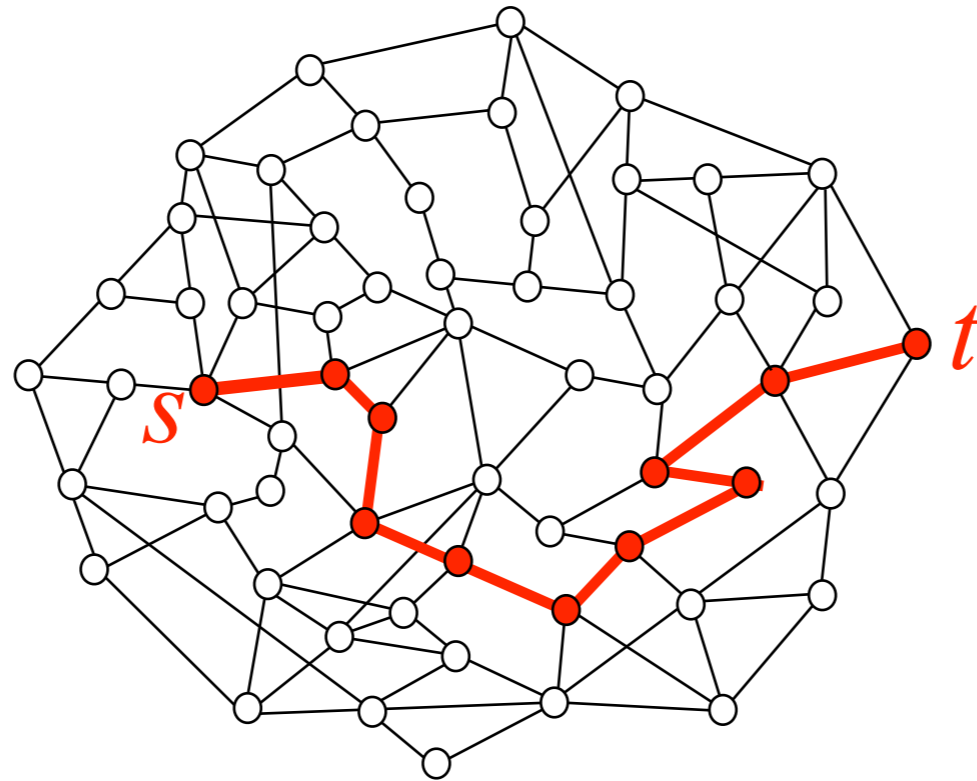
Oren Weimann

Raphy Yuster

The Replacement Paths Problem



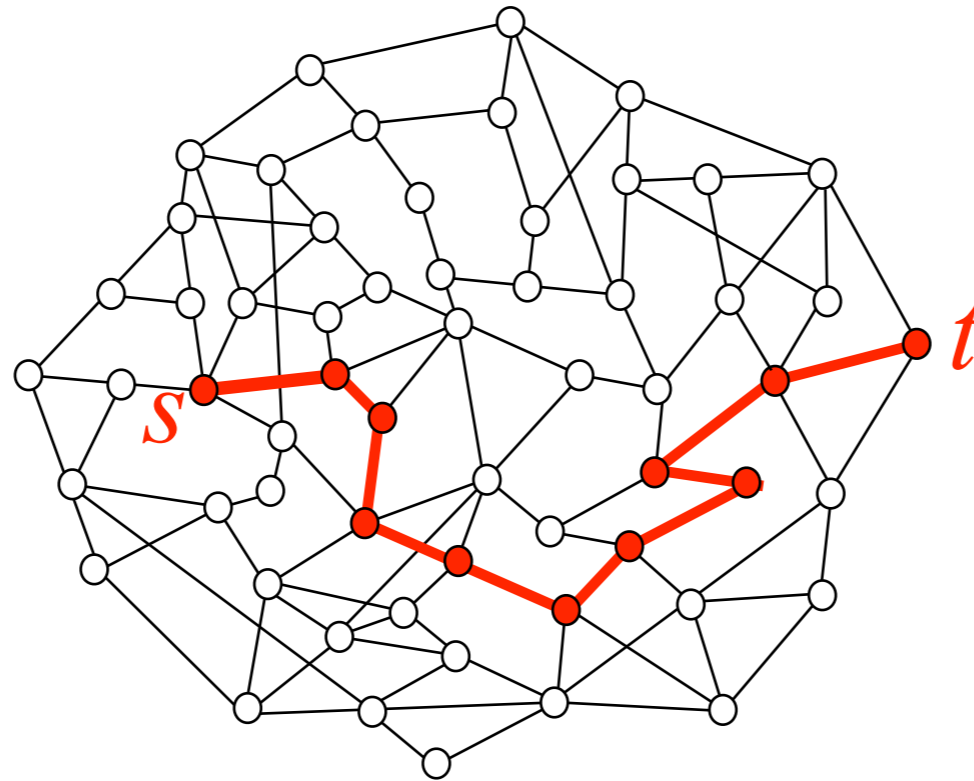
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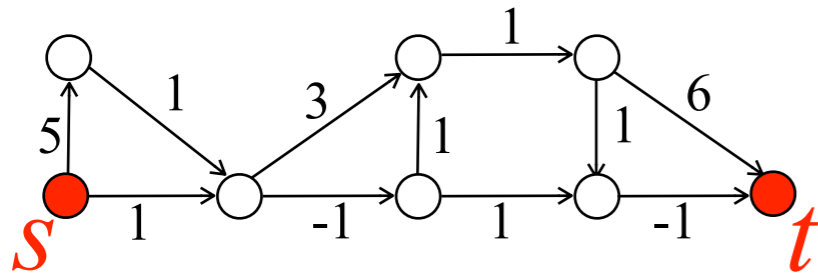
The Replacement Paths Problem



Vickrey pricing of edges owned by selfish agents

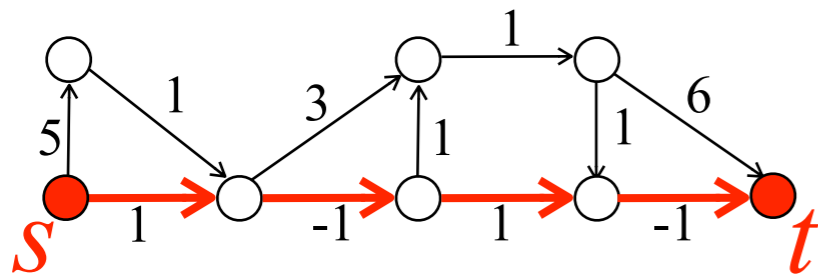
The Replacement Paths Problem

- General directed graphs
- Positive and negative lengths



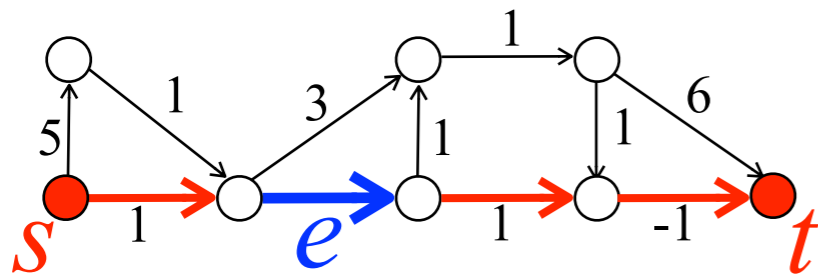
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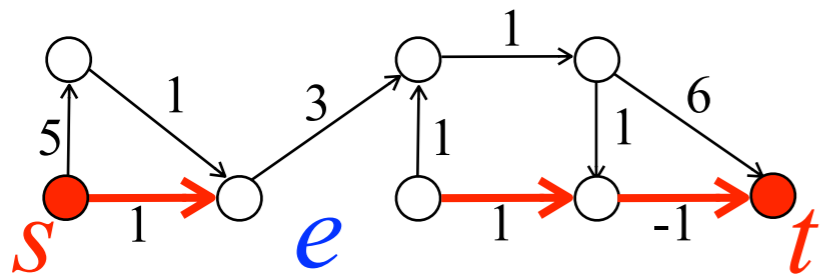
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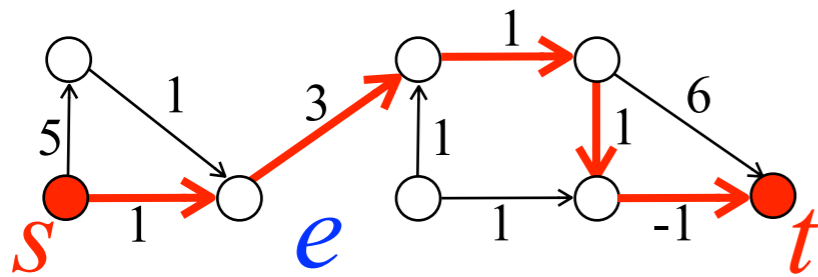
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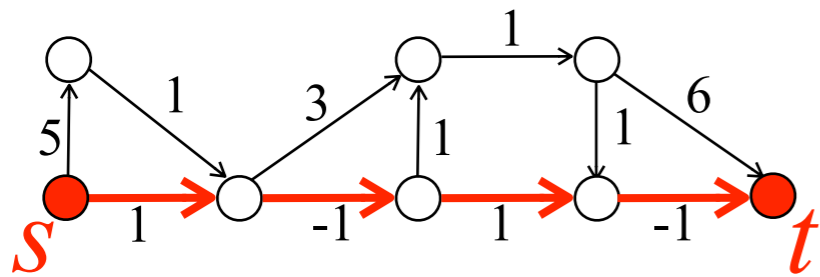


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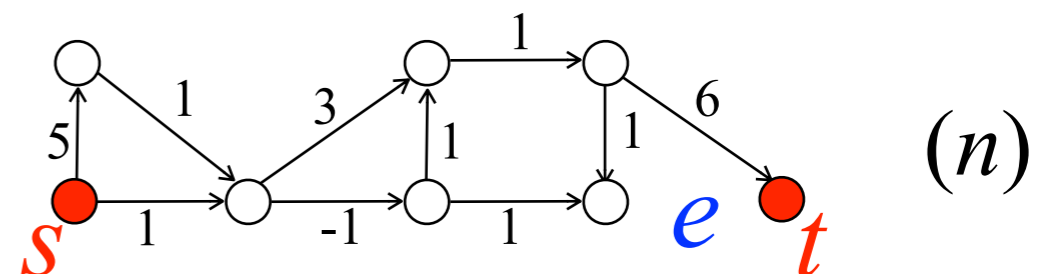
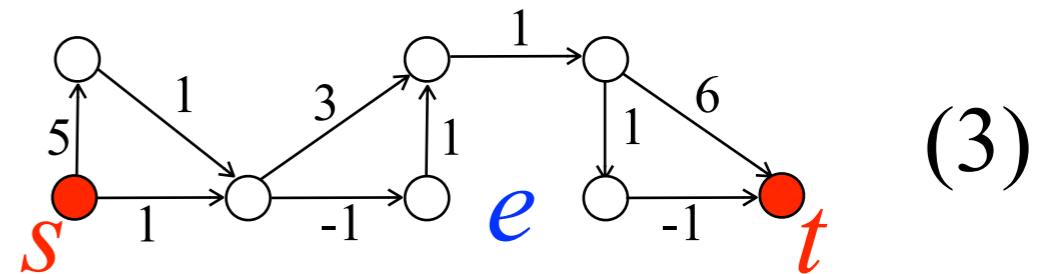
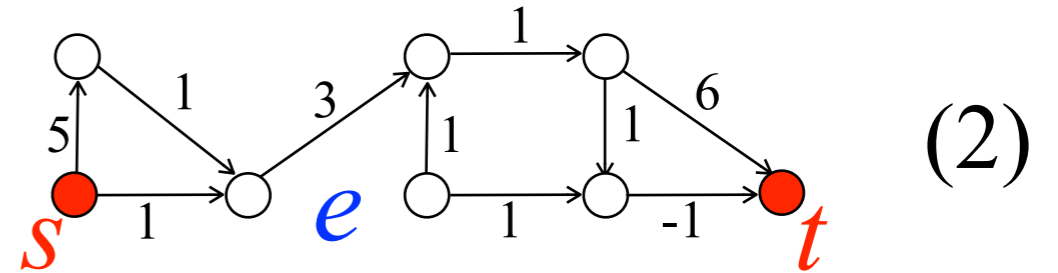
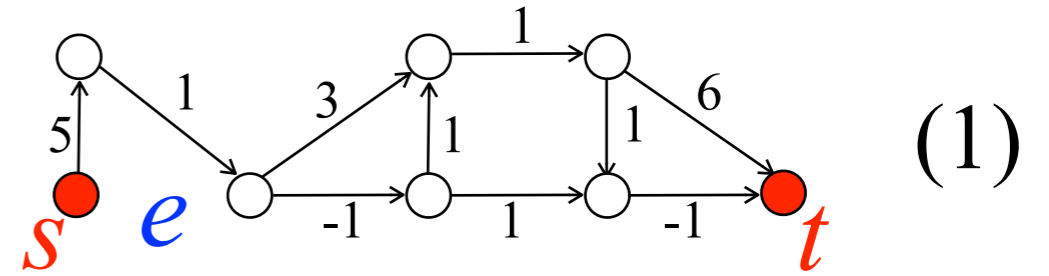
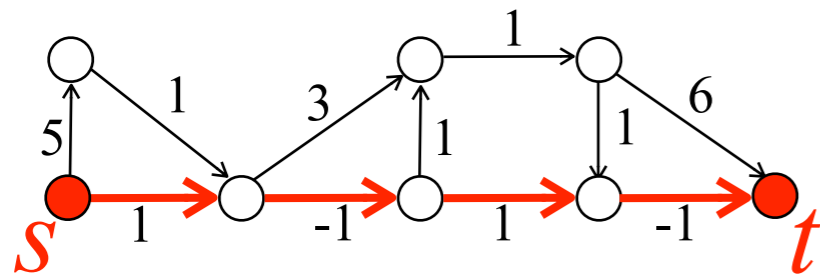
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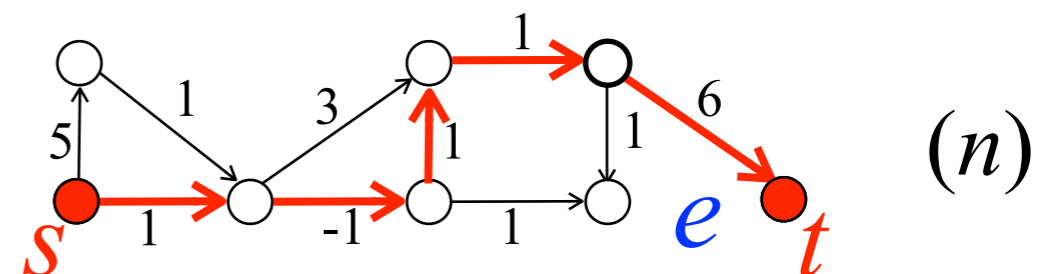
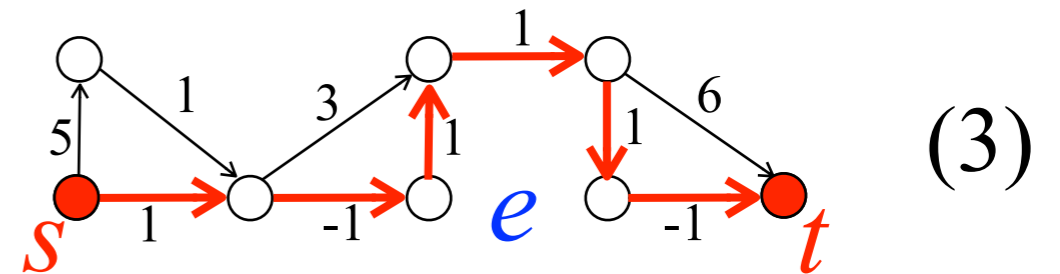
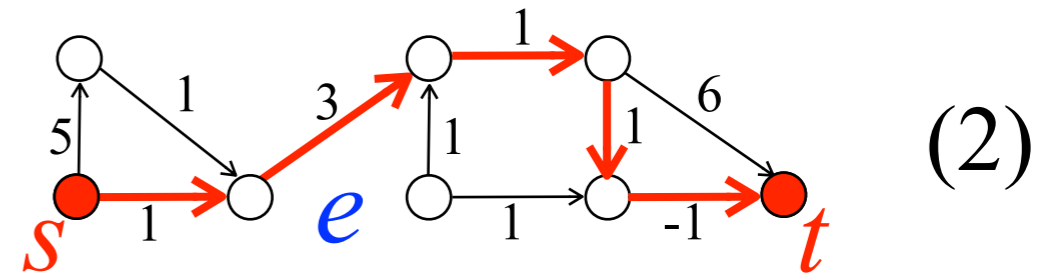
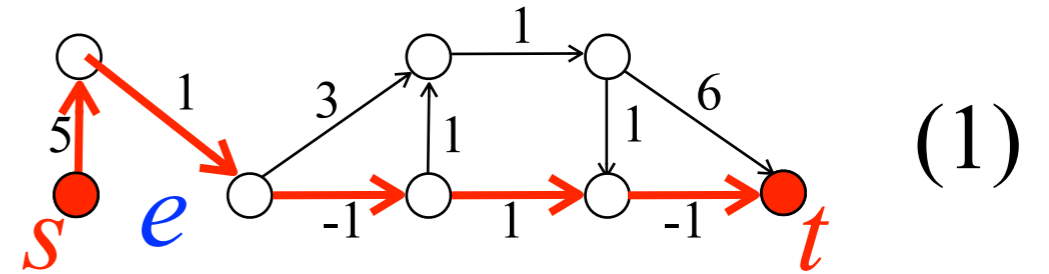
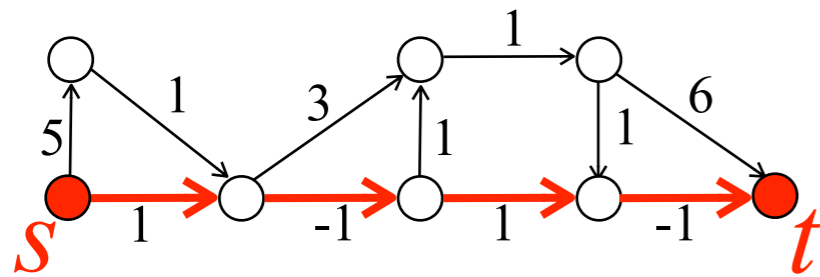
A Naive Solution



A Naive Solution

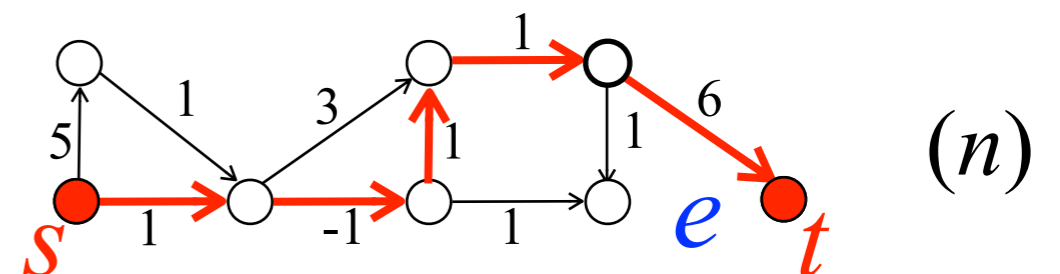
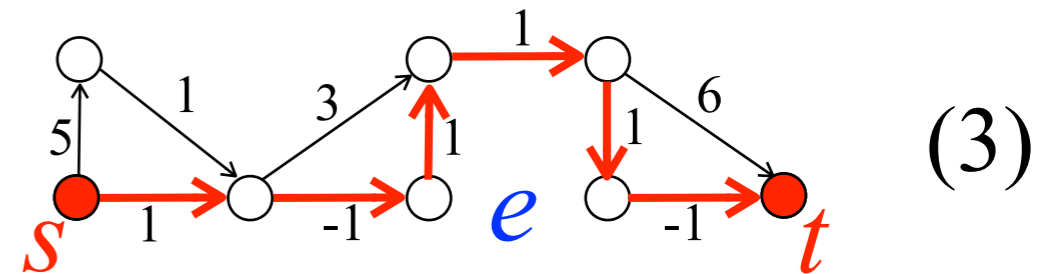
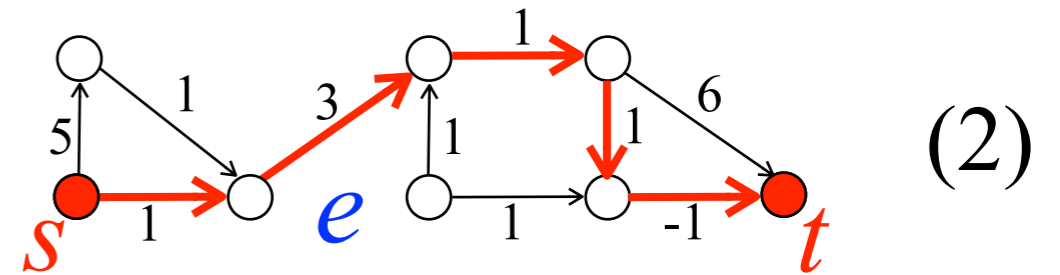
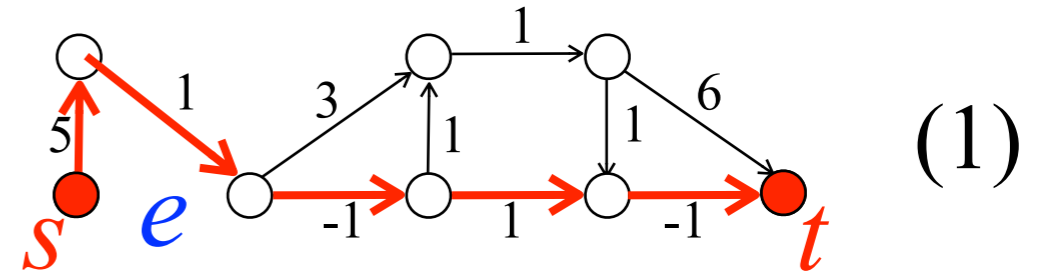
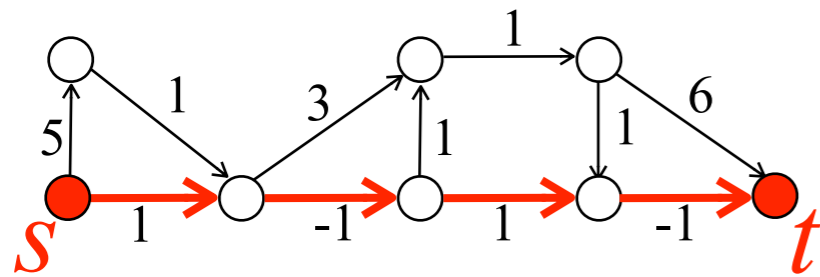


A Naive Solution



A Naive Solution

$$O(nm + n^2 \log n) = O(n^3)$$



Related Work

Directed weighted graphs:

- $O(nm + n^2 \log n)$ - naive solution
- $O(nm + n^2 \log \log n)$ - [Gotthilf, Lewenstein 2009]
- $\Omega(m\sqrt{n})$ lower bound - [Hershberger 2003]
- $\tilde{O}(m \log(nM)/\varepsilon)$ for $(1+\varepsilon)$ -approximation - [Bernstein 2010]
- $\tilde{O}(Mn^{1+2\omega/3}) = O(Mn^{2.584})$ for weights in $\{-M, \dots, M\}$ - [Yuster, W.]

