A Near-Optimal Algorithm for Testing Isomorphism of Two Unknown Graphs

#### Krzysztof Onak IBM T.J. Watson Research Center

Joint work with Xiaorui Sun (Columbia)

Problem: Are two graphs identical?



Problem: Are two graphs identical?



Problem: Are two graphs identical?



Problem: Are two graphs identical?



Status:

- Not known to be in P or NP-hard
- **D** Best known algorithm:  $2^{\tilde{O}(\sqrt{n})}$  time (early 1980's)

## **Property Testing Version**

This Talk: Dense graph model



	1	1	0	1	1	0
1		0	0	1	0	0
1	0		0	0	1	0
0	0	0		1	1	1
1	1	0	1		0	1
1	0	1	1	0		1
0	0	0	1	1	1	

# **Property Testing Version**

This Talk: Dense graph model



	1	1	0	1	1	0
1		0	0	1	0	0
1	0		0	0	1	0
0	0	0		1	1	1
1	1	0	1		0	1
1	0	1	1	0		1
0	0	0	1	1	1	

Requirements:

- accept with probability 9/10 if graphs isomorphic
- reject with probability 9/10 if for any matching of vertices at least  $\epsilon n^2$  edges disagree

# **Property Testing Version**

This Talk: Dense graph model



	1	1	0	1	1	0
1		0	0	1	0	0
1	0		0	0	1	0
0	0	0		1	1	1
1	1	0	1		0	1
1	0	1	1	0		1
0	0	0	1	1	1	

Requirements:

- accept with probability 9/10 if graphs isomorphic
- reject with probability 9/10 if for any matching of vertices at least  $\epsilon n^2$  edges disagree
- This talk: focus on the complexity as a function of n, assume that  $\epsilon$  is a small constant (say,  $\epsilon = 10^{-9}$ )

# **Query Complexity**

Fischer, Matsliah (2006):

	Upper bound	Lower bound
One sided error, one graph known	$\widetilde{O}(n)$	$\Omega(n)$
One sided error, both graphs unknown	$\widetilde{O}(n^{3/2})$	$\Omega(n^{3/2})$
Two sided error, one graph known	$\widetilde{O}(n^{1/2})$	$\Omega(n^{1/2})$
Two sided error, both graphs unknown	$\widetilde{O}(n^{5/4})$	$\Omega(n)$

#### (one sided error = never reject if isomorphic)

# **Query Complexity**

Fischer, Matsliah (2006):

	Upper bound	Lower bound
One sided error, one graph known	$\widetilde{O}(n)$	$\Omega(n)$
One sided error, both graphs unknown	$\widetilde{O}(n^{3/2})$	$\Omega(n^{3/2})$
Two sided error, one graph known	$\widetilde{O}(n^{1/2})$	$\Omega(n^{1/2})$
Two sided error, both graphs unknown	$\widetilde{O}(n^{5/4})$	$\Omega(n)$

(one sided error = never reject if isomorphic)

Remaining open case:

neither graph known, two-sided testing

# **Query Complexity**

Fischer, Matsliah (2006):

	Upper bound	Lower bound
One sided error, one graph known	$\widetilde{O}(n)$	$\Omega(n)$
One sided error, both graphs unknown	$\widetilde{O}(n^{3/2})$	$\Omega(n^{3/2})$
Two sided error, one graph known	$\widetilde{O}(n^{1/2})$	$\Omega(n^{1/2})$
Two sided error, both graphs unknown	$\widetilde{O}(n^{5/4})$	$\Omega(n)$

(one sided error = never reject if isomorphic)

Remaining open case:

neither graph known, two-sided testing

Our result:

Algorithm that makes  $n \cdot 2^{O(\sqrt{\log n})}$  queries

# Review of Fischer-Matsliah Techniques

#### **Core sets**

• Core set = list of polylog *n* vertices  $(v_1, v_2, \ldots, v_k)$ 



#### **Core sets**

- Core set = list of polylog *n* vertices  $(v_1, v_2, \ldots, v_k)$
- Every vertex u has a label  $l \in \{0, 1\}^k$  with respect to core set:



#### **Core sets**

- Core set = list of polylog *n* vertices  $(v_1, v_2, \ldots, v_k)$
- Every vertex u has a label  $l \in \{0, 1\}^k$  with respect to core set:



Intuition: a large random core set partitions vertices into sets of similar vertices

