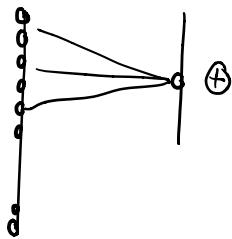
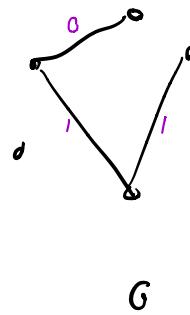
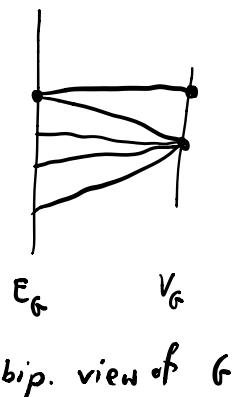


# Tanner / Sipser - Spielman Codes



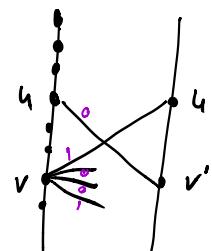
Let  $G$  be a  $d$ -reg graph  $G = (V_G, E_G)$



Let  $C_0 \subseteq \{0,1\}^d$  with distance  $d_0 d$ . Linear code.

Tanner code  $G(C_0) = \left\{ w : E \rightarrow \{0,1\} \mid \forall v \quad w|_{E(v)} \in C_0 \right\}$

Def: The double cover of  $G$  is a bip. graph  $G_2$  ( $V_G \cup V_{G'}, E = \{(u, v'), (u', v) \mid u \sim v\}$ )



Rate: Suppose  $\dim C_0 = \frac{r \cdot d}{\text{relative rate}}$

\*edges  
#verts  $h \cdot d$   
 $2 \cdot h$

# lin. constraints per vertex:  $d - rd$ .

# constraints in  $G_2(C_0)$        $2 \cdot n \cdot (d - rd)$

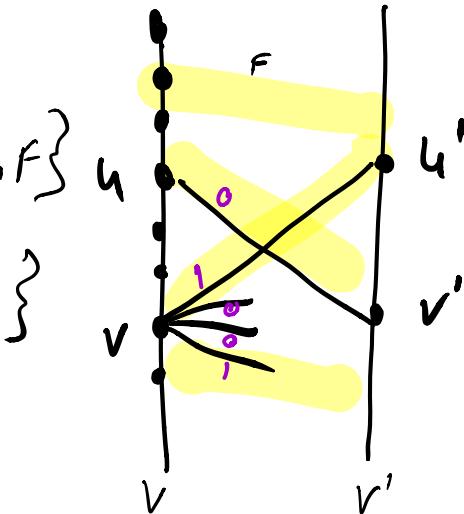
$$\dim G_2(C_0) \geq nd - 2nd + 2nr \underset{\uparrow}{d} = nd(2r - 1)$$

if  $r > \frac{1}{2}$   $G_2(C_0)$  has  $\Rightarrow$  rate  $> 0$ .

Distance: Let  $w \neq 0$  codeword. Let  $F = \{(a, b) \mid w(a, b) = 1\}$   
 $w: E \rightarrow \{0, 1\}$

$$S = \{u \in V \mid u \text{ touches an edge in } F\}$$

$$T = \{u' \in V' \mid \dots\}$$



EML :  $\frac{S \subseteq V}{T \subseteq V'} \quad |E(S, T)| - |S| \cdot |T| \cdot \frac{d}{n} \leq d \lambda \sqrt{|S| \cdot |T|}$

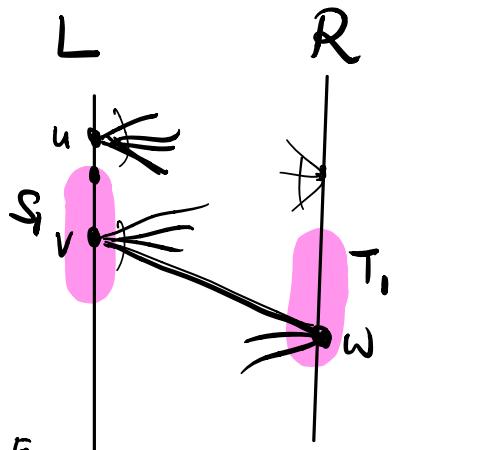
$\lambda$  normalized  
 $\max(\lambda_2, \lambda_1)$