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Undirected graphs:

- $O(m + n \log n)$ - [Malik, Mittal, Gupta 1989]
- $O(m\alpha(n, m))$ - [Nardelli, Proietti, Widmayer 2001]

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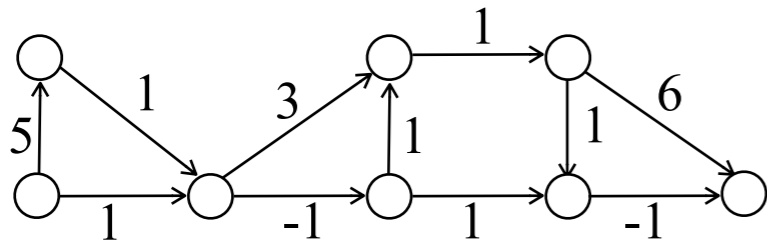
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Unweighted graphs:

- $\tilde{O}(m\sqrt{n})$ - [Roditty and Zwick 2005]

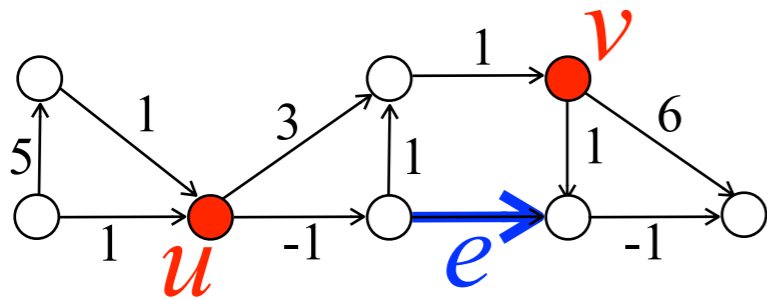
The Replacement Paths Problem

All Pairs



The Replacement Paths Problem

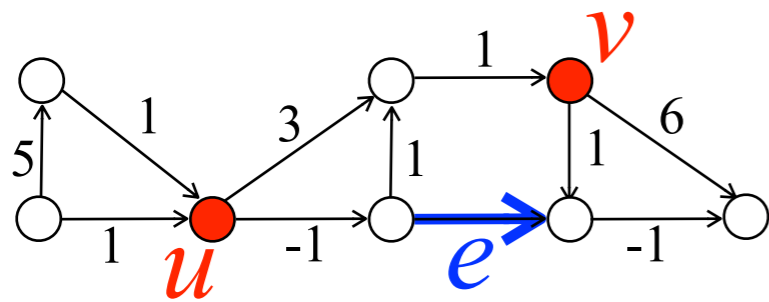
All Pairs



Query: (u, v, e) ?

The Replacement Paths Problem

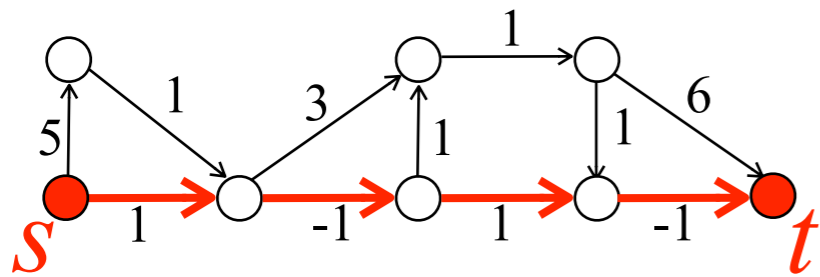
All Pairs



Query: (u, v, e) ?

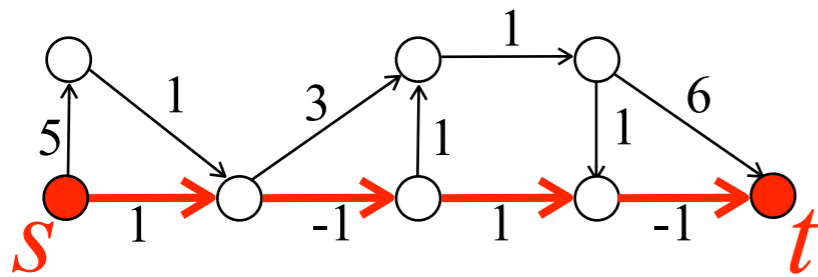
- $\tilde{O}(mn^2)$, constant query time
[Demetrescu, Thorup, Chowdhury, Ramachandran 2008]
- $\tilde{O}(mn)$, constant query time
[Bernstein, Karger 2009]
- Poly., $O(\log n)$ query time, 2 failures
[Duan, Pettie 2009]
- Poly., $\tilde{O}(f)$ query time, f failures
constant-approximation
[Chechick, Langberg, Peleg, Roditty 2009]
- $\tilde{O}(Mn^{1+\omega-\alpha})$, $\tilde{O}(n^{1+\alpha})$ query time, f failures
[Yuster, W.]

A Replacement Paths Algorithm



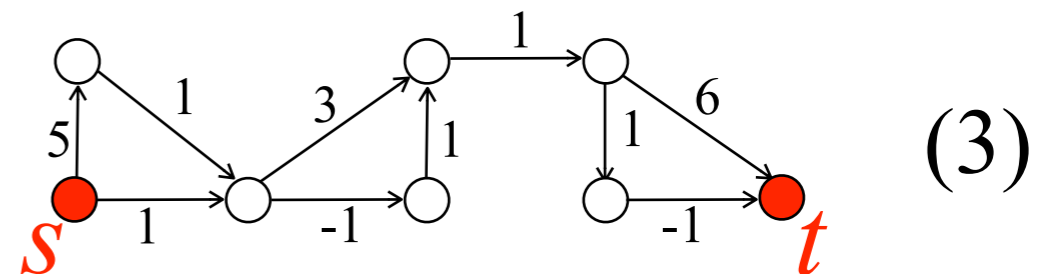
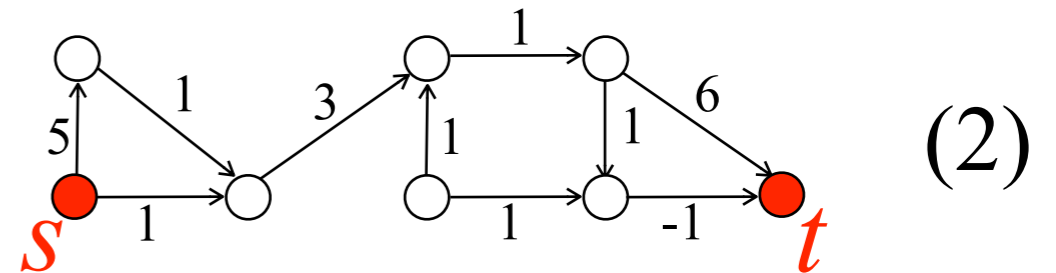
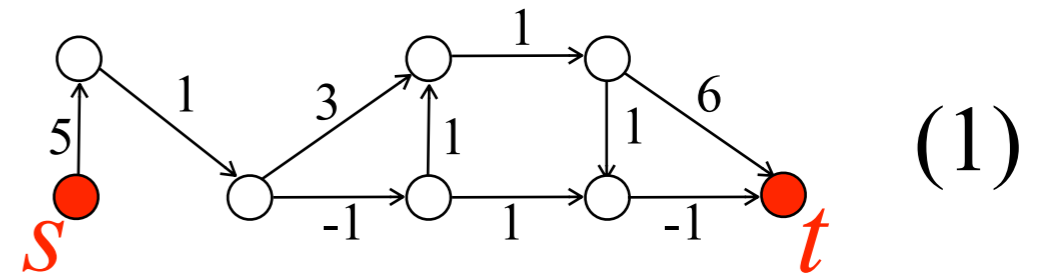
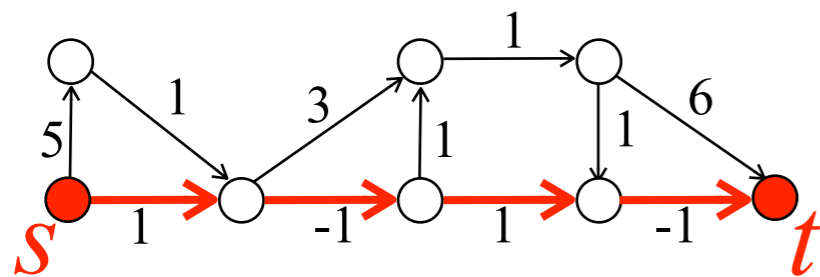
A Replacement Paths Algorithm

- Success probability $1-1/n$



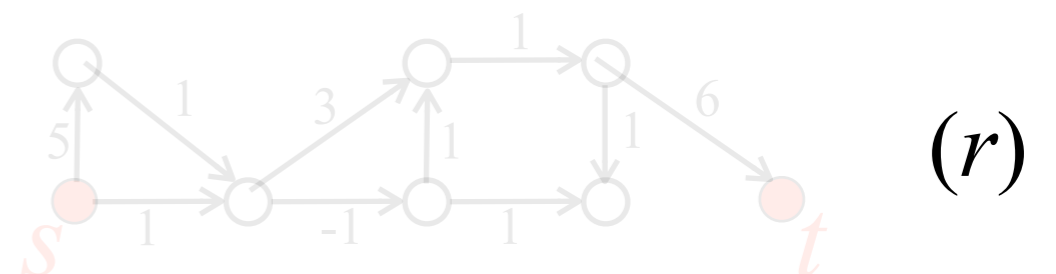
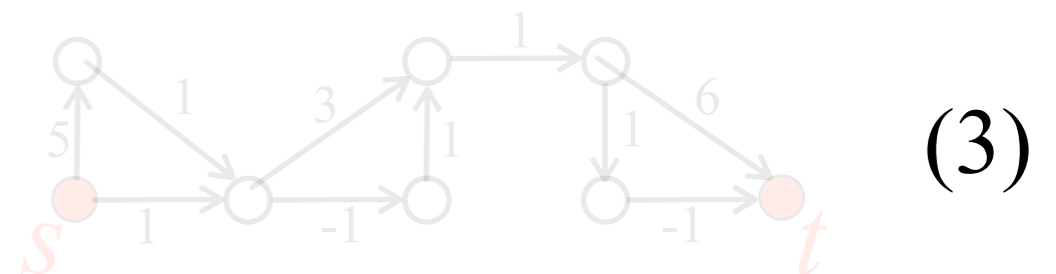
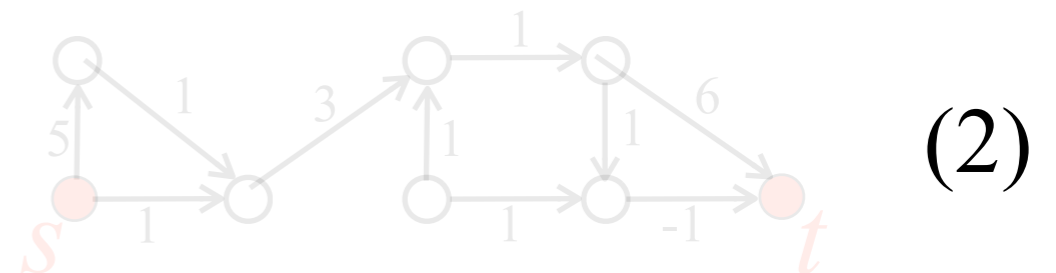
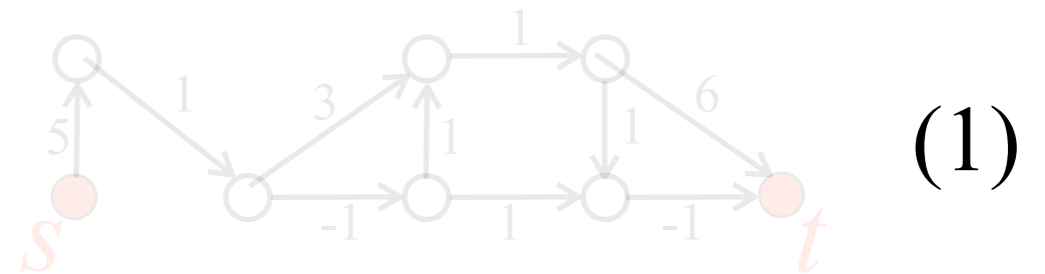
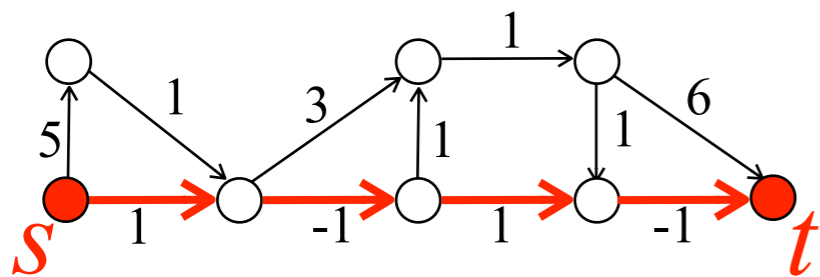
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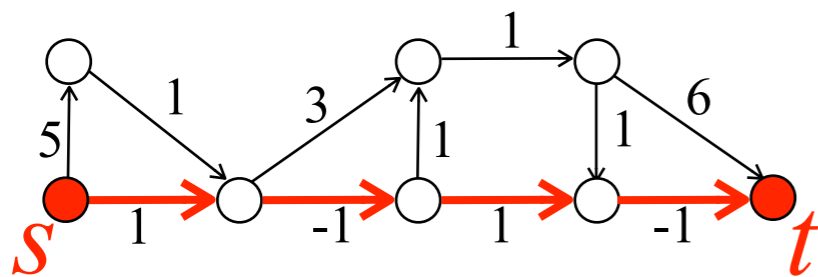
A Replacement Paths Algorithm

- Success probability $1-1/n$
- $r = \tilde{O}(n^{1-\alpha})$ for $0 < \alpha < 1$

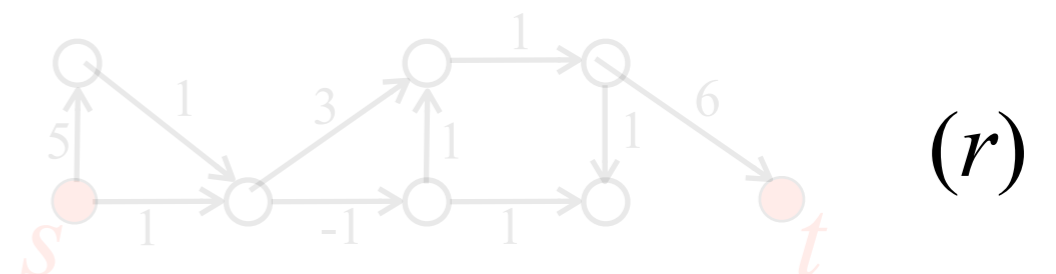
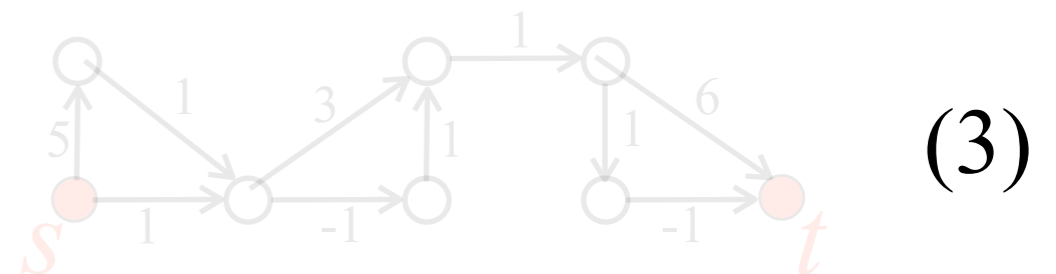
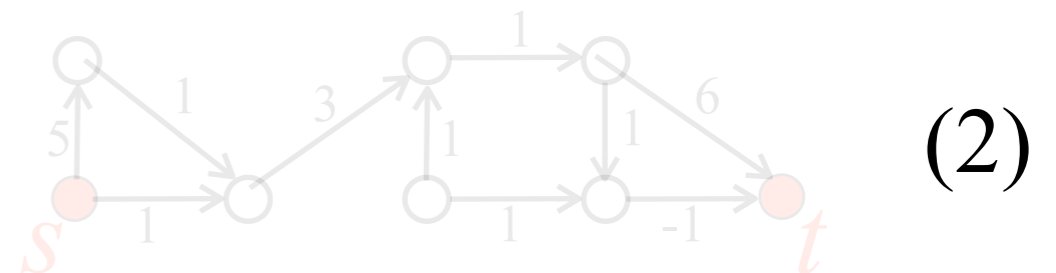
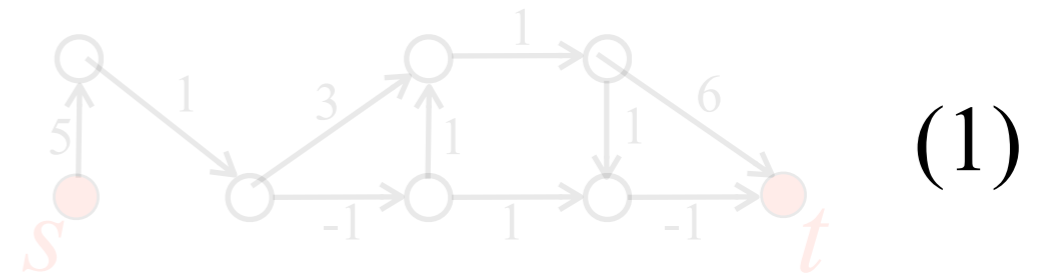


A Replacement Paths Algorithm

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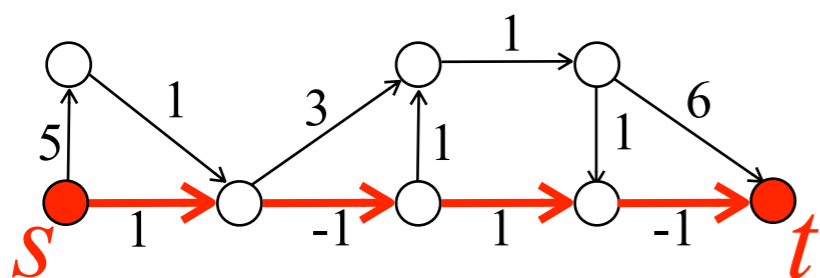


Remove every edge
with probability $n^{\alpha-1}$

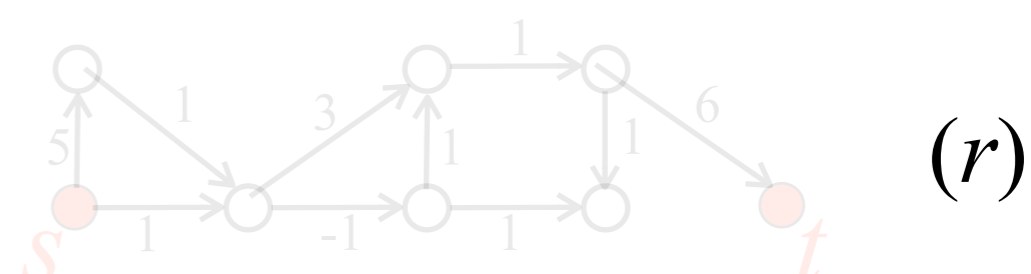
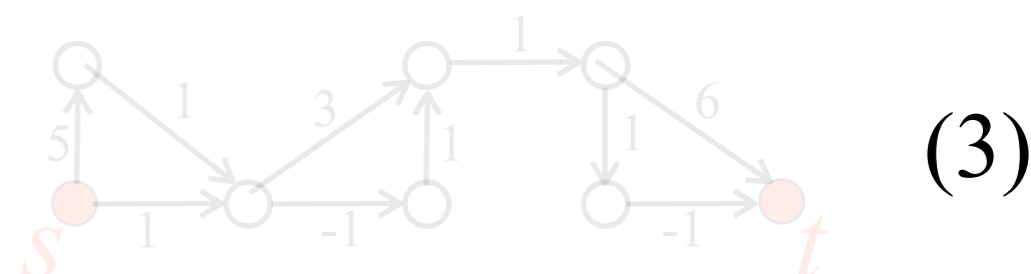
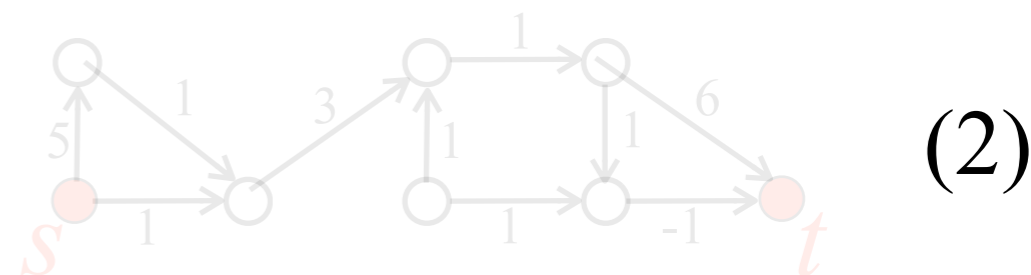
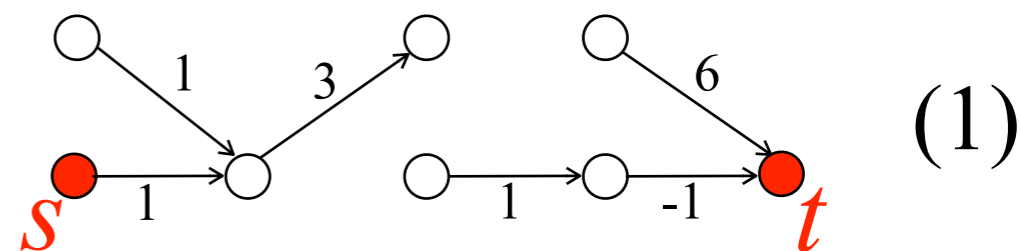


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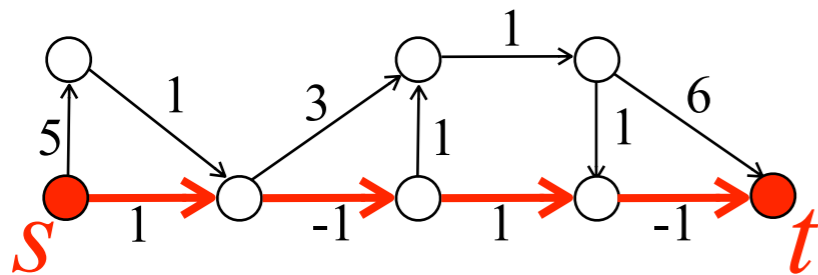