If G and H have core sets  $(v_1, \ldots, v_k)$  and  $(w_1, \ldots, w_k)$ , respectively, such that:



If G and H have core sets  $(v_1, \ldots, v_k)$  and  $(w_1, \ldots, w_k)$ , respectively, such that:

• the distributions on labels are  $\epsilon_1$ -close



If G and H have core sets  $(v_1, \ldots, v_k)$  and  $(w_1, \ldots, w_k)$ , respectively, such that:

- the distributions on labels are  $\epsilon_1$ -close
- if you take two random vertices in *G* and two random vertices in *H* with the same labels, then w.p.  $1 \epsilon_2$ , the connectivity is the same



If G and H have core sets  $(v_1, \ldots, v_k)$  and  $(w_1, \ldots, w_k)$ , respectively, such that:

- the distributions on labels are  $\epsilon_1$ -close
- if you take two random vertices in G and two random vertices in H with the same labels, then w.p.  $1 \epsilon_2$ , the connectivity is the same

then G and H are  $\epsilon_3$ -close to being isomorphic



If G and H have core sets  $(v_1, \ldots, v_k)$  and  $(w_1, \ldots, w_k)$ , respectively, such that:

- the distributions on labels are  $\epsilon_1$ -close
- if you take two random vertices in G and two random vertices in H with the same labels, then w.p.  $1 \epsilon_2$ , the connectivity is the same

then G and H are  $\epsilon_3$ -close to being isomorphic



Generic tester:

Search for such a pair of core sets and accept if found

#### • Select $\tilde{O}(n^{3/4})$ random vertices $V_G^{\star}$ from G



• Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices



- Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices
- Select  $\tilde{O}(n^{1/4})$  random vertices  $V_H^{\star}$  from H



- Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices
- Select  $\tilde{O}(n^{1/4})$  random vertices  $V_H^{\star}$  from Hand query their connections to all other vertices



- Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices
- Select  $\tilde{O}(n^{1/4})$  random vertices  $V_H^{\star}$  from Hand query their connections to all other vertices
- Enumerate over all possible core sets from  $V_G^{\star}$  and  $V_H^{\star}$  (quasipoly(*n*) options)



- Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices
- Select  $\tilde{O}(n^{1/4})$  random vertices  $V_H^{\star}$  from *H* and query their connections to all other vertices
- Enumerate over all possible core sets from  $V_G^{\star}$  and  $V_H^{\star}$  (quasipoly(*n*) options)
- For each pair of candidates:
  - Step 1: See if distributions of labels similar (Use the  $\tilde{O}(\sqrt{n})$ -sample tester of Batu et al. (2001))

- Select  $\tilde{O}(n^{3/4})$  random vertices  $V_G^{\star}$  from Gand query their connections to  $\tilde{O}(n^{1/2})$  random vertices
- Select  $\tilde{O}(n^{1/4})$  random vertices  $V_H^{\star}$  from Hand query their connections to all other vertices
- Enumerate over all possible core sets from  $V_G^{\star}$  and  $V_H^{\star}$  (quasipoly(*n*) options)
- For each pair of candidates:
  - Step 1: See if distributions of labels similar (Use the  $\tilde{O}(\sqrt{n})$ -sample tester of Batu et al. (2001))
  - Step 2: Select polylog n pairs of random vertices in G and see if the connectivity of their labels almost the same in H

# **First Attempts**

# **Better Label Distribution Testing?**

- Idea: Use a different distribution tester
  - Select  $\tilde{O}(\sqrt{n})$  vertices from G and H
  - Query connections to random subset of size  $\tilde{O}(n^{2/3})$
  - Use the distribution tester of Batu et al. (2000)
  - Query Complexity:  $\tilde{O}(n^{7/6})$

# **Better Label Distribution Testing?**

- Idea: Use a different distribution tester
  - Select  $\tilde{O}(\sqrt{n})$  vertices from G and H
  - Query connections to random subset of size  $\tilde{O}(n^{2/3})$
  - Use the distribution tester of Batu et al. (2000)
  - Query Complexity:  $\tilde{O}(n^{7/6})$
- Problem: Unclear how to do Step 2
  - Only a subset of labels known
  - Sampling subsets and comparing discovered identical labels introduces a bias



# **Better Label Distribution Testing?**

- Idea: Use a different distribution tester
  - Select  $\tilde{O}(\sqrt{n})$  vertices from G and H
  - Query connections to random subset of size  $\tilde{O}(n^{2/3})$
  - Use the distribution tester of Batu et al. (2000)
  - Query Complexity:  $\tilde{O}(n^{7/6})$
- Problem: Unclear how to do Step 2
  - Only a subset of labels known
  - Sampling subsets and comparing discovered identical labels introduces a bias



Ignore this issue for now

• Could the  $\Omega(n^{2/3})$  distribution testing lower bound [Valiant 2008] imply a  $\Omega(n^{7/6})$  lower bound?