$$\delta_0 d \cdot \sqrt{|S| \cdot |T|} \leq \max(\delta_0 d \cdot |T|, \delta_0 \cdot d \cdot |S|) \leq |F| \leq |E(S, T)| \leq |S| \cdot |T| \cdot \frac{d}{n} + d \lambda \sqrt{|S| \cdot |T|}$$

$$d \cdot (\delta_0 - \lambda) \leq \sqrt{|S| \cdot |T|} \cdot \frac{d}{n} \leq \frac{d}{n} \cdot \frac{|F|}{\delta_0 d}$$

$$\underbrace{n d \delta_0}_{\sim} (\delta_0 - \lambda) \leq |F| \quad \square$$

**Lemma 17** Assume that  $\lambda < \delta_0/3$ . When the number of errors is at most  $(1 - \epsilon) \frac{\delta_0}{2} (\frac{\delta_0}{2} - \frac{\lambda}{d})nd$ , the above algorithm converges to the correct codeword when run for  $A(\epsilon) \log n$  iterations.



ALG

All left decode (local-correct)  
All right decode  
repeat.

input:  $y \in \{0,1\}^E$

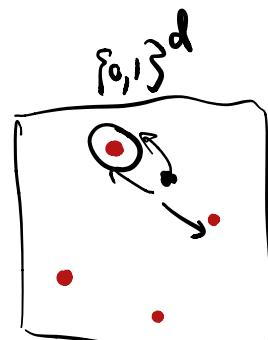
"error" means bit that differs from  $w_e \in C$  the nearest codeword.

$$F = \left\{ e \in E \mid \begin{array}{l} w(e) \neq y(e) \\ \uparrow \quad \uparrow \\ \text{closest codeword} \quad \text{received} \end{array} \right\}$$

$$S_L = \left\{ u \in L \mid u \text{ sees an error after the first left-decoding} \right\}$$

every  $u \in S_L$  sees  $\geq \frac{\delta_0 d}{2}$  errors

$$|S_L| \cdot \frac{\delta_0 d}{2} \leq |F| \leq (1 - \epsilon) \frac{\delta_0}{2} \left( \frac{\delta_0}{2} - \frac{\lambda}{d} \right) nd$$



$$\rightarrow |S_L| \leq (1 - \epsilon) \left( \frac{\delta_0}{2} - \frac{\lambda}{d} \right) \cdot n$$

$$T_R = \left\{ v \in R \mid v \text{ sees an error after the first right-decoding} \right\}$$

Claim:  $|T_R| \leq \frac{|S_L|}{1 + \epsilon}$

$$|T_1| \cdot \frac{\delta_0 d}{2} \leq_{\lambda} E(S_1, T_1)$$

errors  $\leq$

$$E(S_1, T_1) \leq \underbrace{\frac{1}{n} |S_1| \cdot |T_1|}_{\text{errors}} + \lambda d \sqrt{|S_1| \cdot |T_1|}$$

$$\frac{\delta_0 d}{2} \cdot |T_1| \leq |T_1| \cdot \left( \frac{d \delta_0}{2} - \lambda \right) (1-\varepsilon) + \lambda d \frac{|S_1| + |T_1|}{2}$$

$$|T_1| \leq \frac{\lambda d}{\varepsilon \delta_0 d + (1-2\varepsilon) \lambda d} \cdot |S_1| \leq \frac{|S_1|}{1+\varepsilon}$$

$\lambda \leq \frac{\varepsilon b}{3}$ .

Conclusion: after 1 step, #error vertices shrinks by

— after  $\log_{1+\varepsilon} n$  steps we converge.

$$\text{rate, distance.} \rightarrow r_0 > \frac{1}{2} + \varepsilon \quad 2r - 1 \sim 2\varepsilon$$

$$\rightarrow \delta_0$$

$$\underbrace{\delta_0 (\delta_0 - \lambda)}_{\gamma}$$

$$h(\delta_0) + r > 1 - \varepsilon$$