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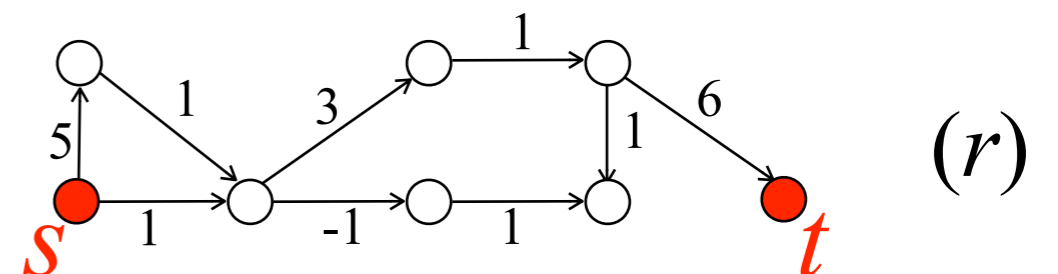
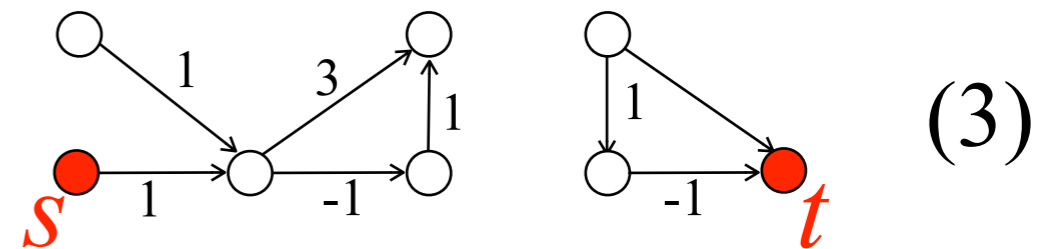
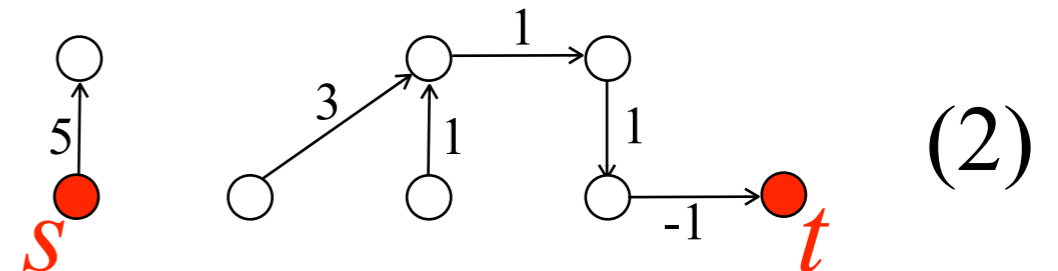
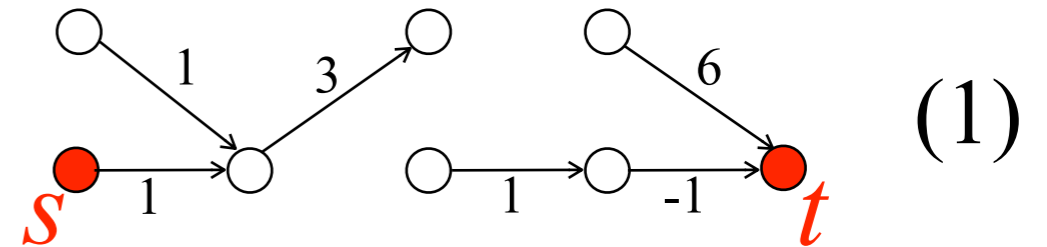


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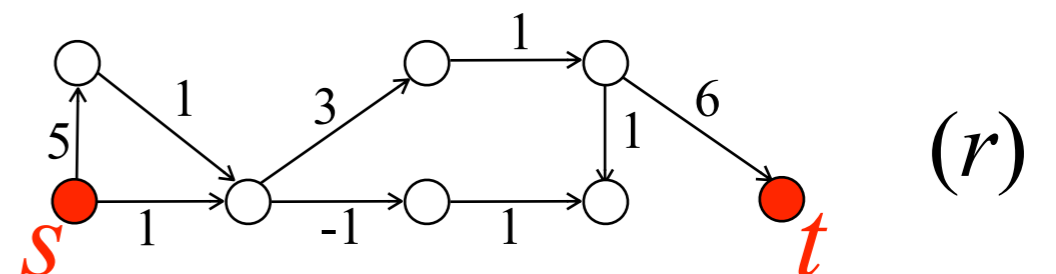
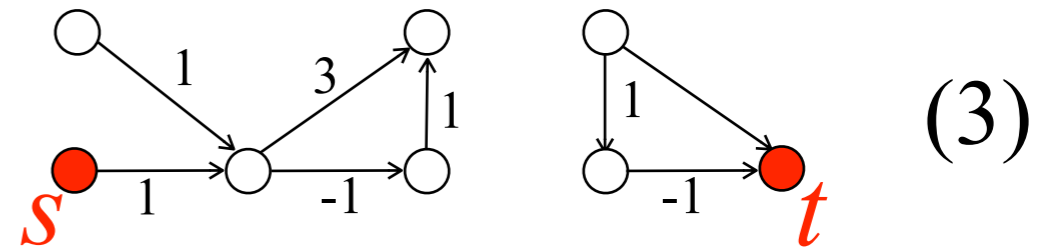
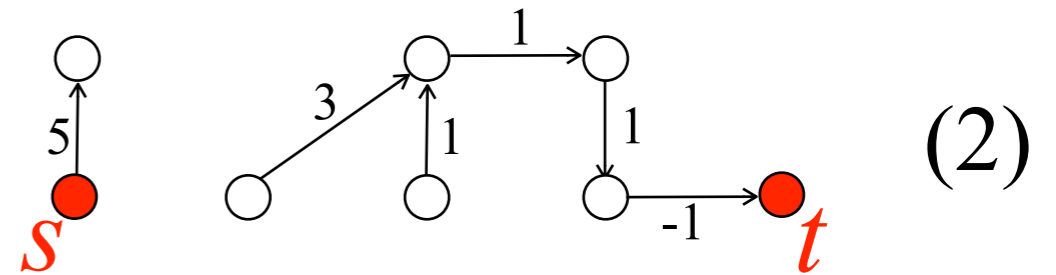
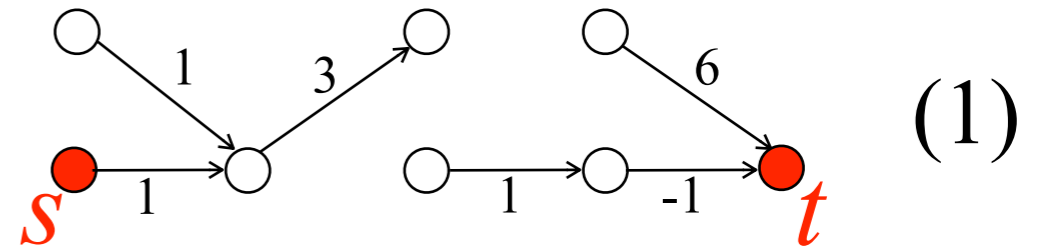
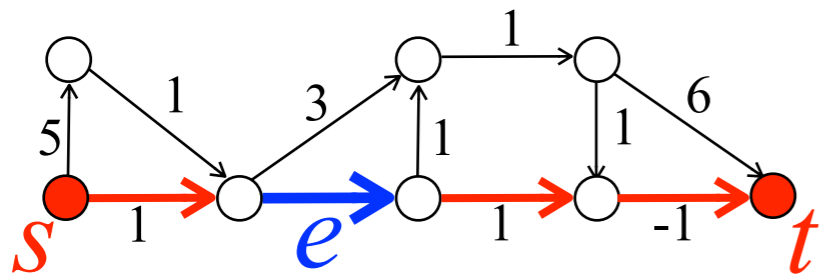


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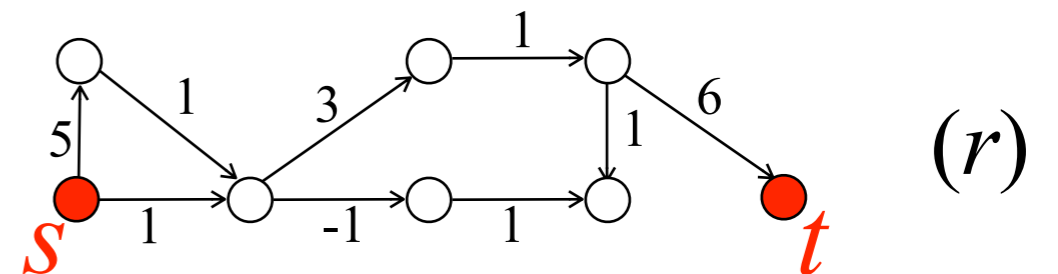
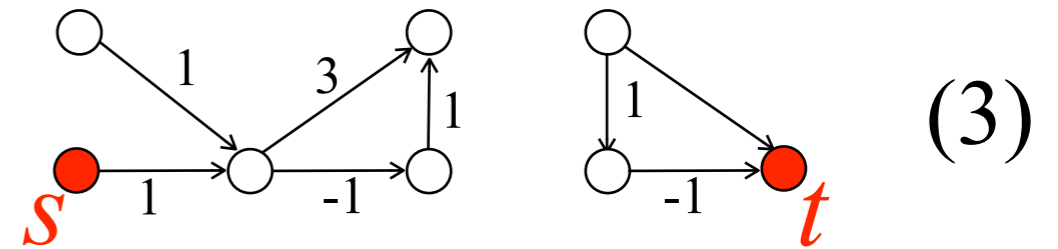
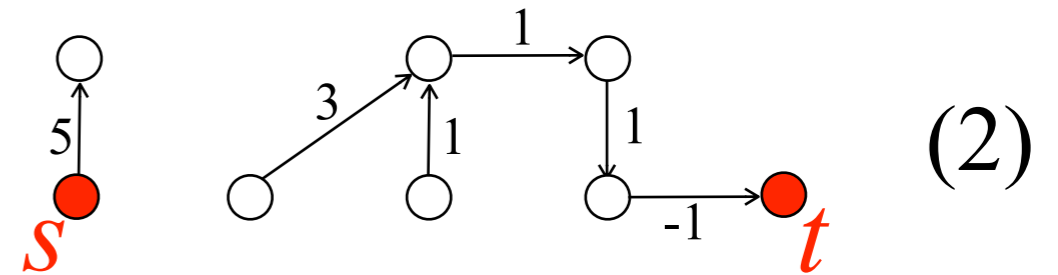
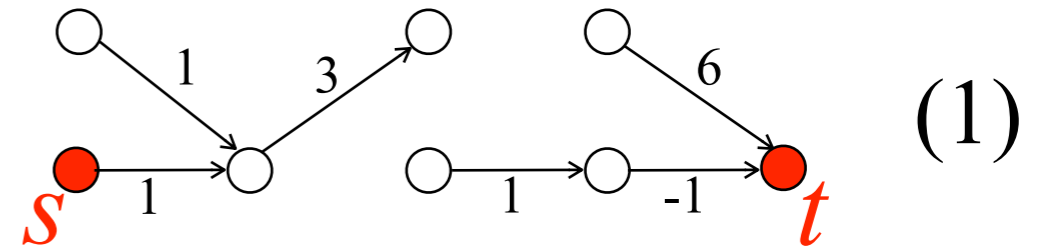
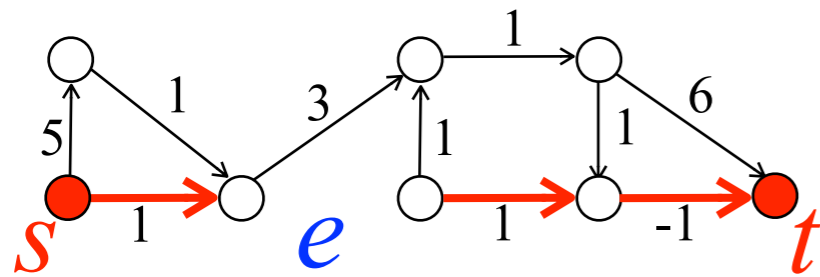
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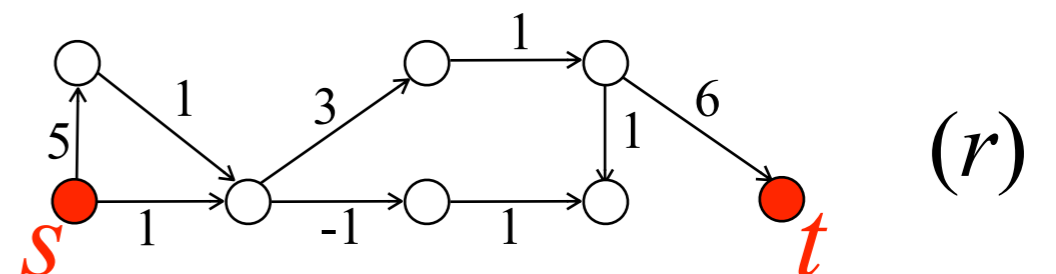
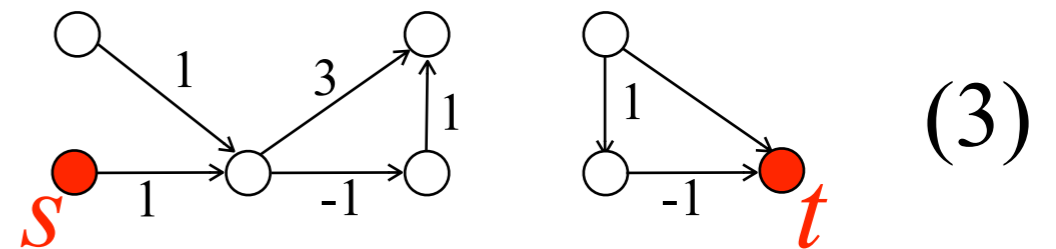
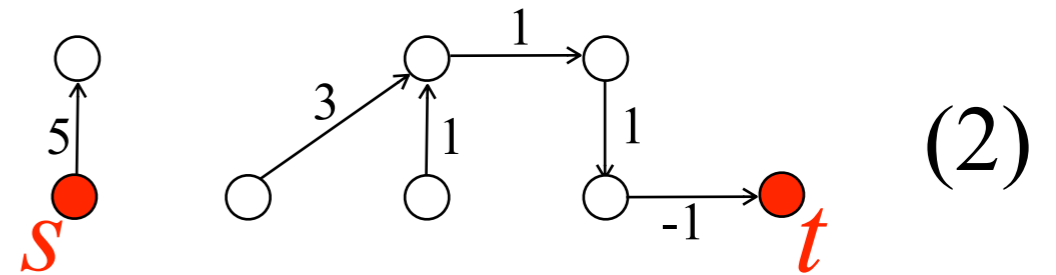
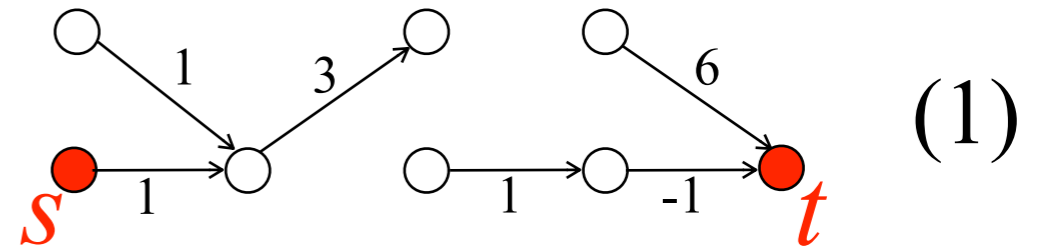
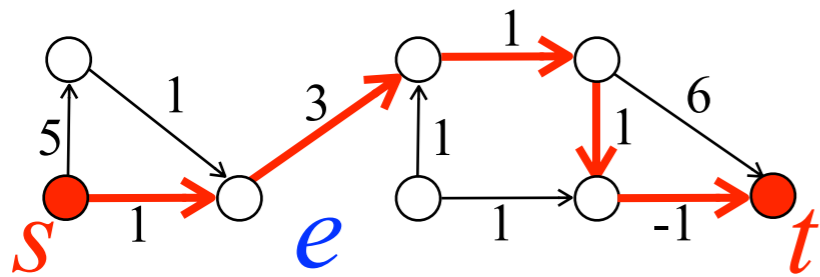
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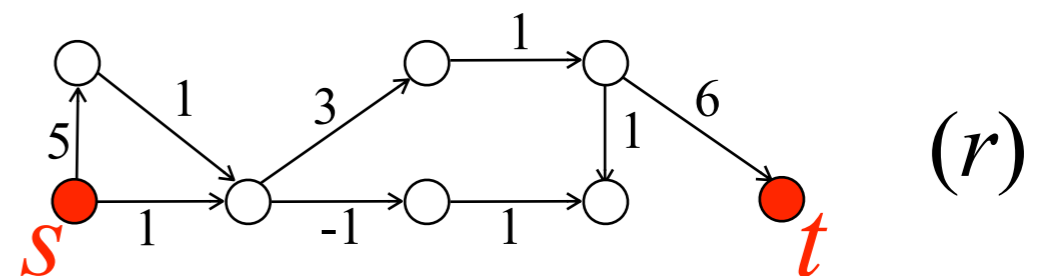
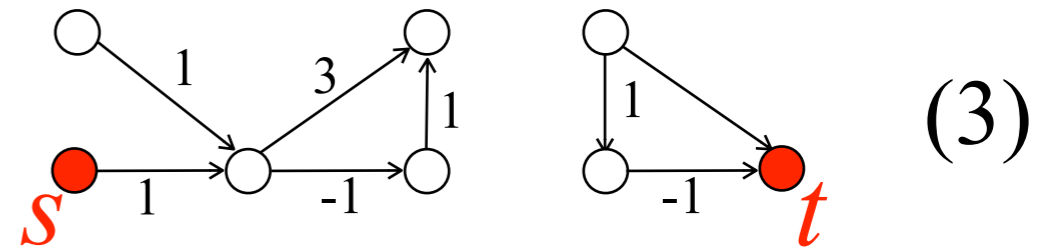
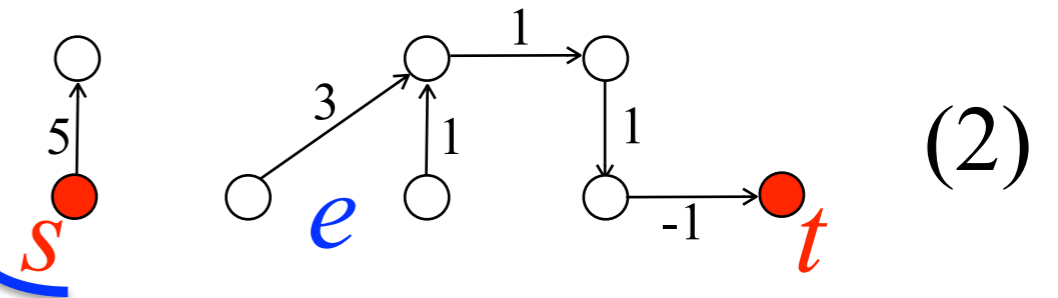
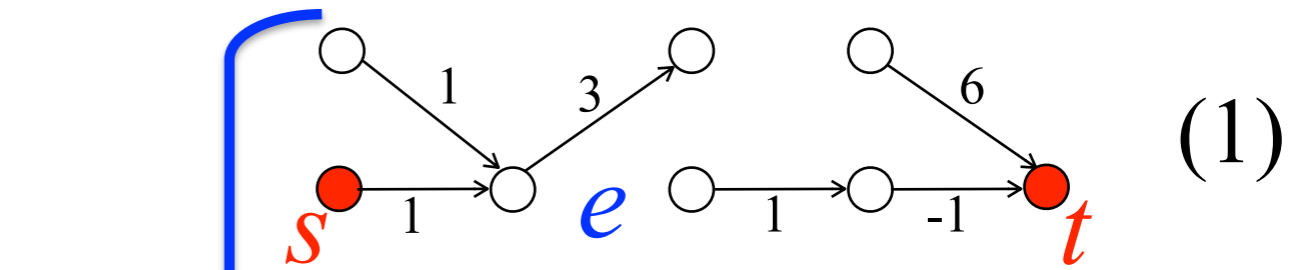
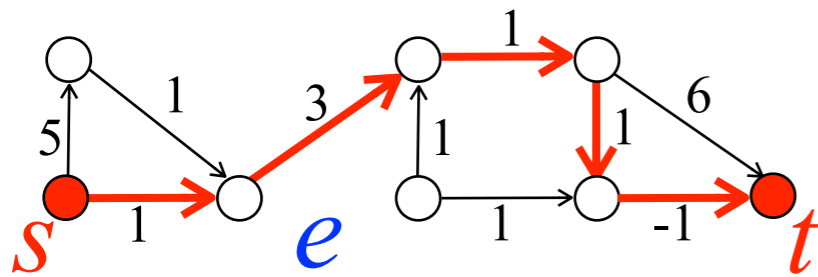
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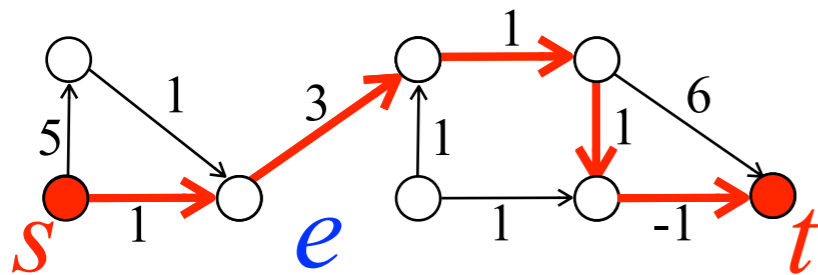
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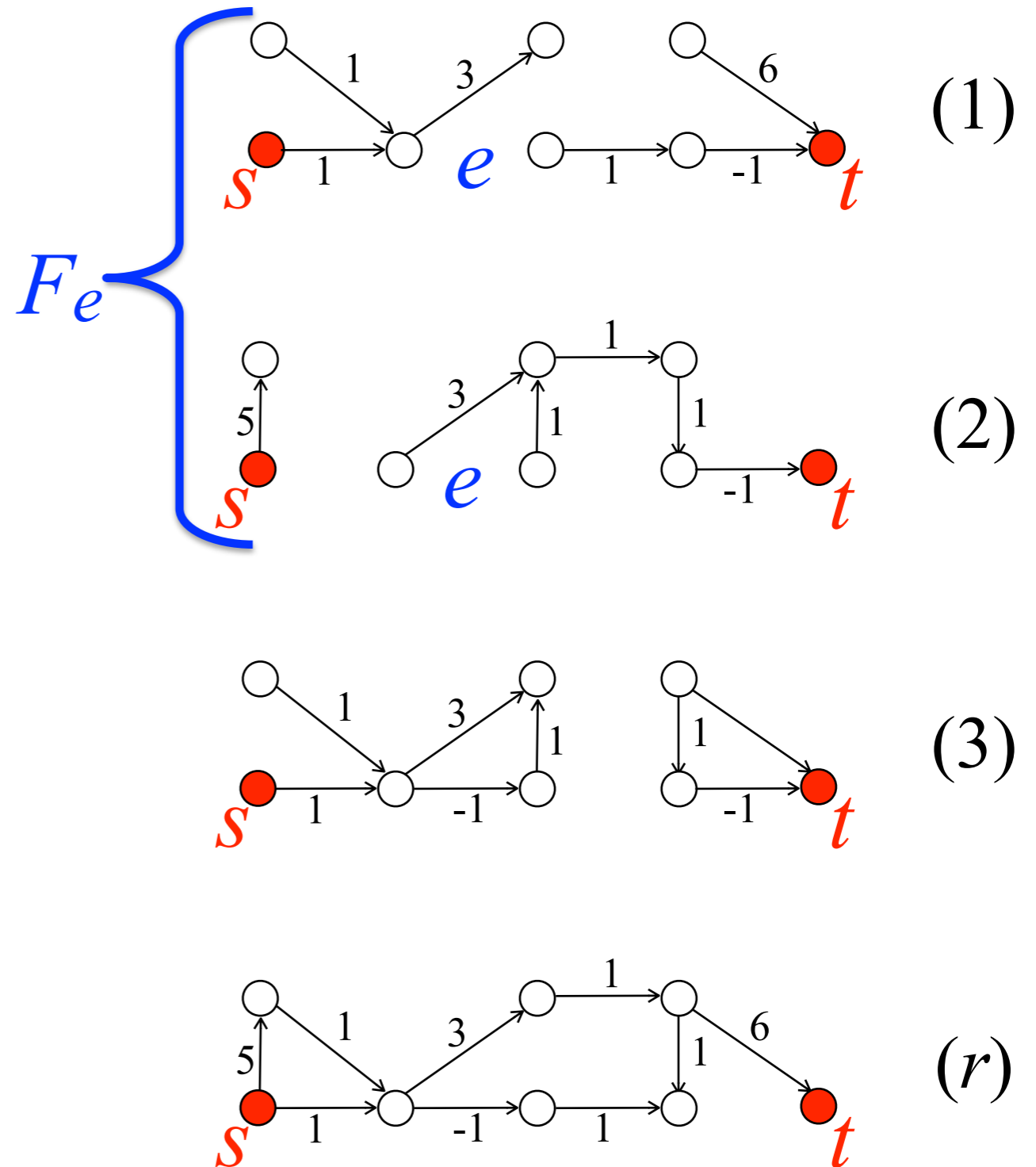