• Could the  $\Omega(n^{2/3})$  distribution testing lower bound [Valiant 2008] imply a  $\Omega(n^{7/6})$  lower bound?



We have additional information

• Could the  $\Omega(n^{2/3})$  distribution testing lower bound [Valiant 2008] imply a  $\Omega(n^{7/6})$  lower bound?



- We have additional information:
  - Estimate in advance distances between adjacency vectors in both graphs
  - We care about random core sets, where labels preserve distances between adjacency vectors
  - We should be able to distinguish heavy and light elements

• Could the  $\Omega(n^{2/3})$  distribution testing lower bound [Valiant 2008] imply a  $\Omega(n^{7/6})$  lower bound?



- We have additional information:
  - Estimate in advance distances between adjacency vectors in both graphs
  - We care about random core sets, where labels preserve distances between adjacency vectors
  - We should be able to distinguish heavy and light elements
- Nice consistent clustering of slightly different adjacency vectors still difficult

Our Algorithm
$(O^{\star}(f(n)) \equiv O(f(n)) \cdot 2^{O(\sqrt{\log n})})$ 

#### $(O^{\star}(f(n)) \equiv O(f(n)) \cdot 2^{O(\sqrt{\log n})})$

• Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$ 
  - Step 0: sample  $O^*(\sqrt{n})$  vertices to see if the core sets preserve distances well

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$ 
  - Step 0: sample  $O^*(\sqrt{n})$  vertices to see if the core sets preserve distances well
  - Step 1: relaxed test required to reject only sets of labels that are far in Earth-Mover Distance

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$ 
  - Step 0: sample  $O^*(\sqrt{n})$  vertices to see if the core sets preserve distances well
  - Step 1: relaxed test required to reject only sets of labels that are far in Earth-Mover Distance
  - Step 2: approximate matching of labels, rejection sampling to avoid biases

#### $(O^{\star}(f(n)) \equiv O(f(n)) \cdot 2^{O(\sqrt{\log n})})$

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$ 
  - Step 0: sample  $O^*(\sqrt{n})$  vertices to see if the core sets preserve distances well
  - Step 1: relaxed test required to reject only sets of labels that are far in Earth-Mover Distance
  - Step 2: approximate matching of labels, rejection sampling to avoid biases

#### Will show simplified versions

#### $(O^{\star}(f(n)) \equiv O(f(n)) \cdot 2^{O(\sqrt{\log n})})$

- Compute good approximations of distances between adjacency vectors with  $O^*(n)$  queries
- Sample  $O^{\star}(\sqrt{n})$  vertices from both graphs
- Consider all pairs of corsets of size  $O^{\star}(1)$ 
  - Step 0: sample  $O^*(\sqrt{n})$  vertices to see if the core sets preserve distances well
  - Step 1: relaxed test required to reject only sets of labels that are far in Earth-Mover Distance
  - Step 2: approximate matching of labels, rejection sampling to avoid biases

Will show simplified versions Assume labels preserve all distances

Standard distribution testing collisions: identical labels

- Standard distribution testing collisions: identical labels
- Here:
  - pick small threshold r
  - labels at distance r collide



- Standard distribution testing collisions: identical labels
- Here:
  - pick small threshold r
  - labels at distance r collide
- Can apply the standard distribution testing?
  - Not in a trivial way
  - Colliding vertices can have very different degrees
  - Hard to partition them into classes of similar degrees

- Standard distribution testing collisions: identical labels
- Here:
  - pick small threshold r
  - Jabels at distance r collide
- Can apply the standard distribution testing?
  - Not in a trivial way
  - Colliding vertices can have very different degrees
  - Hard to partition them into classes of similar degrees
- Our solution:
  - $\hfill \hfill \hfill$
  - Design a tool for estimating the number of collisions
  - Reject only if Earth-Mover Distance large

• Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$ 



- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?



- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 15/22

- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels
- Requirement: good multiplicative approximation



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 15/22

- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels
- Requirement: good multiplicative approximation
- Problem: What if few of them do?



