

Intro to learning theory - ex 4

1. Prove lemma 2.2 and 2.3 in lecture 7.
2. Define $\ell^{0-1}(y, y') = \frac{1}{2}(\text{sign}(y' \cdot y) + 1)$ and $\ell^h(y, y') = \max\{0, 1 - y \cdot y'\}$. Prove that if $\ell(y, y')$ is convex, 1-Lipshitz in y' and $\forall y, y' : \ell^{0-1}(y, y') \leq \ell(y, y')$ then $\forall y, y' : \ell^h(y, y') \leq \ell(y, y')$. This shows that the hinge loss is the smallest surrogate loss with these properties.
3. Define $\mathcal{H}_1 = \{h_w(x) = \langle x, w \rangle : \|w\|_1 \leq 1\}$ where $\|x\|_1 = \sum_{i=1}^d |x_i|$. Let $S = \{x_1, \dots, x_m\}$ be vectors in \mathbb{R}^d . Prove that

$$R(\mathcal{H}_1 \circ S) = R(\{(\langle x_1, w \rangle, \dots, \langle x_m, w \rangle) : \|w\|_1 \leq 1\}) \leq \max_i \|x\|_\infty \sqrt{\frac{2 \log(2d)}{m}}$$

where $\|x\|_\infty = \max_i |x_i|$.

Hint: You can use the result from the Holder inequality, $\langle x, y \rangle \leq \|x\|_1 \cdot \|y\|_\infty$ to reduce the problem to a finite set.

4. Learnability without uniform convergence: Let B_d be the unit ball in \mathbb{R}^d . Define $\mathcal{H} = B_d$, $Z = B_d \times \{0, 1\}^d$ and The loss function ℓ is define as $\ell(w, (x, \alpha)) = \sum_{i=1}^d \alpha_i (x_i - w_i)^2$. Intuitively, we need to learn the "center of mass" of the distribution only we get another vector α of binary weights which tells us which indices we can ignore for this example.

- (a) Show that this can be learned using regularized risk minimization, with sample complexity independent of d .
- (b) Consider a distribution \mathcal{D} over Z as follows: x is fixed to be some x_0 , and each element of α is sampled to be either 1 or 0 with equal probability. Show that the rate of uniform convergence of this problem grows with d .

Hint: Let m be a training set size. Show that if $d \gg 2^m$, then there is a high probability to sample a set of examples such that there exists some $j \in [d]$ for which $\alpha_j = 0$ for all samples in the training set.