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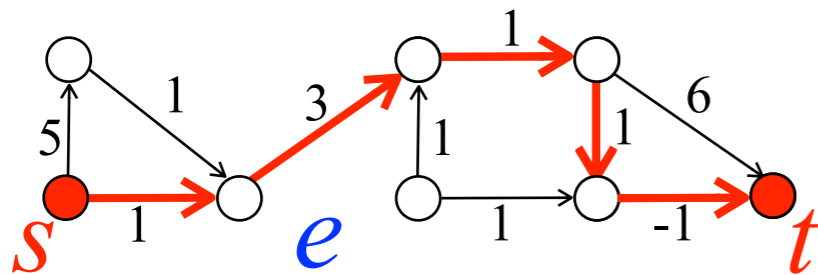


- With high probability
 - short subpaths survive

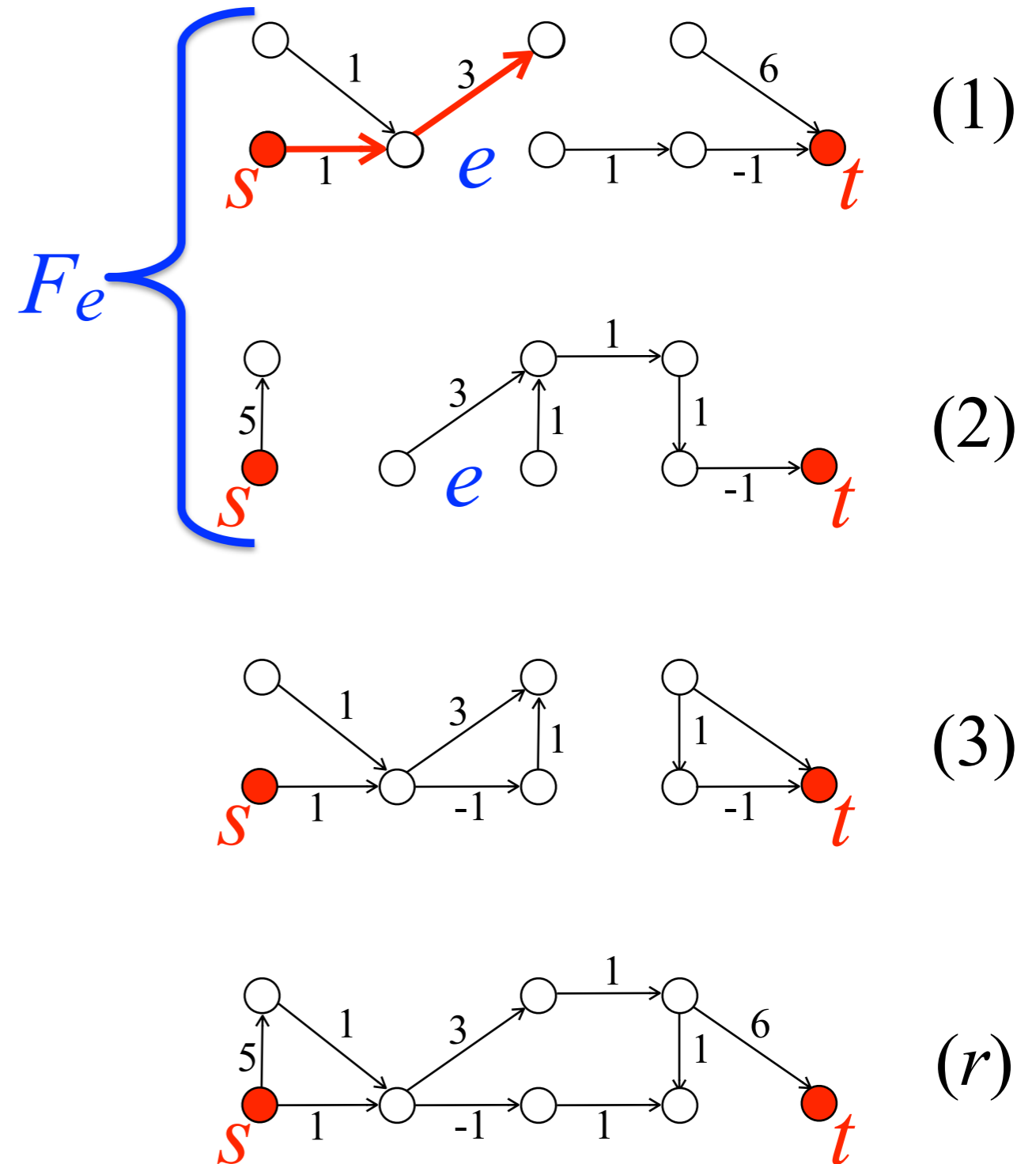


A Replacement Paths Algorithm

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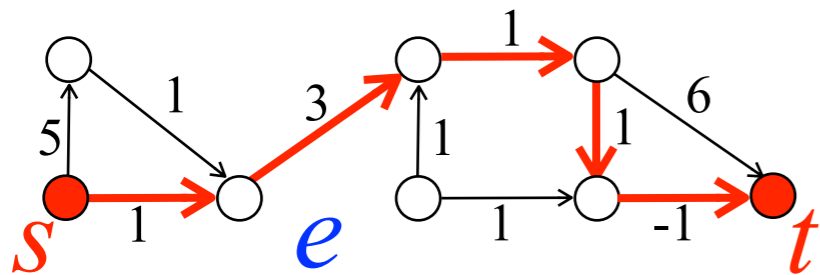


- With high probability
 - short subpaths survive

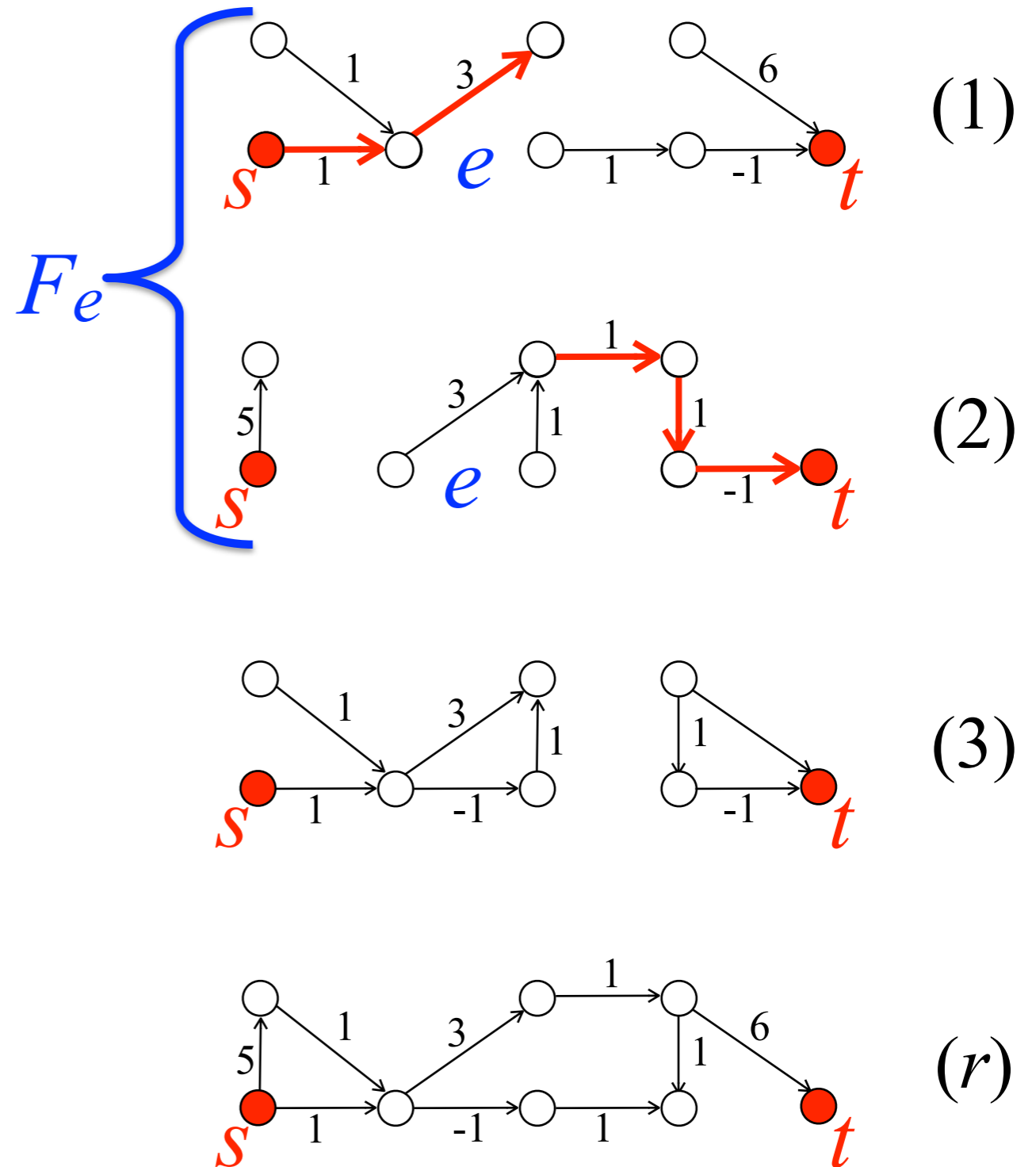


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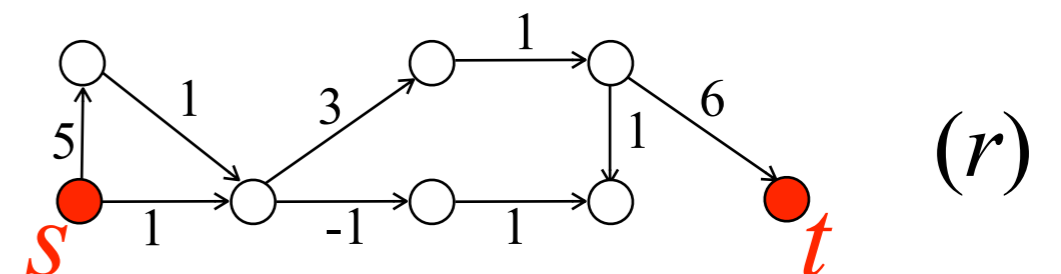
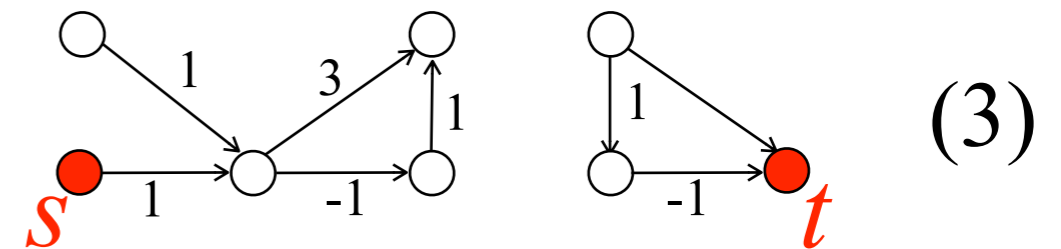
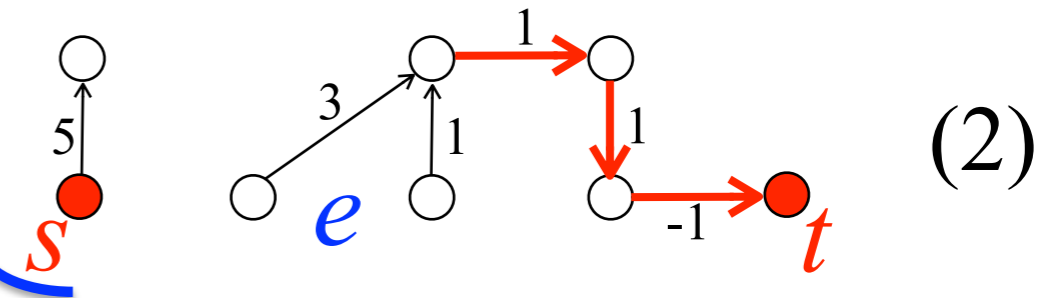
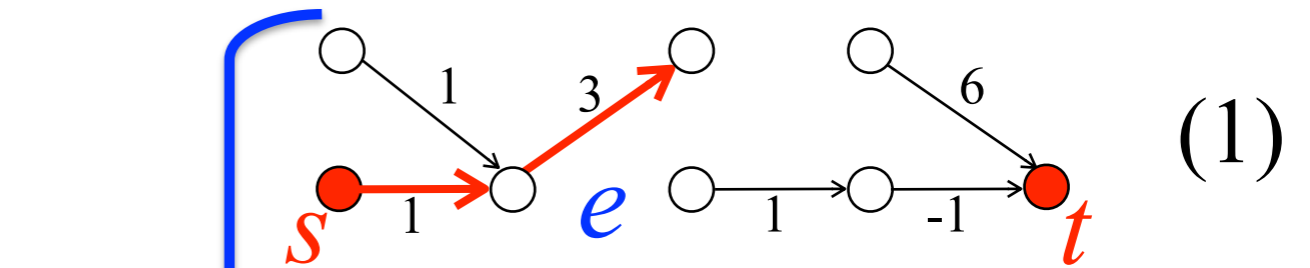
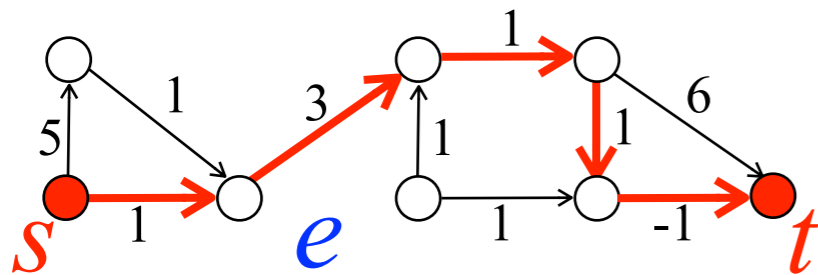


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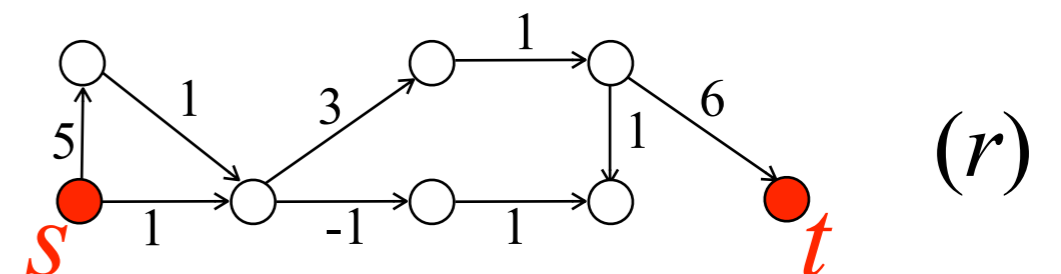
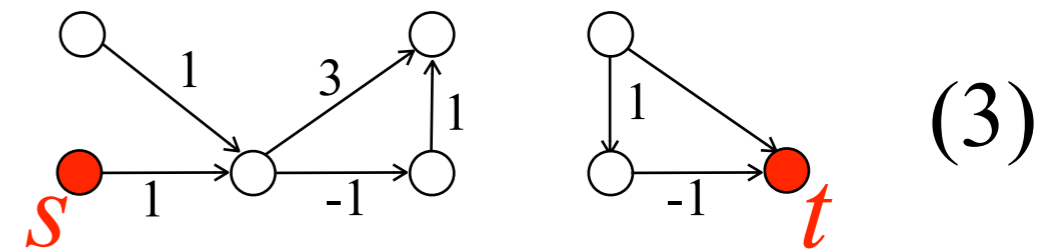
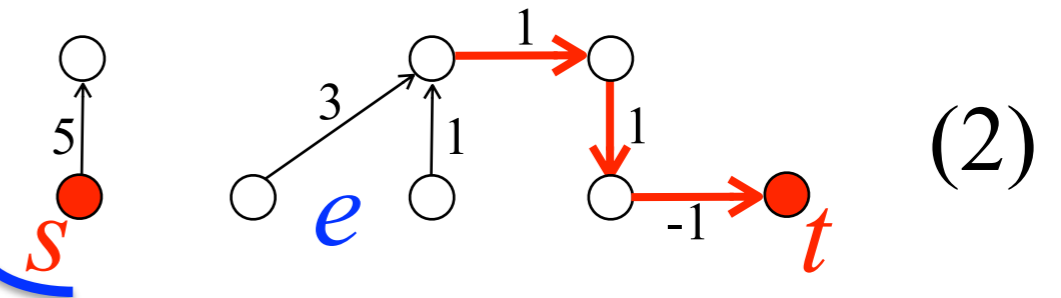
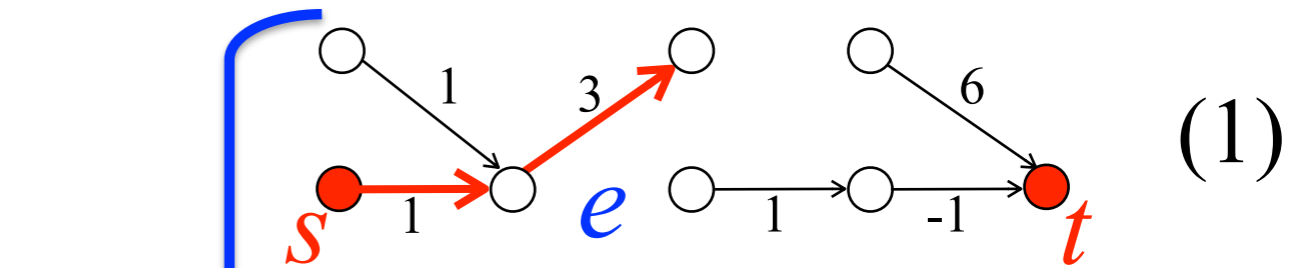
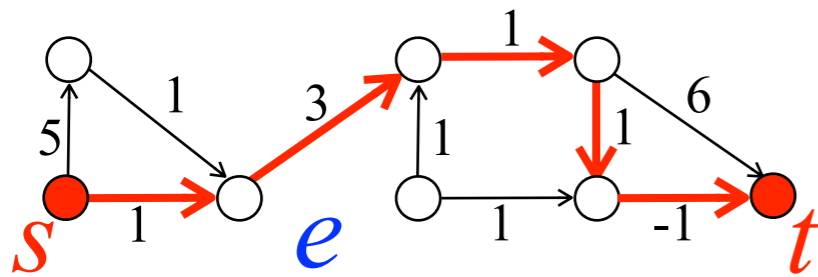
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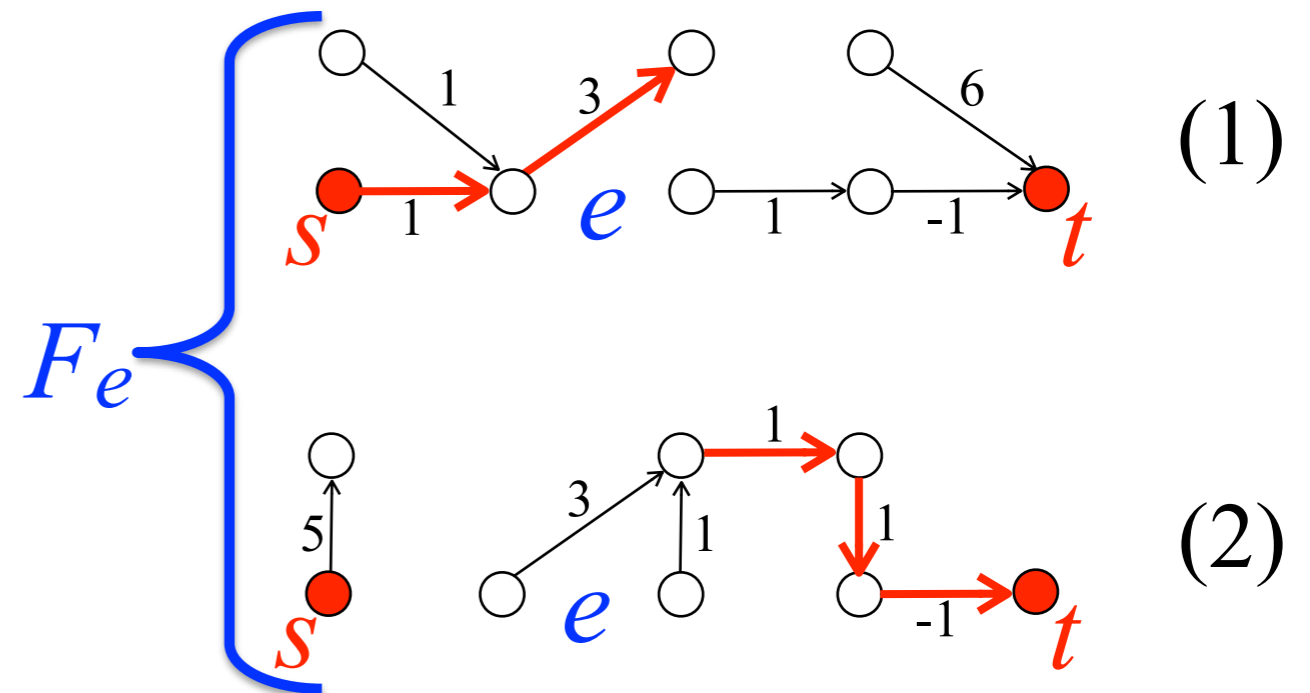
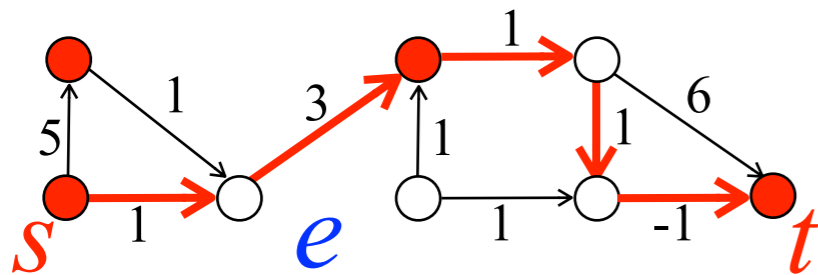
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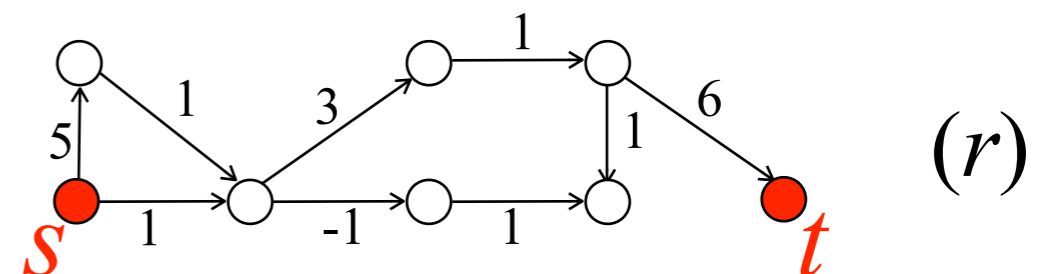
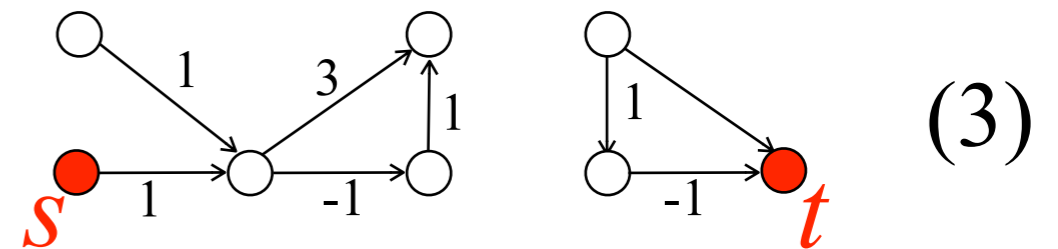
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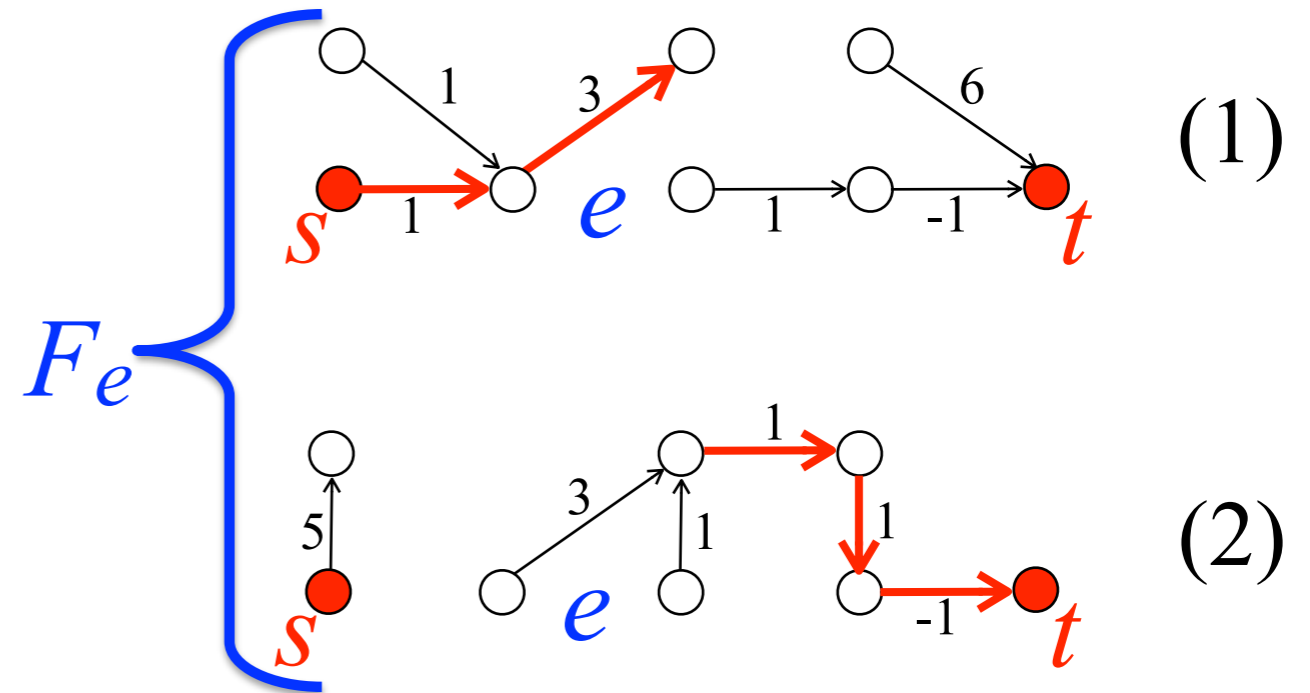
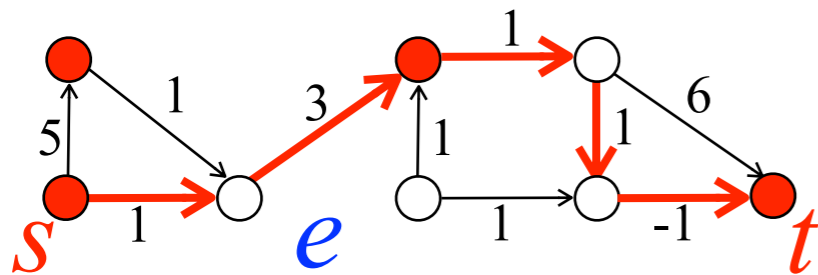