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 15/22

- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels
- Requirement: good multiplicative approximation
- Problem: What if few of them do?
- ▶ Pick a threshold  $r = 2^{-t} / \operatorname{polylog} n$ , where  $t \in [0, O(\sqrt{\log n})]$



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 15/22

- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels
- Requirement: good multiplicative approximation
- Problem: What if few of them do?
- Pick a threshold  $r = 2^{-t} / \operatorname{polylog} n$ , where  $t \in [0, O(\sqrt{\log n})]$

• For most thresholds most points will require  $O^*(1)$  samples



- Found colliding labels for vertices  $v \in V[G]$  and  $w \in V[H]$
- **Question:** How many vertices in H have labels colliding with v?
- Solution: Sample similar vertices in H up to distance 2r + (error-term) and see their labels
- Requirement: good multiplicative approximation
- Problem: What if few of them do?
- Pick a threshold  $r = 2^{-t} / \operatorname{polylog} n$ , where  $t \in [0, O(\sqrt{\log n})]$

• For most thresholds most points will require  $O^*(1)$  samples



• Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )



- Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )
- $f_G : \mathcal{M}_G \to \mathcal{M}$  and  $f_H : \mathcal{M}_H \to \mathcal{M}$  preserve distances up to a small additive term



- Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )
- $f_G : \mathcal{M}_G \to \mathcal{M}$  and  $f_H : \mathcal{M}_H \to \mathcal{M}$  preserve distances up to a small additive term
- Tester required to
  - Accept if  $f_G(\mathcal{M}_G) = f_H(\mathcal{M}_H)$



- Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )
- $f_G : \mathcal{M}_G \to \mathcal{M}$  and  $f_H : \mathcal{M}_H \to \mathcal{M}$  preserve distances up to a small additive term
- Tester required to
  - Accept if  $f_G(\mathcal{M}_G) = f_H(\mathcal{M}_H)$
  - Reject if  $\operatorname{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \geq \epsilon n$



- Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )
- $f_G : \mathcal{M}_G \to \mathcal{M}$  and  $f_H : \mathcal{M}_H \to \mathcal{M}$  preserve distances up to a small additive term
- Tester required to
  - Accept if  $f_G(\mathcal{M}_G) = f_H(\mathcal{M}_H)$
  - Reject if  $\operatorname{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \geq \epsilon n$
- Our solution:
  - Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ , and vice versa

- Three metric spaces:  $\mathcal{M}_G$ ,  $\mathcal{M}_H$ ,  $\mathcal{M}$ (diameter bounded by 1,  $|\mathcal{M}_G| = |\mathcal{M}_H| = n$ )
- $f_G : \mathcal{M}_G \to \mathcal{M}$  and  $f_H : \mathcal{M}_H \to \mathcal{M}$  preserve distances up to a small additive term
- Tester required to
  - Accept if  $f_G(\mathcal{M}_G) = f_H(\mathcal{M}_H)$
  - Reject if  $\operatorname{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \geq \epsilon n$
- Our solution:
  - Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ , and vice versa
  - Step 1b: if two points collide make sure their metrics can be matched

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

**•** Take  $O^*(\sqrt{n})$  samples

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- **•** Take  $O^*(\sqrt{n})$  samples
- Estimate weighted number of collisions

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- **•** Take  $O^*(\sqrt{n})$  samples
- Estimate weighted number of collisions
- Divide each collision by the estimated number of collisions

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- Take  $O^*(\sqrt{n})$  samples
- Estimate weighted number of collisions
- Divide each collision by the estimated number of collisions
- Bad case:



Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- Take  $O^*(\sqrt{n})$  samples
- Estimate weighted number of collisions
- Divide each collision by the estimated number of collisions
- Bad case:



Randomized threshold makes it unlikely to happen for a large fraction of vertices

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- Take  $O^{\star}(\sqrt{n})$  samples
- Estimate weighted number of collisions
- Divide each collision by the estimated number of collisions
- Bad case:



Randomized threshold makes it unlikely to happen for a large fraction of vertices

Step 1b: if two points  $p_G$  and  $p_H$  collide make sure their metrics can be matched

Step 1a: make sure almost all points in  $f_G(\mathcal{M}_G)$  collide with  $f_H(\mathcal{M}_H)$ 

- **J** Take  $O^*(\sqrt{n})$  samples
- Estimate weighted number of collisions
- Divide each collision by the estimated number of collisions
- Bad case:



- Randomized threshold makes it unlikely to happen for a large fraction of vertices
- Step 1b: if two points  $p_G$  and  $p_H$  collide make sure their metrics can be matched
  - Is there a mapping  $\mathcal{F} : \mathcal{M}_G \to \mathcal{M}_H$ , where  $\mathcal{F}(p_G) = p_H$ and all distances preserved up to a small additive term?