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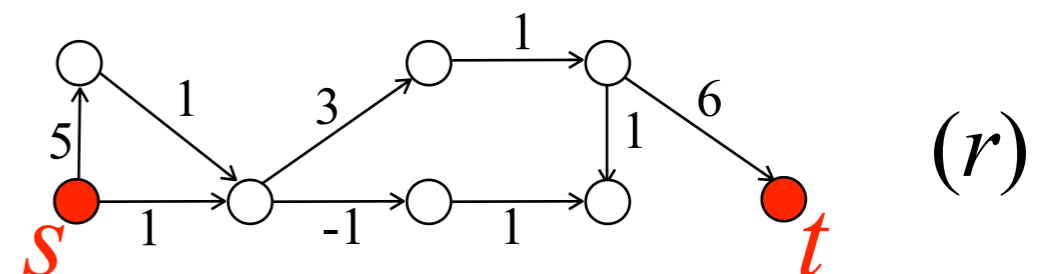
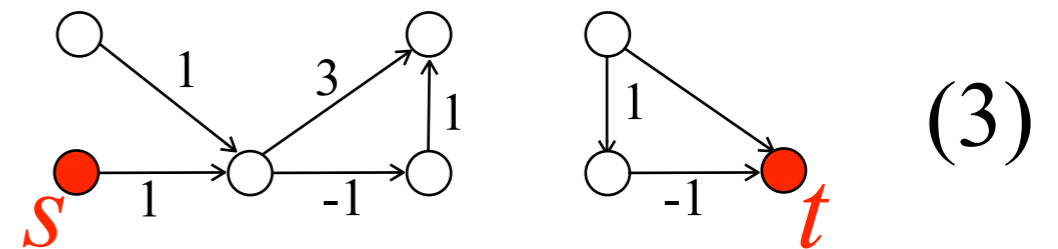


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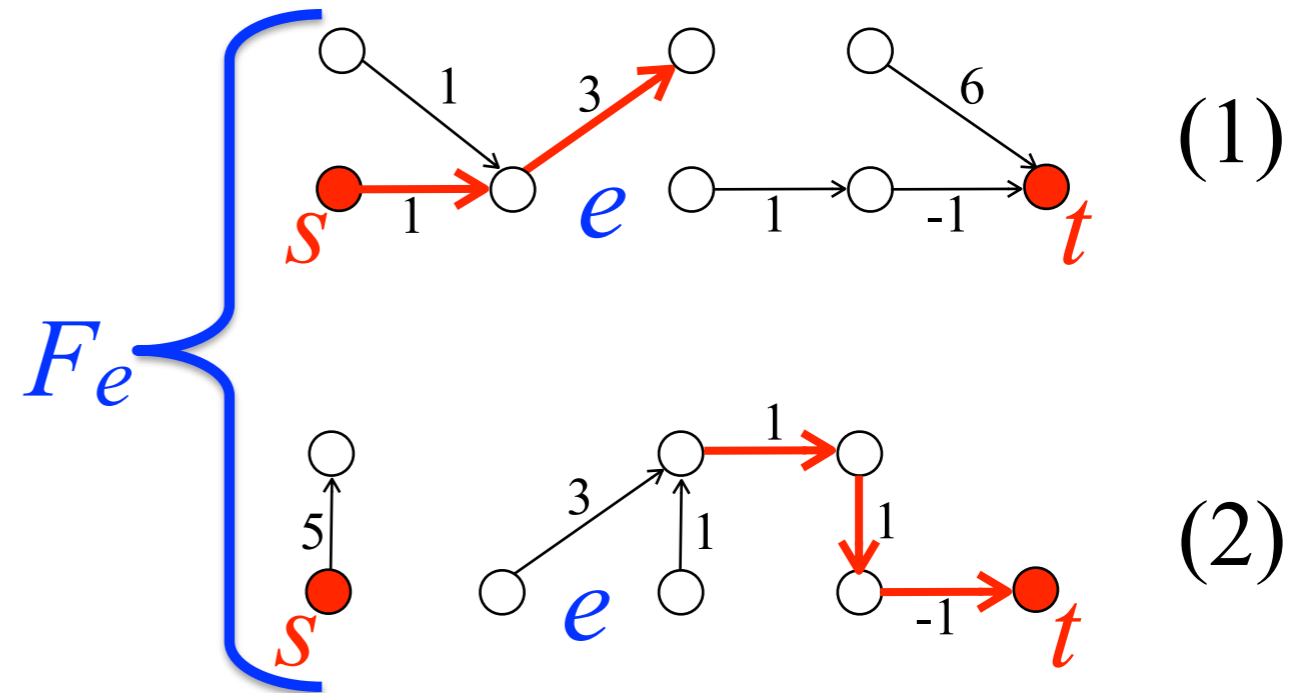
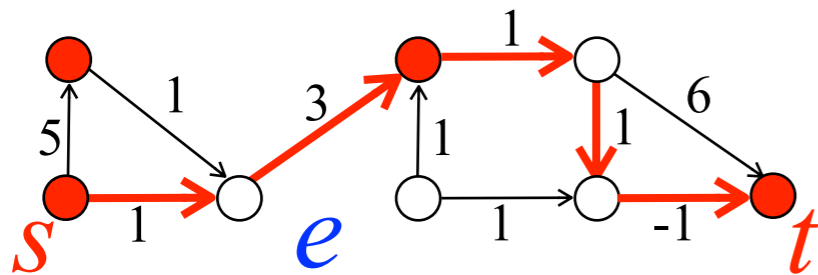


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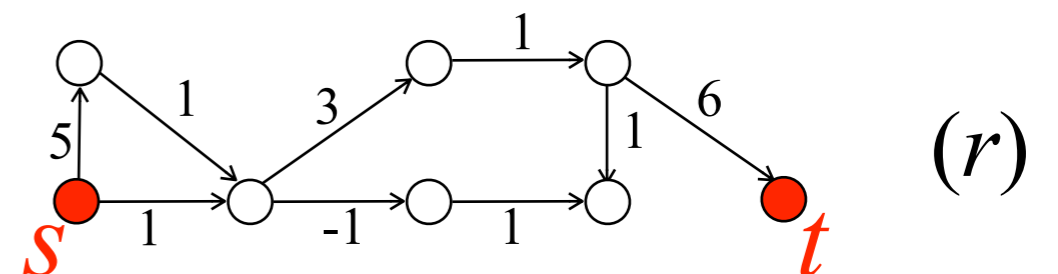
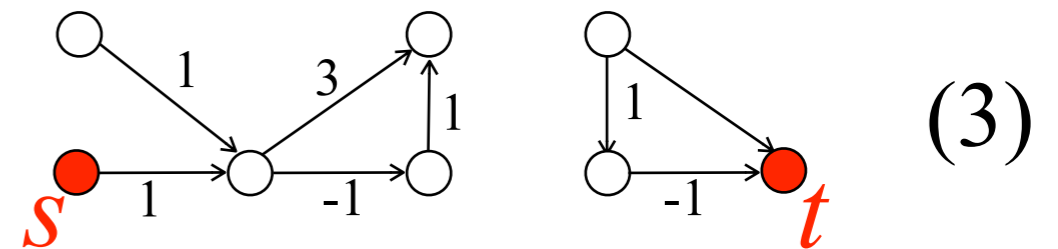


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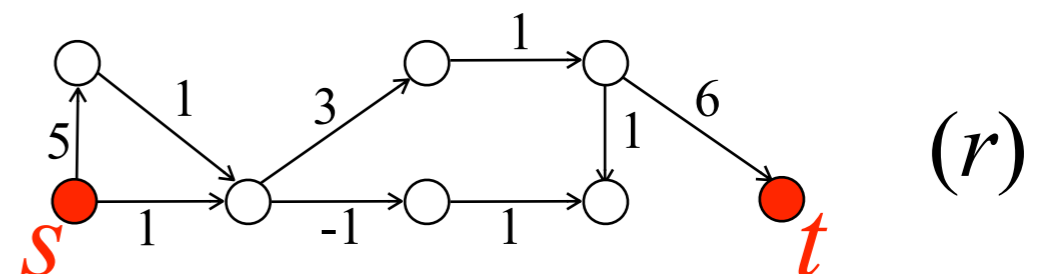
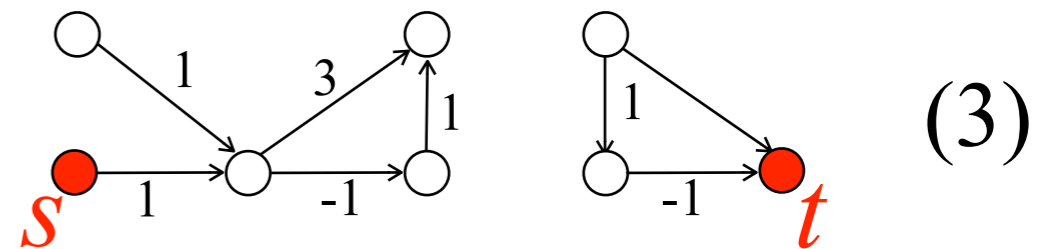
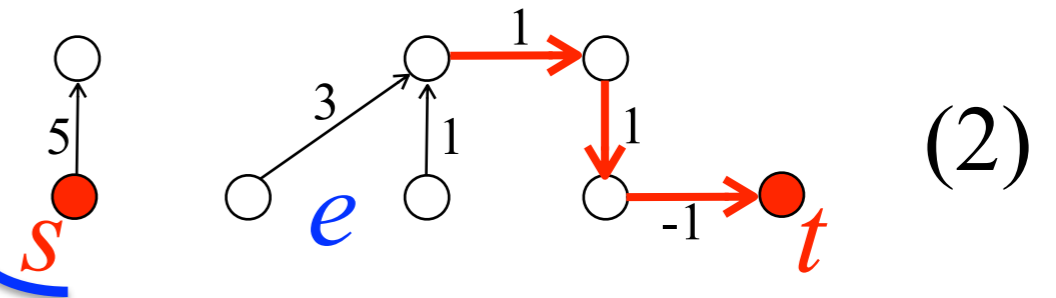
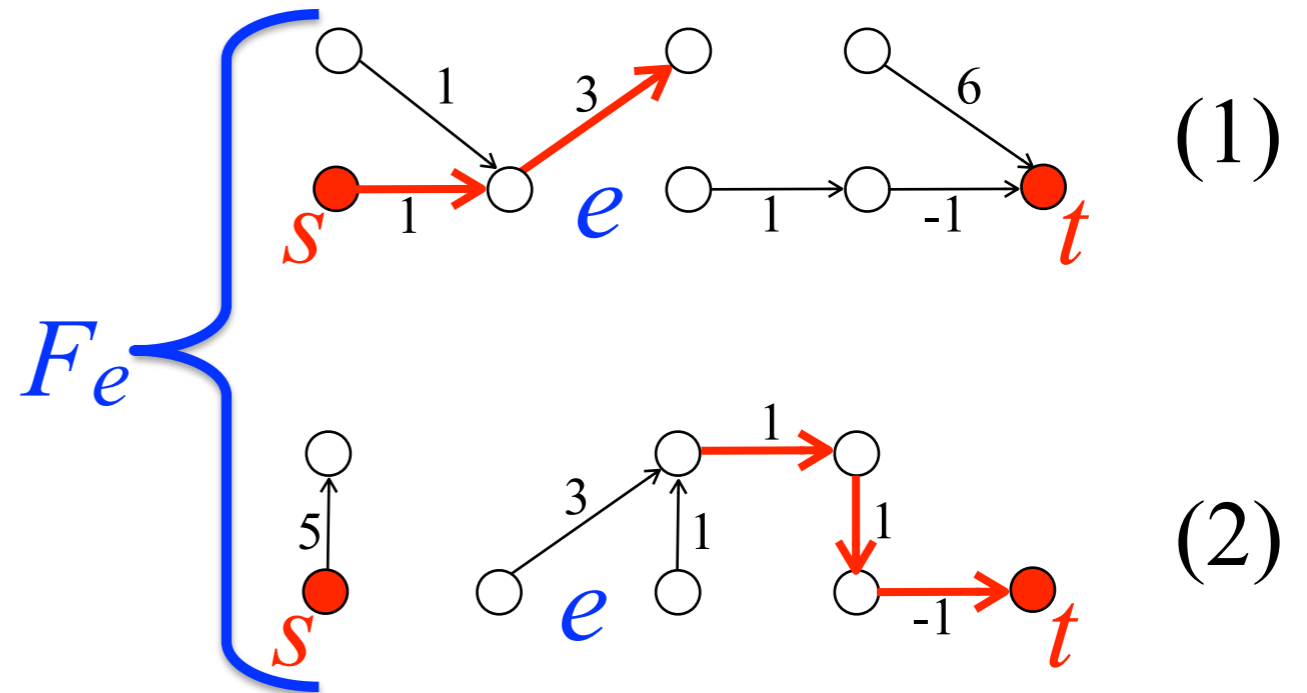
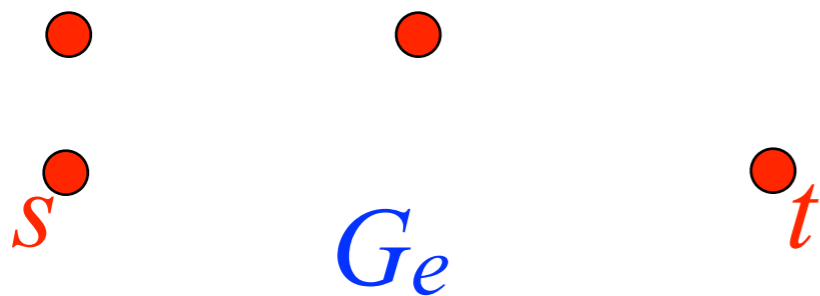


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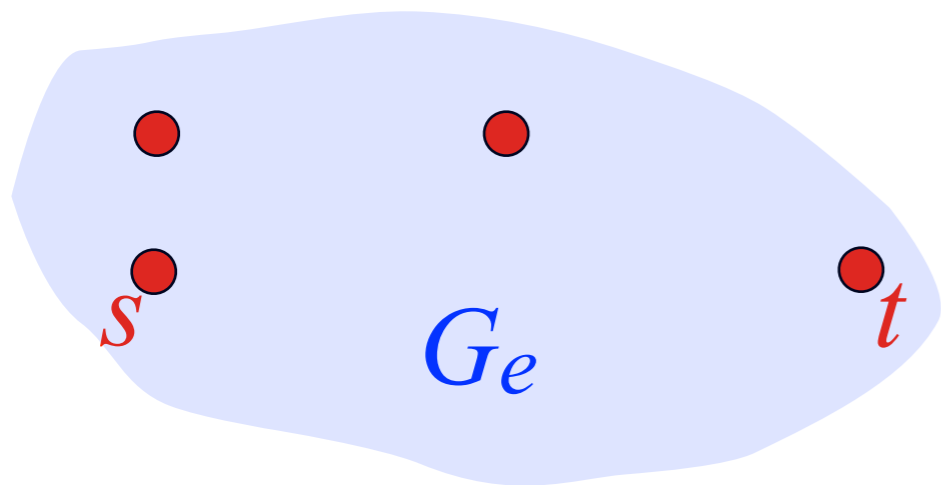
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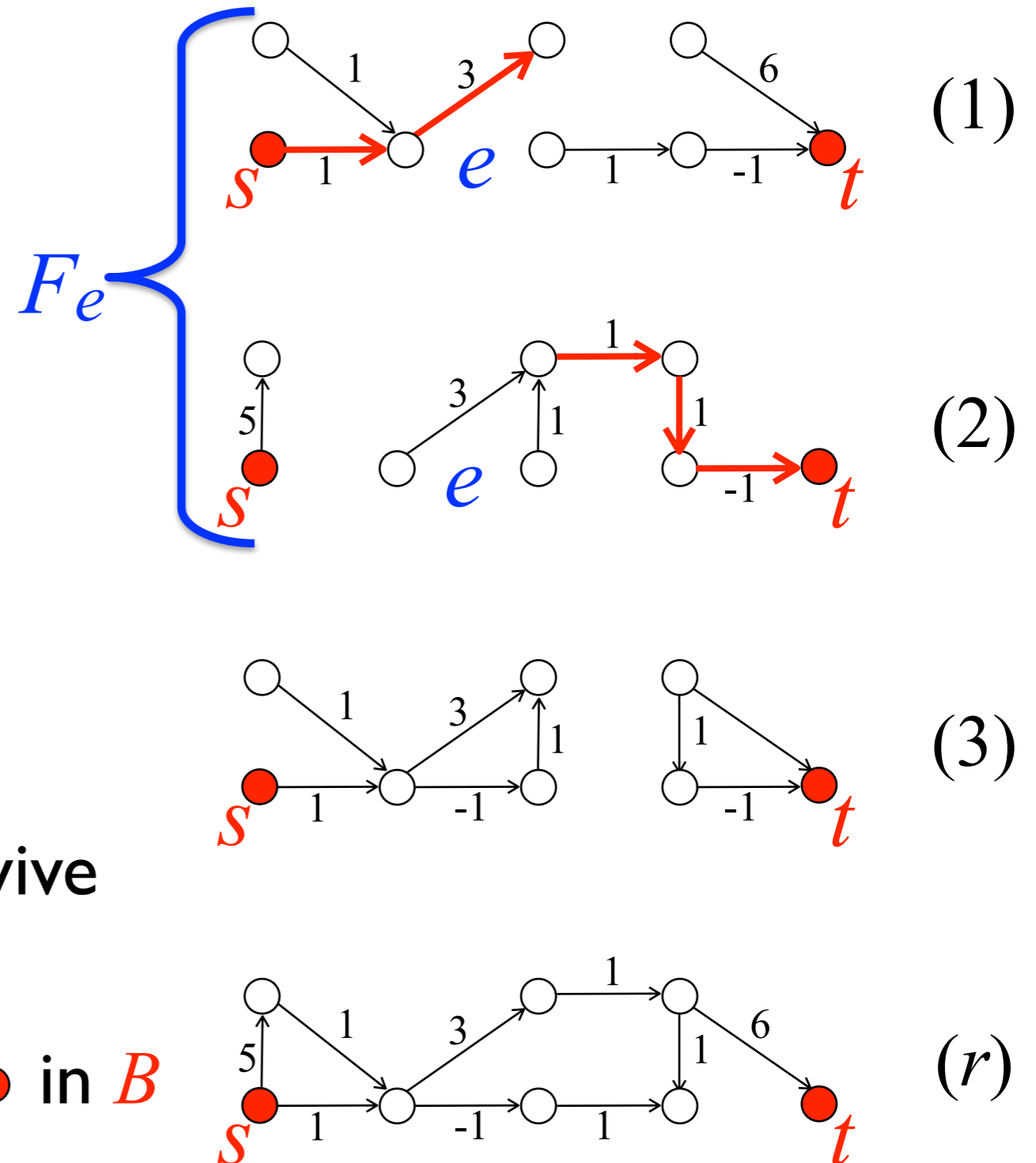
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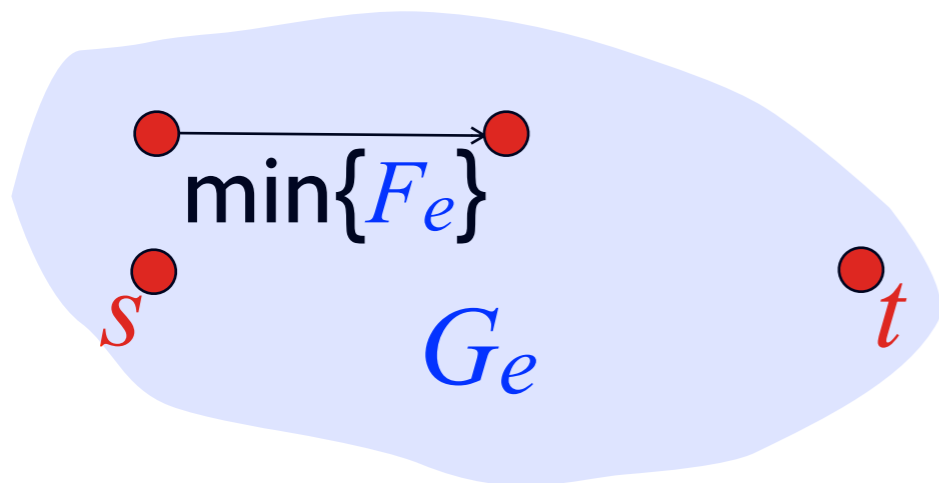


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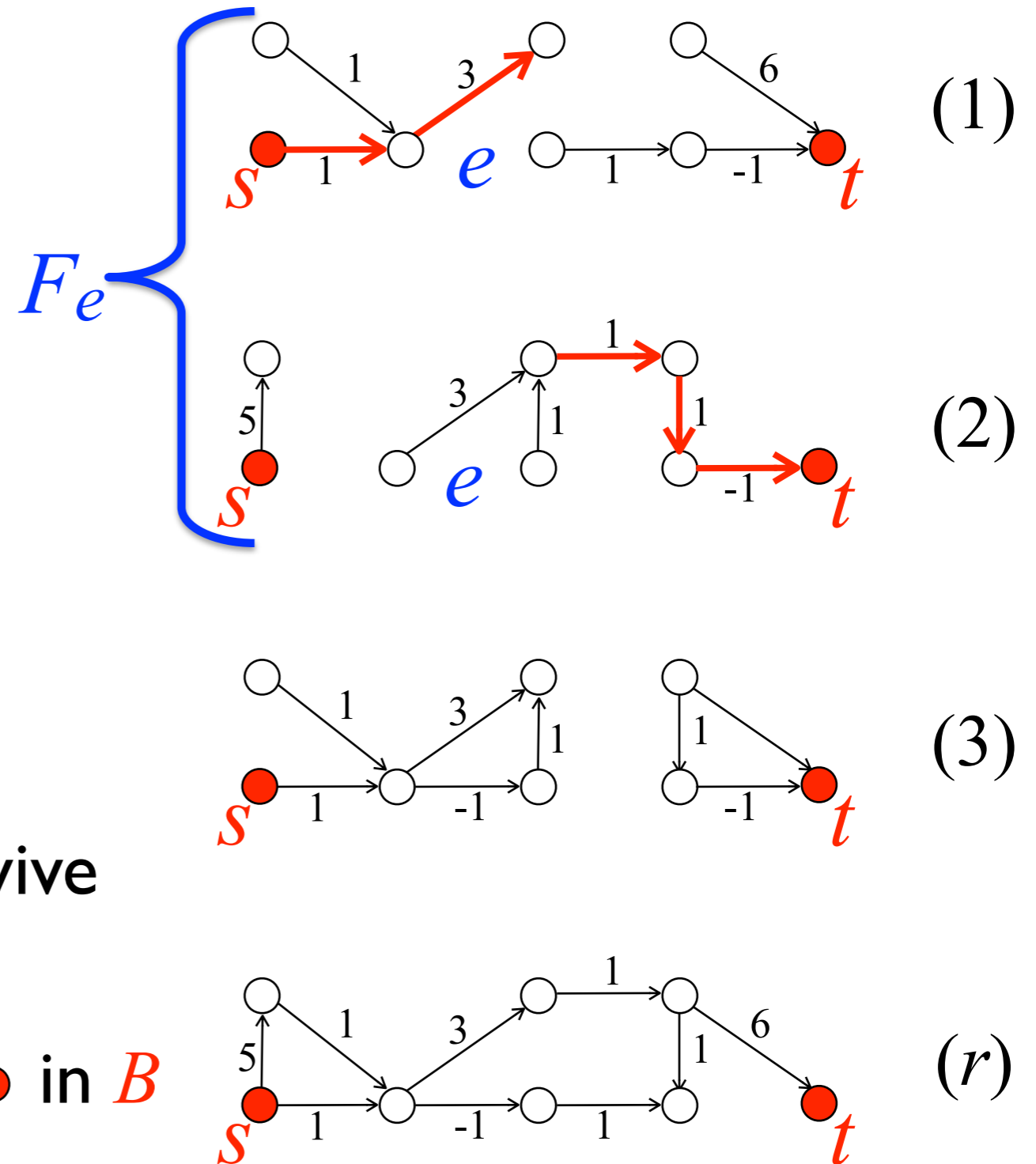


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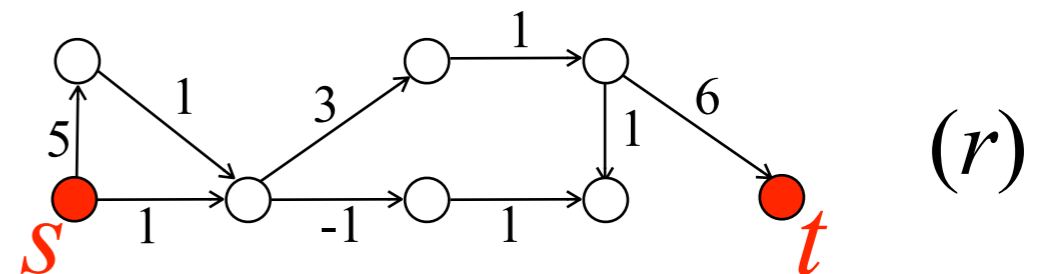
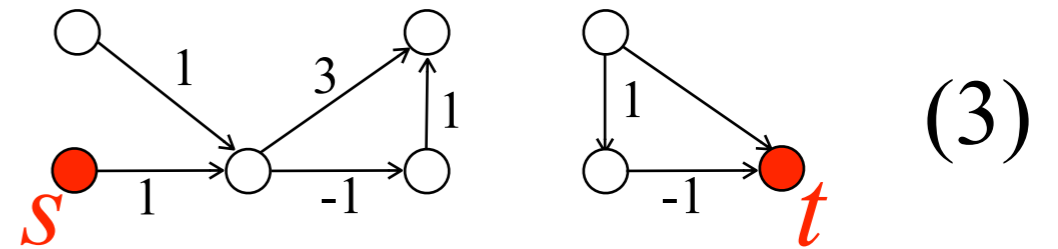
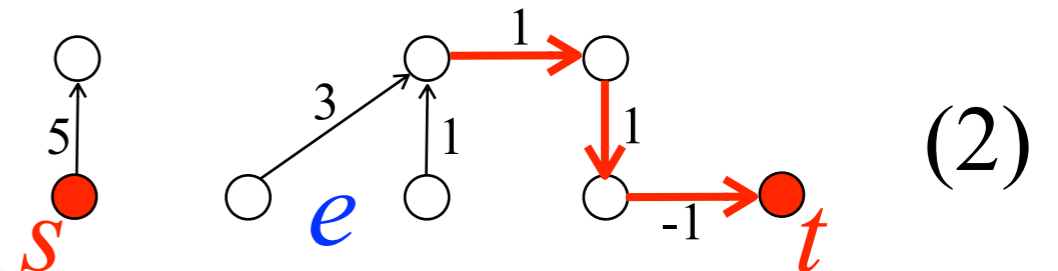
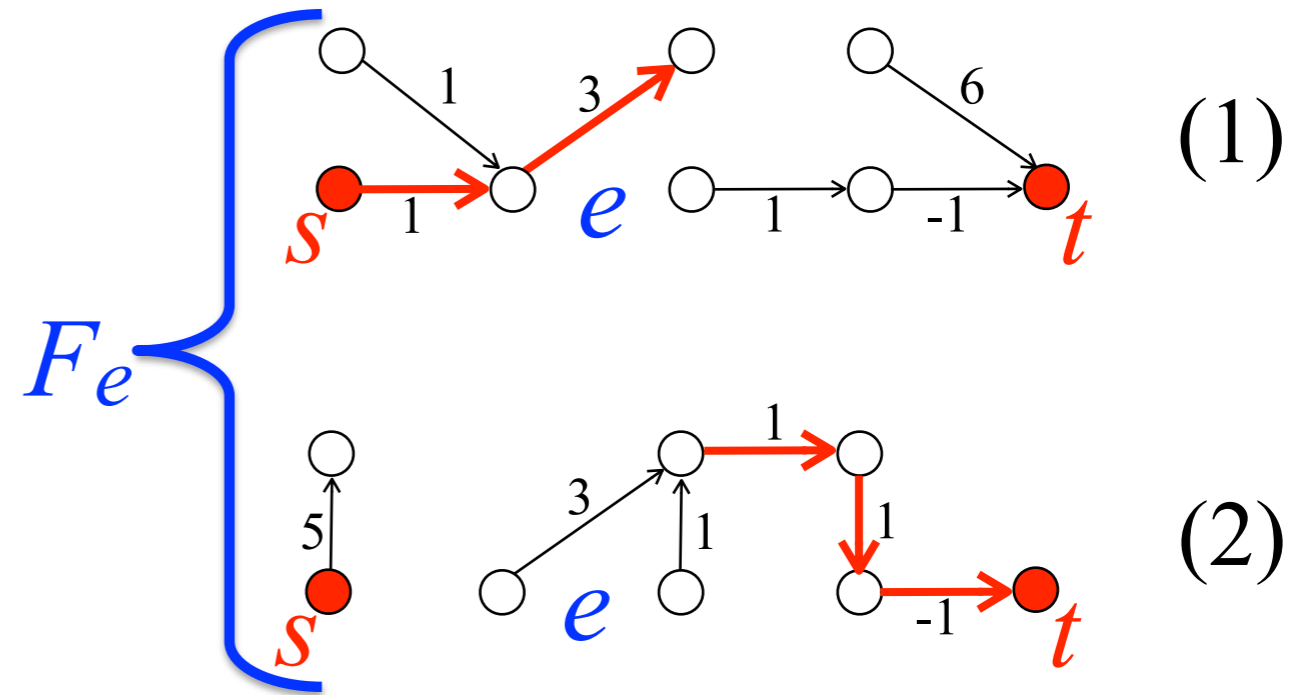
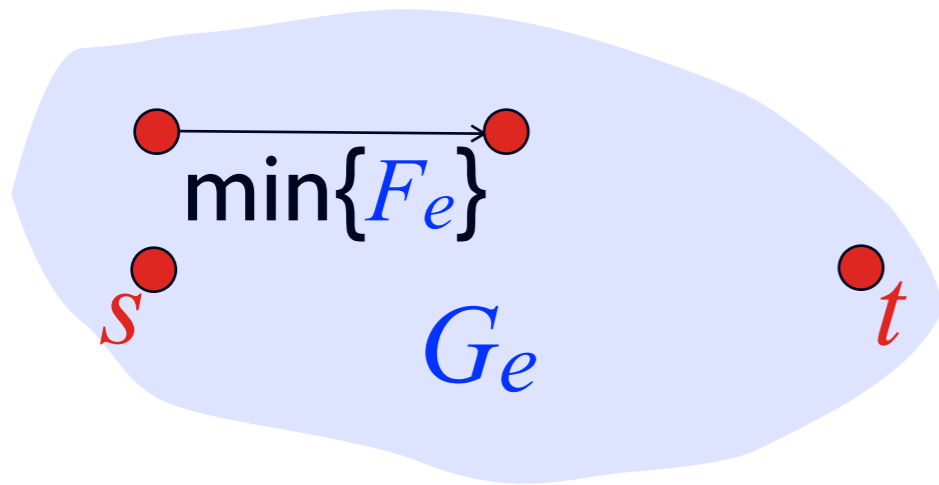


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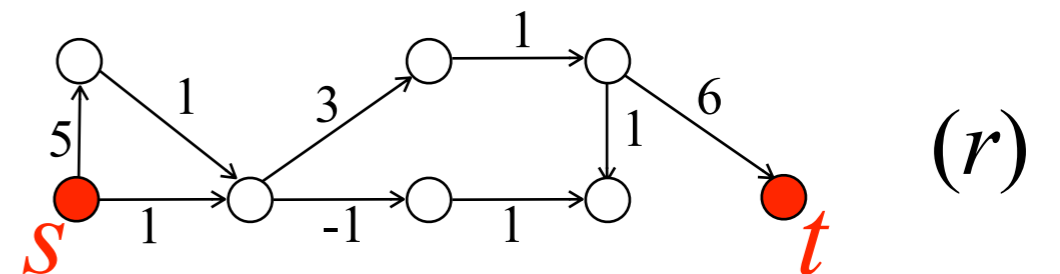
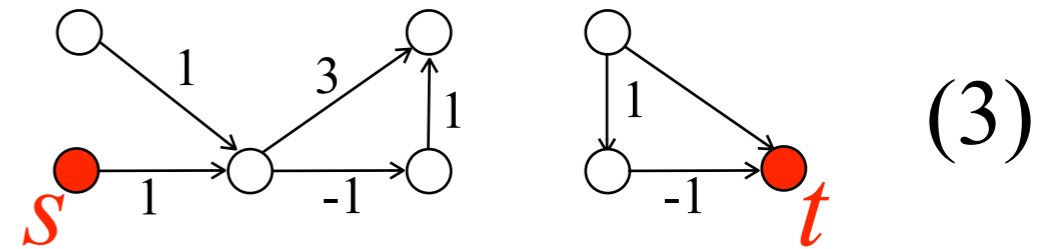
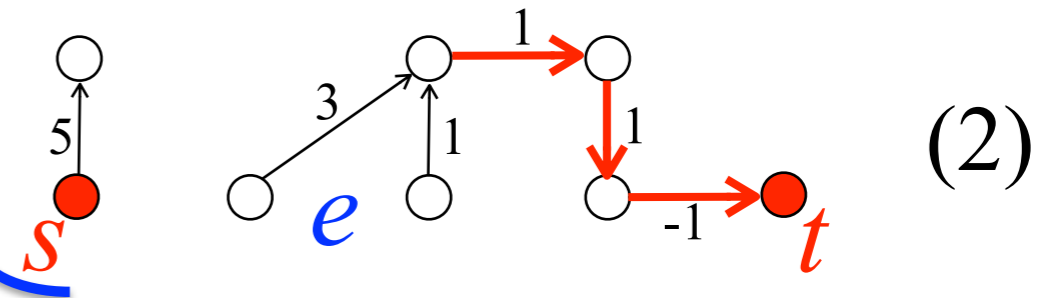
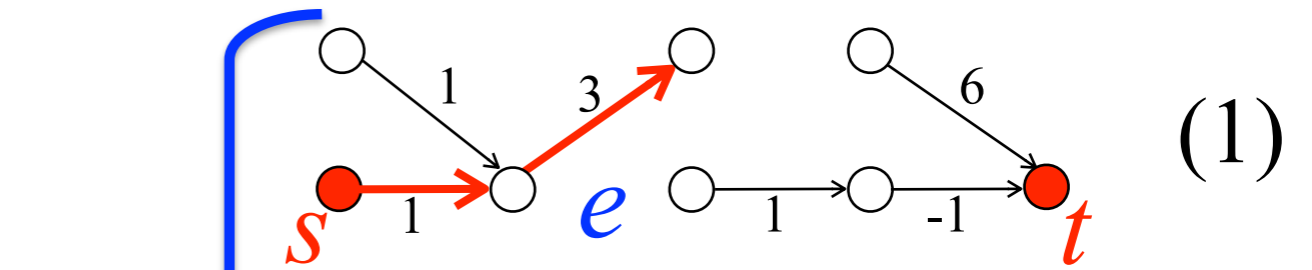
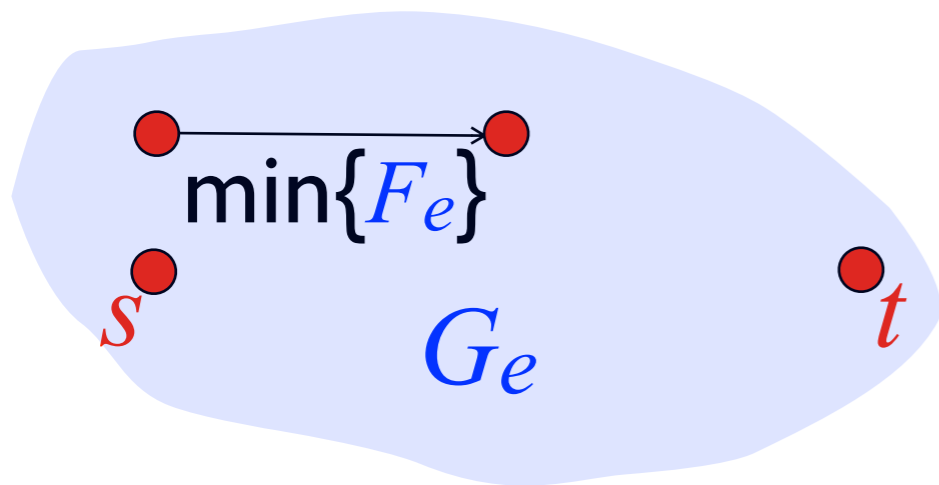


Challenges:

- Construct G_e
- Compute st-paths in all G_e

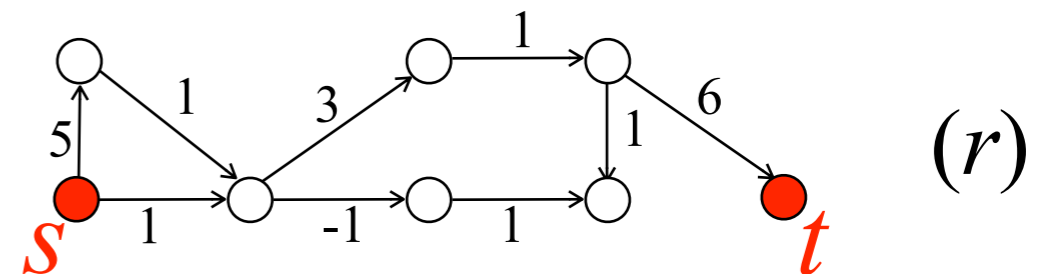
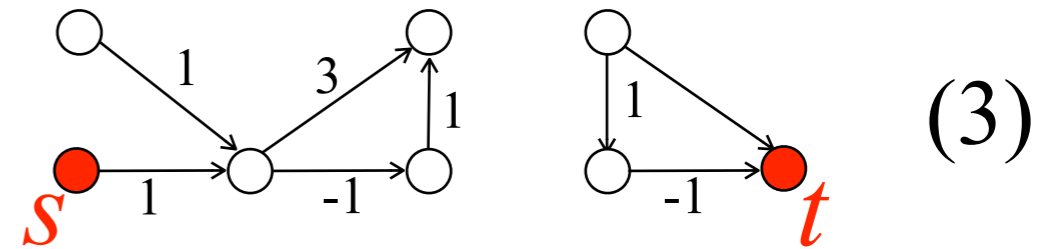
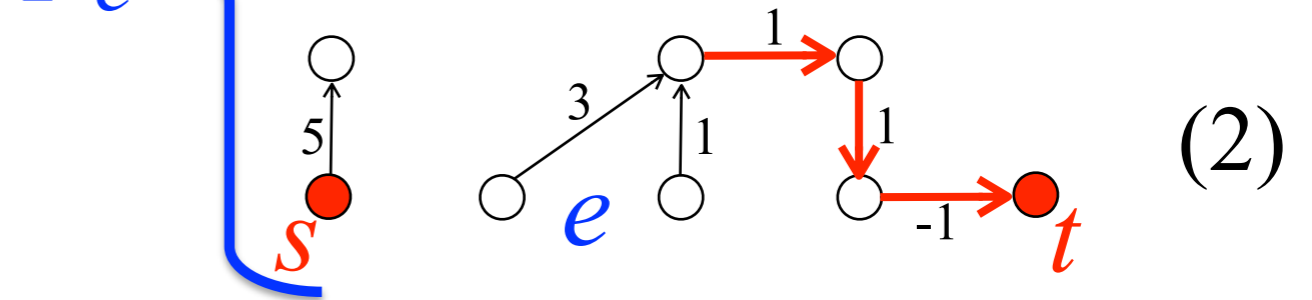
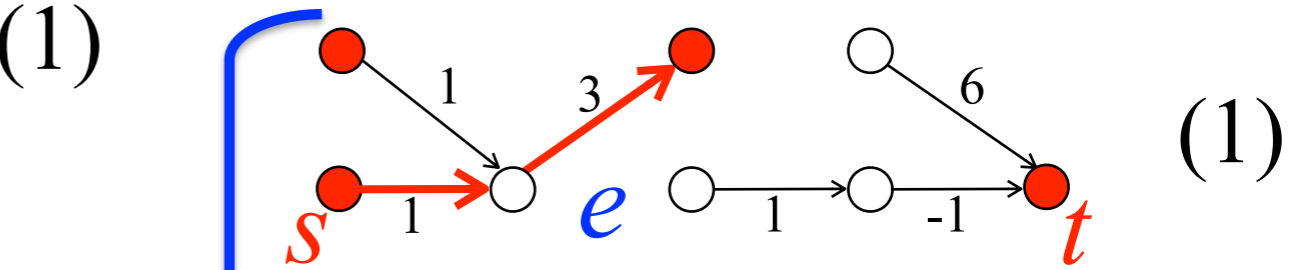
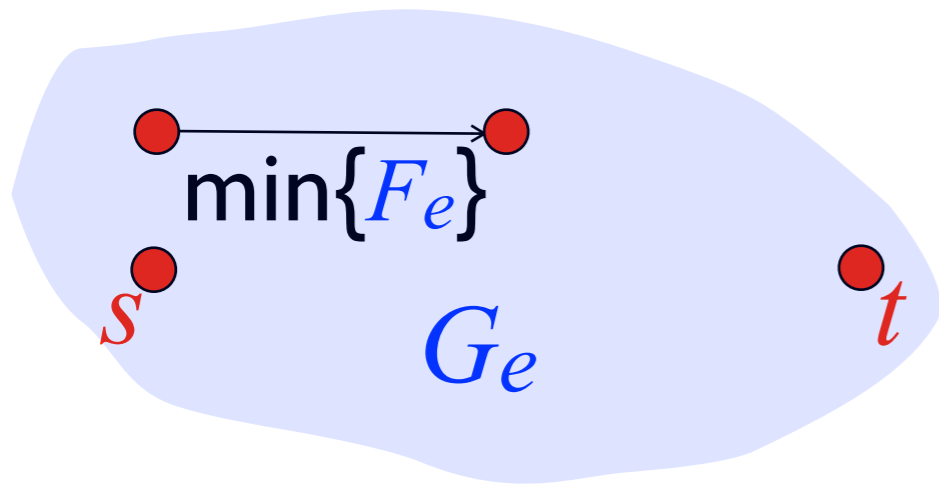


Constructing G_e



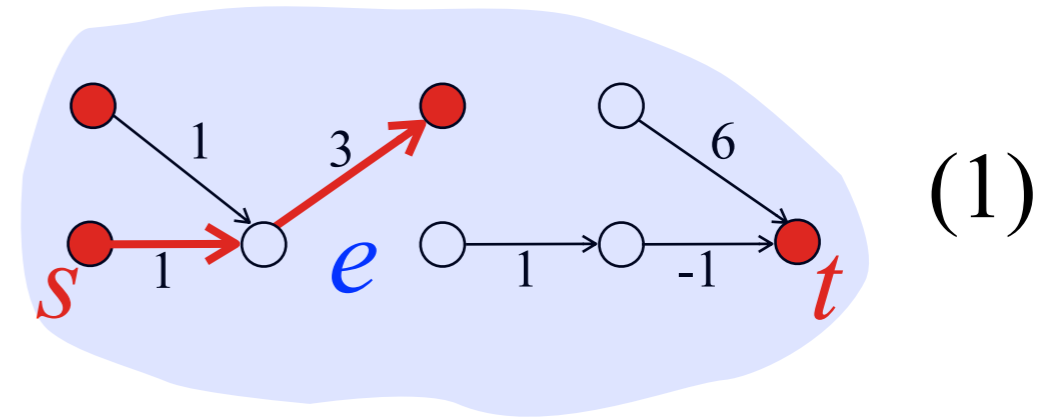
Constructing G_e

- Focus on ●-to-● distances in (1)



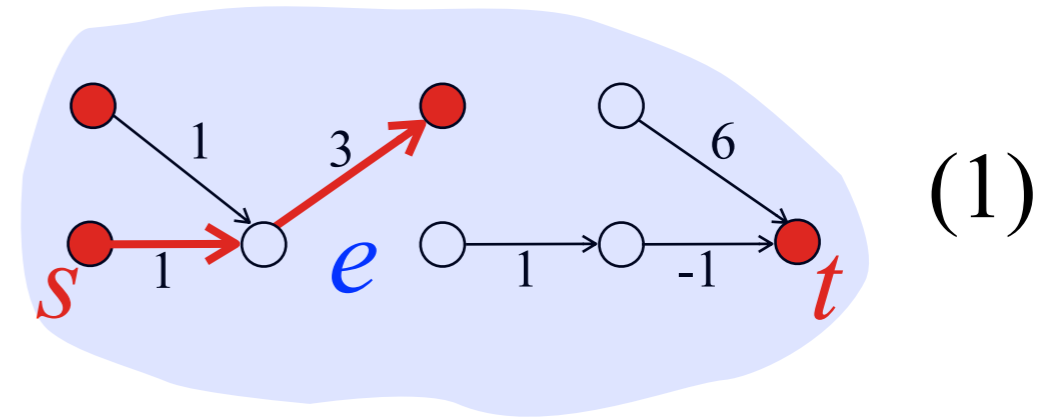
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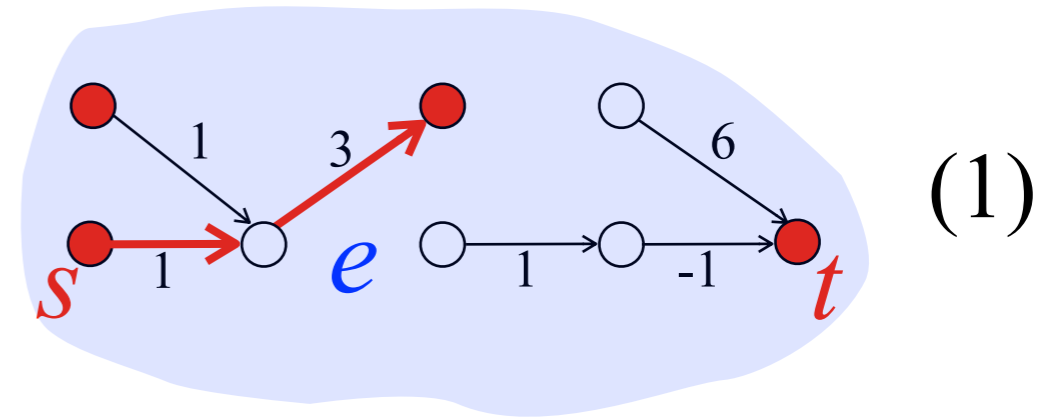
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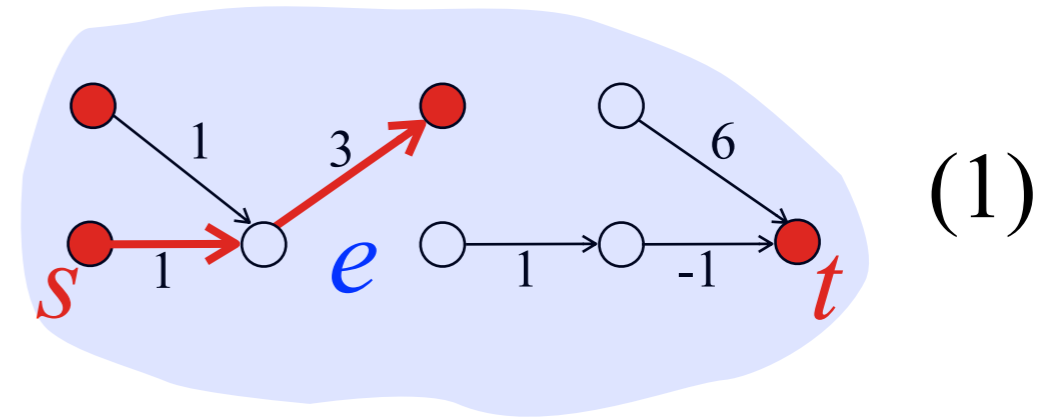
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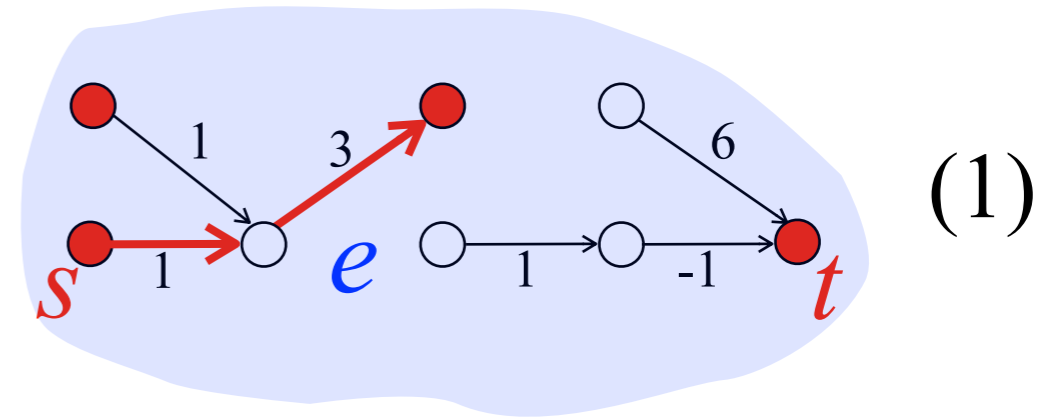
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(1)

Constructing G_e

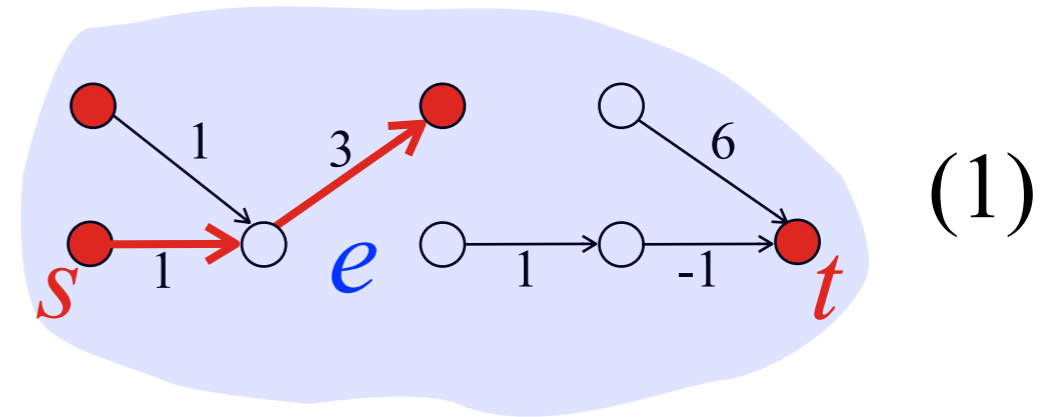
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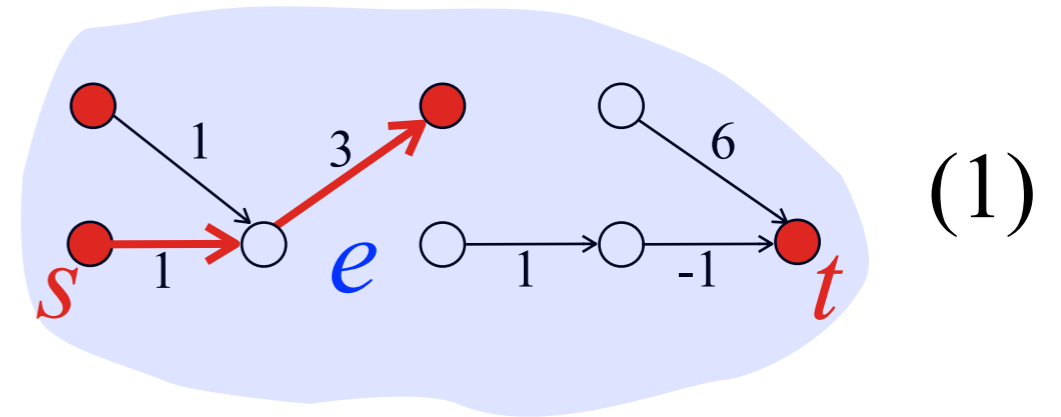
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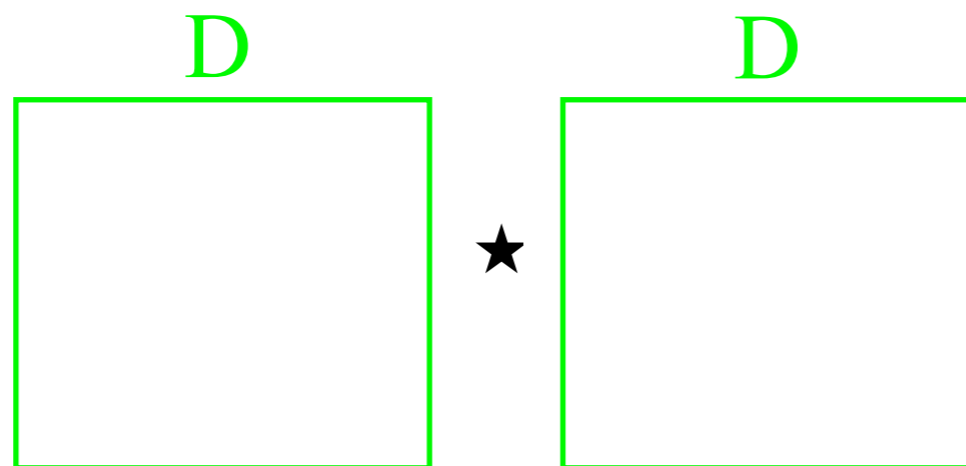
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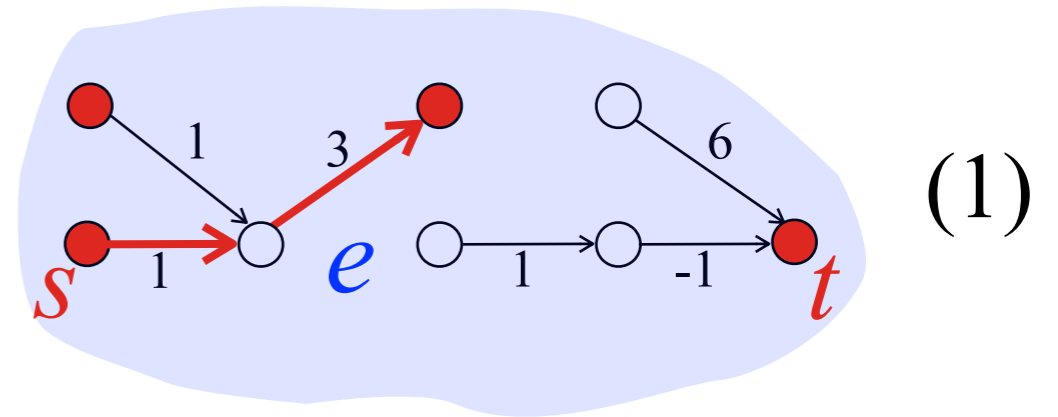


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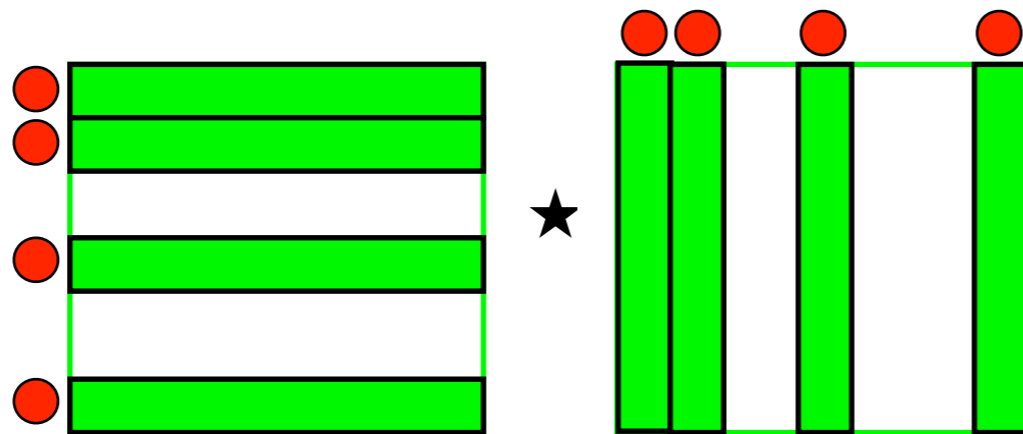


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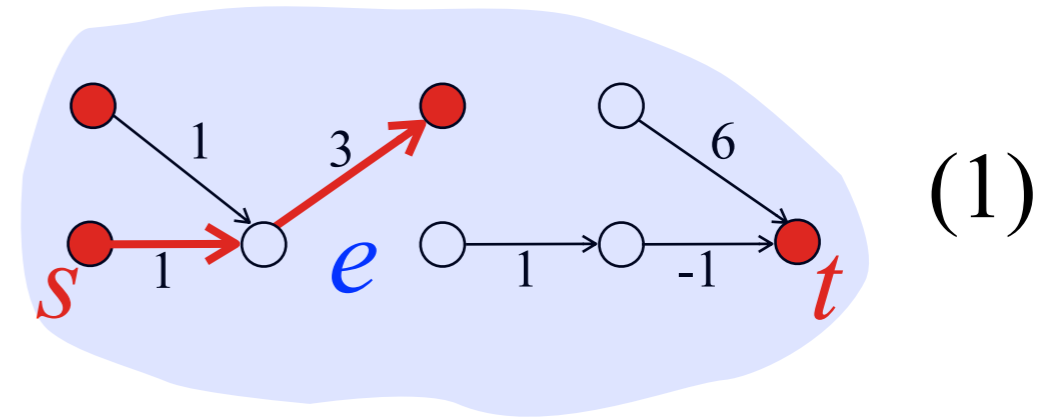


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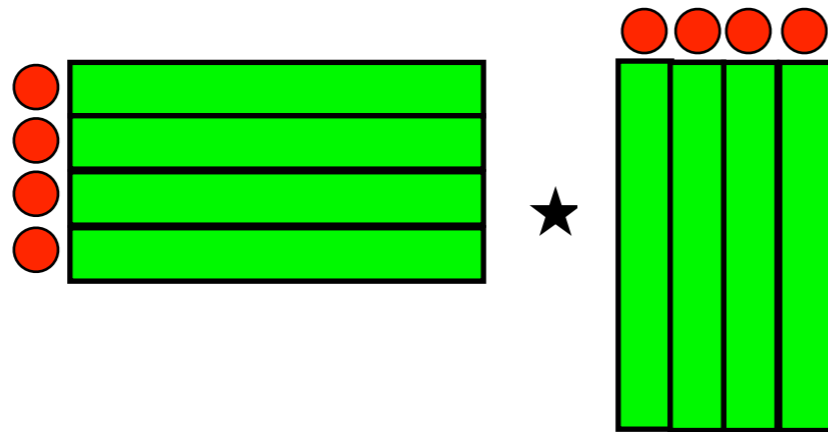


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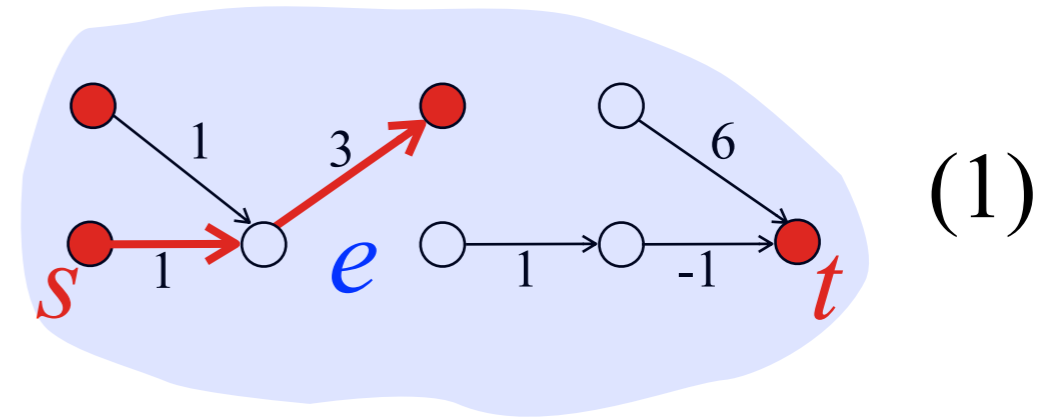


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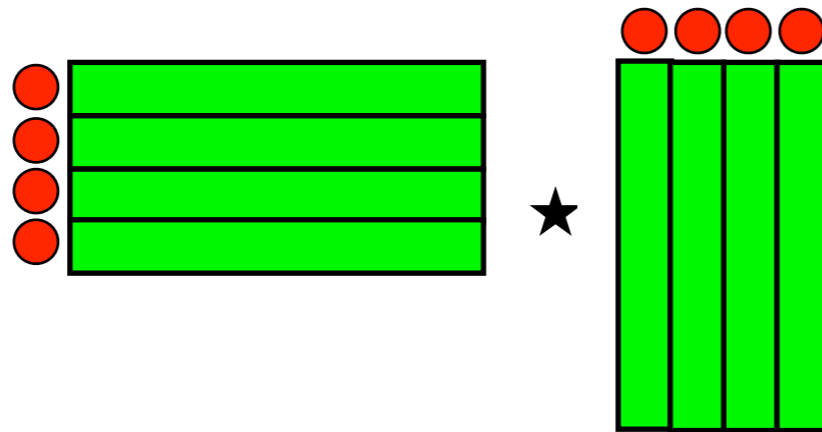


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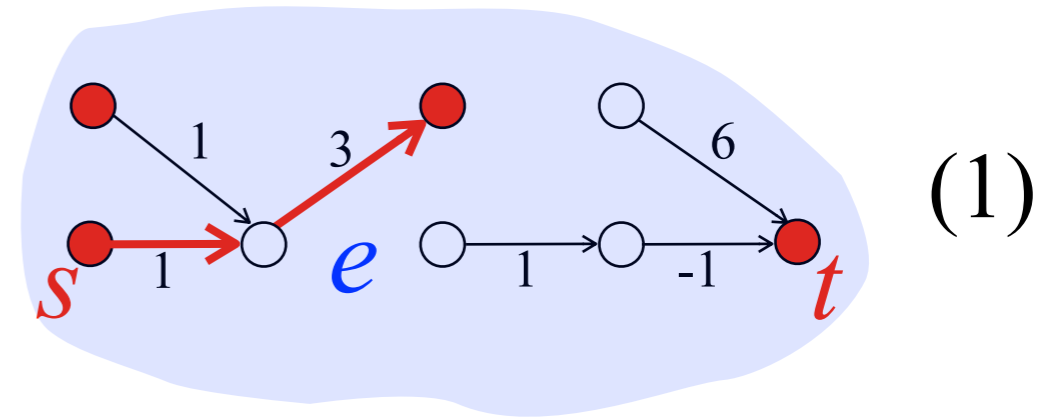
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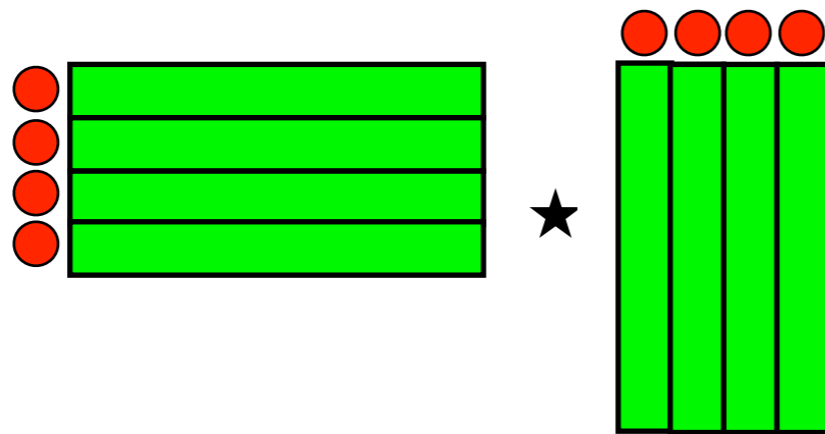
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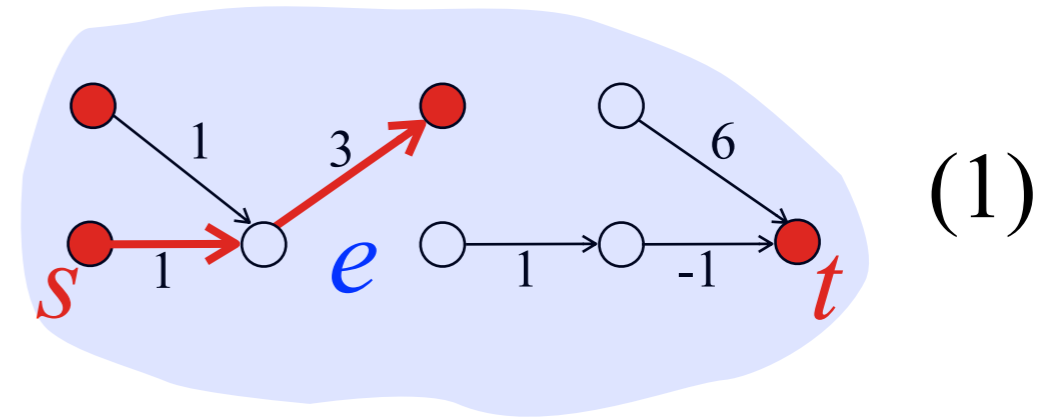


D elements can be as large as nM

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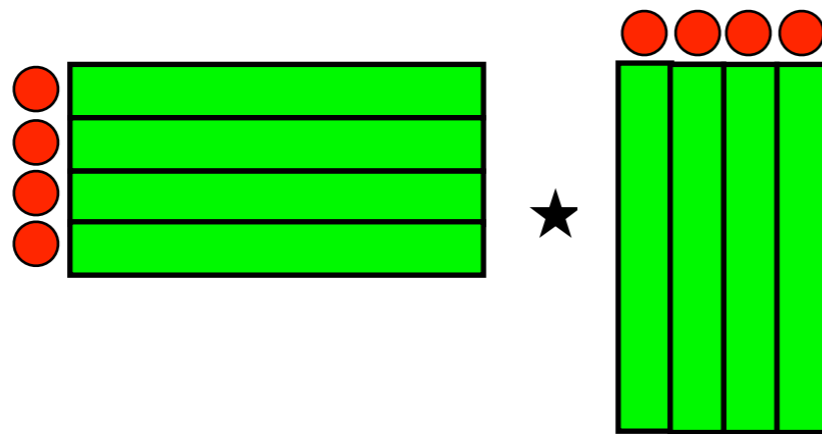
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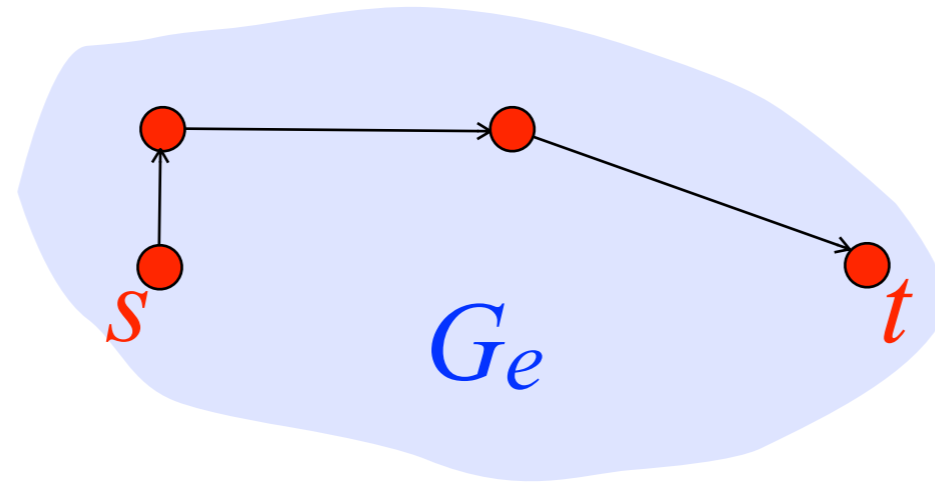
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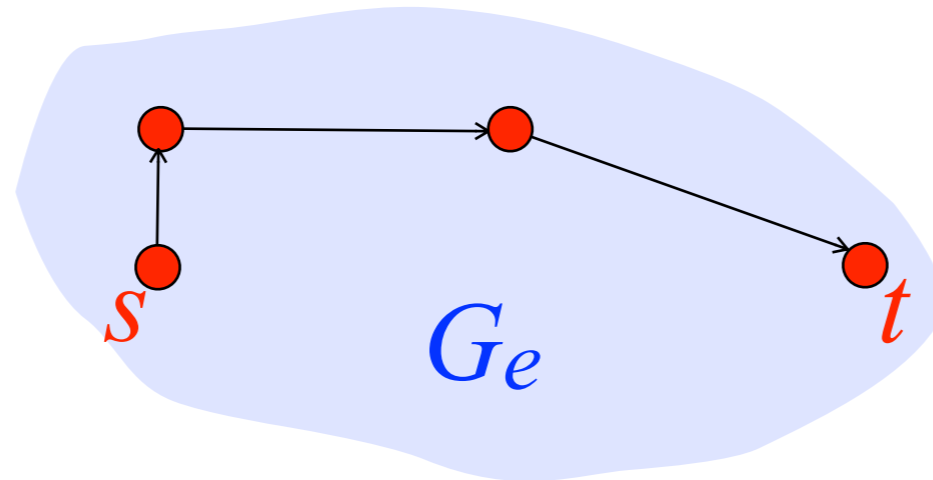
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 - Safe to ignore D elements larger than $Mn^{1-\alpha}$

Computing st -paths in all G_e



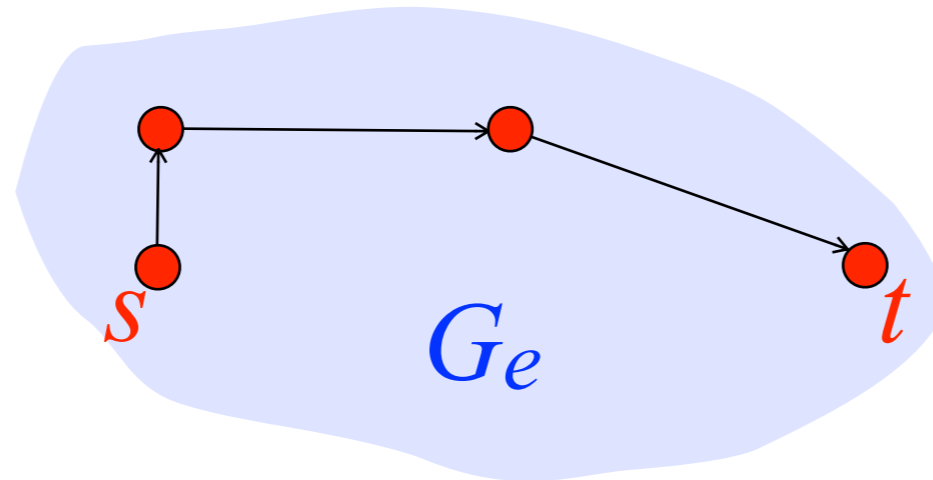
- Unbounded weights.

Computing st -paths in all G_e



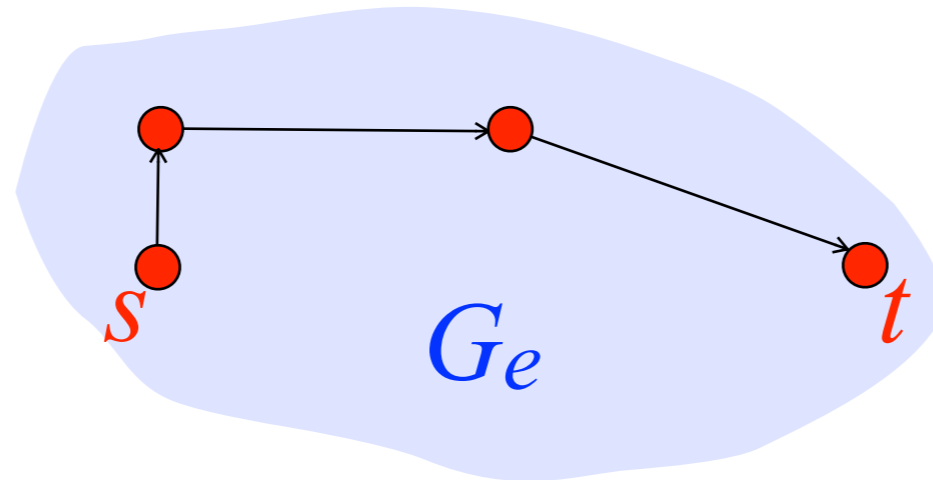
- Unbounded weights.
- n executions of Goldberg or Bellman-Ford 🤔

Computing st -paths in all G_e



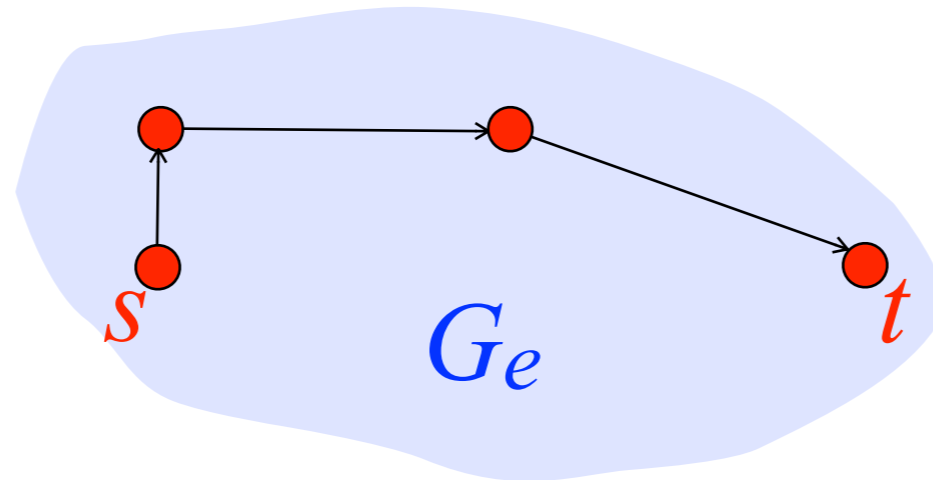
- Unbounded weights.
- n executions of Goldberg or Bellman-Ford 🤔
- 1 execution of Goldberg, n executions of Dijkstra 😊

Computing st -paths in all G_e



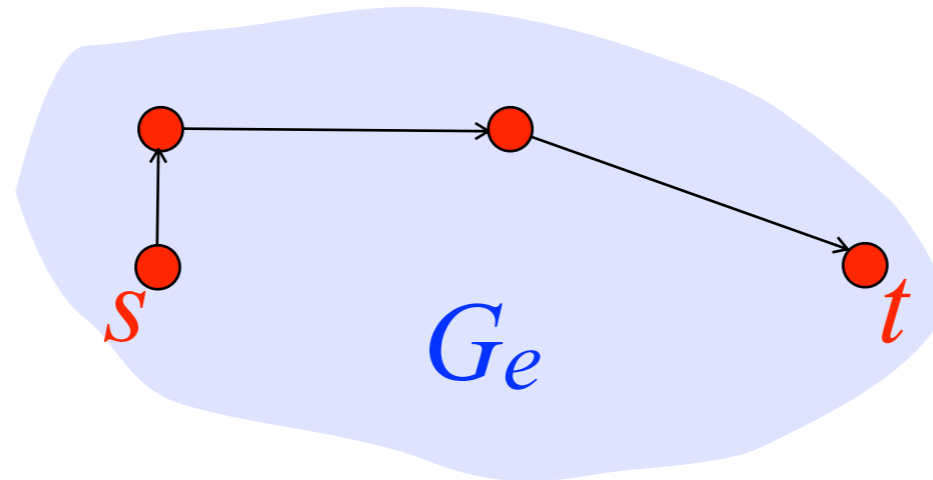
- Unbounded weights.
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- Compute shortest paths $d(v)$ from s in G

Computing st -paths in all G_e



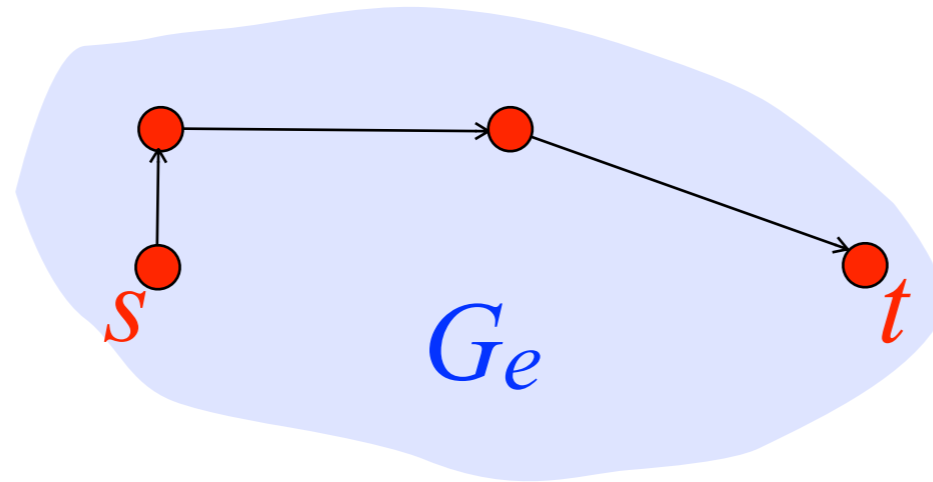
- Unbounded weights.
- n executions of Goldberg or Bellman-Ford 🤔
- 1 execution of Goldberg, n executions of Dijkstra 😊
- Compute shortest paths $d(v)$ from s in G
- In every G_e reweigh $w(u, v)$ to $w(u, v) + d(u) - d(v)$

Computing st -paths in all G_e



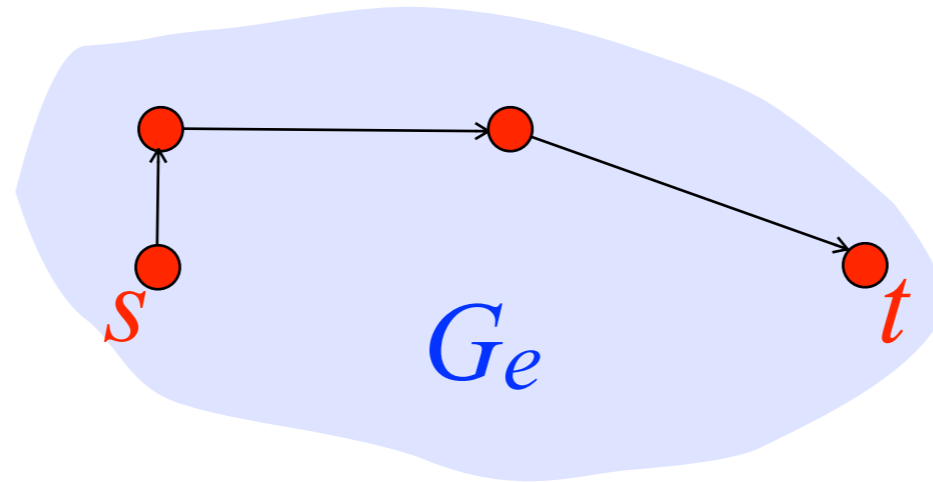
- Unbounded weights.
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- Compute shortest paths $d(v)$ from s in G
- In every G_e reweigh $w(u, v)$ to $w(u, v) + d(u) - d(v)$
 - Dijkstra on every (positive weighted) G_e

Computing st -paths in all G_e



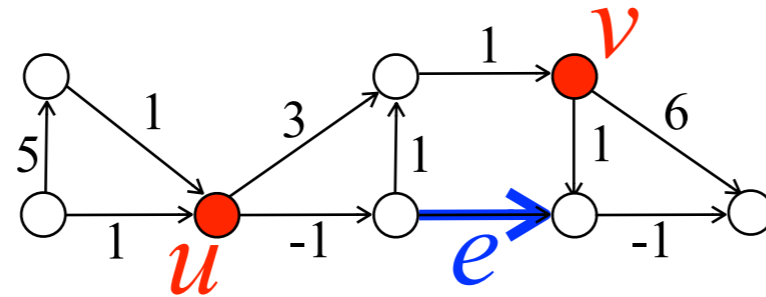
- Unbounded weights.
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- Compute shortest paths $d(v)$ from s in G
- In every G_e reweigh $w(u, v)$ to $w(u, v) + d(u) - d(v)$
 - Dijkstra on every (positive weighted) G_e
 - $O(n|B|^2)$

Putting it all Together



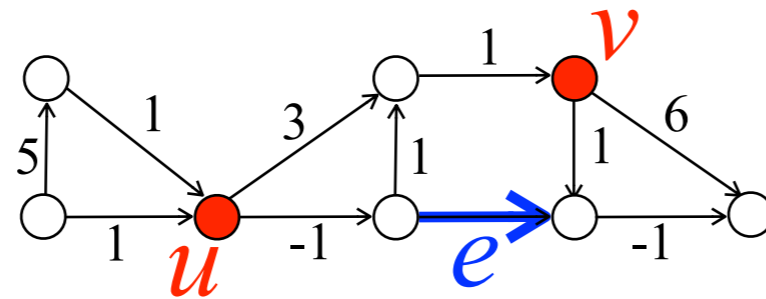
- Replacement paths in $\tilde{O}(Mn^{1+2\omega/3}) = O(Mn^{2.584})$ time.

All-pairs Replacement Paths



Query: (u, v, e) ?

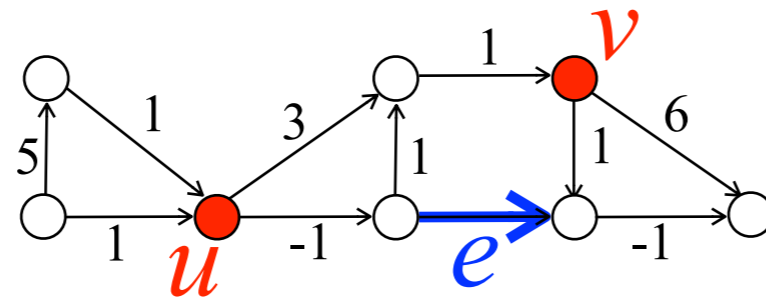
All-pairs Replacement Paths



Query: (u, v, e) ?

- $\tilde{O}(Mn^{1+\omega-\alpha})$ preprocessing: (not knowing u, v, e)
- $\tilde{O}(n^{1+\alpha})$ query time: (knowing u, v, e)

All-pairs Replacement Paths



Query: (u, v, e) ?

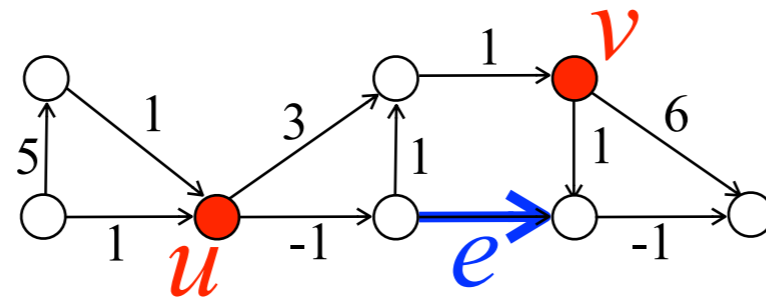
- $\tilde{O}(Mn^{1+\omega-\alpha})$ preprocessing: (not knowing u, v, e)

Construct the random graphs

Pick B , and compute $B \times B$ distances

- $\tilde{O}(n^{1+\alpha})$ query time: (knowing u, v, e)

All-pairs Replacement Paths



Query: (u, v, e) ?

- $\tilde{O}(Mn^{1+\omega-\alpha})$ preprocessing: (not knowing u, v, e)

Construct the random graphs

Pick B , and compute $B \times B$ distances

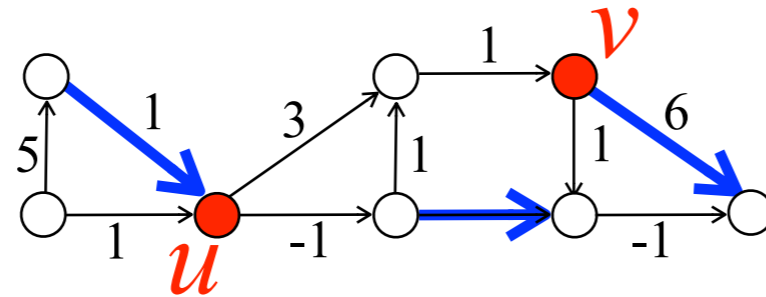
- $\tilde{O}(n^{1+\alpha})$ query time: (knowing u, v, e)

Identify the set F_e

Add u, v to B , and extend $B \times B$ distances

Construct G_e and run Dijkstra

Multiple Failures



Query: (u, v, \mathcal{S}) ?

- $\tilde{O}(Mn^{1+\omega-\alpha})$ preprocessing: (not knowing u, v, e)

Construct the random graphs

Pick \mathbf{B} , and compute $\mathbf{B} \times \mathbf{B}$ distances

- $\tilde{O}(n^{1+\alpha})$ query time: (knowing u, v, e)

Identify the set F_e

Add u, v to \mathbf{B} , and extend $\mathbf{B} \times \mathbf{B}$ distances

Construct G_e and run Dijkstra

Thank You!