## Why This Works

• Need to show that  $\text{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \leq \epsilon n$  if passes the test
- Need to show that  $\text{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \leq \epsilon n$  if passes the test
- We show a large fractional matching using short edges

- Need to show that  $\text{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \leq \epsilon n$  if passes the test
- We show a large fractional matching using short edges
- Two step process:
  - Each point in  $f_G(\mathcal{M}_G)$  sends flow to hubs in  $f_G(\mathcal{M}_G)$
  - Each point in  $f_H(\mathcal{M}_H)$  receives flow from hubs in  $f_G(\mathcal{M}_G)$



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 18/22

- Need to show that  $\text{EMD}(f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)) \leq \epsilon n$  if passes the test
- We show a large fractional matching using short edges
- Two step process:
  - Each point in  $f_G(\mathcal{M}_G)$  sends flow to hubs in  $f_G(\mathcal{M}_G)$
  - Each point in  $f_H(\mathcal{M}_H)$  receives flow from hubs in  $f_G(\mathcal{M}_G)$
- Each point sends/receives one unit, but hubs handle arbitrary amount of flow



Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 18/22

- Need to show that EMD( $f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)$ ) ≤  $\epsilon n$  if passes the test
- We show a large fractional matching using short edges
- Two step process:
  - Each point in  $f_G(\mathcal{M}_G)$  sends flow to hubs in  $f_G(\mathcal{M}_G)$
  - Each point in  $f_H(\mathcal{M}_H)$  receives flow from hubs in  $f_G(\mathcal{M}_G)$
- Each point sends/receives one unit, but hubs handle arbitrary amount of flow
- Amount sent to/received from point x proportional to  $\exp(-\delta(x,y) \cdot \operatorname{polylog} n)$

- Need to show that EMD( $f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)$ ) ≤  $\epsilon n$  if passes the test
- We show a large fractional matching using short edges
- Two step process:
  - Each point in  $f_G(\mathcal{M}_G)$  sends flow to hubs in  $f_G(\mathcal{M}_G)$
  - Each point in  $f_H(\mathcal{M}_H)$  receives flow from hubs in  $f_G(\mathcal{M}_G)$
- Each point sends/receives one unit, but hubs handle arbitrary amount of flow
- Amount sent to/received from point x proportional to  $\exp(-\delta(x,y) \cdot \operatorname{polylog} n)$
- For almost matching metrics: each hub receives and sends almost the same amount

- Need to show that EMD( $f_G(\mathcal{M}_G), f_H(\mathcal{M}_H)$ ) ≤  $\epsilon n$  if passes the test
- We show a large fractional matching using short edges
- Two step process:
  - Each point in  $f_G(\mathcal{M}_G)$  sends flow to hubs in  $f_G(\mathcal{M}_G)$
  - Each point in  $f_H(\mathcal{M}_H)$  receives flow from hubs in  $f_G(\mathcal{M}_G)$
- Each point sends/receives one unit, but hubs handle arbitrary amount of flow
- Amount sent to/received from point x proportional to  $\exp(-\delta(x,y) \cdot \operatorname{polylog} n)$
- For almost matching metrics: each hub receives and sends almost the same amount
- There is a close point: edges longer than some small threshold carry almost no flow

Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 18/22

Question: Do labels describe connectivity?

- Question: Do labels describe connectivity?
- Problem: Sampling pairs of similar labels more likely (Reason why Fischer & Matsliah didn't get  $\tilde{O}(n^{7/6})$ ?)

- Question: Do labels describe connectivity?
- Problem: Sampling pairs of similar labels more likely (Reason why Fischer & Matsliah didn't get  $\tilde{O}(n^{7/6})$ ?)
- Use rejection sampling to uniformly sample a label for V[G] with a colliding label for V[H]

- Question: Do labels describe connectivity?
- Problem: Sampling pairs of similar labels more likely (Reason why Fischer & Matsliah didn't get  $\tilde{O}(n^{7/6})$ ?)
- Use rejection sampling to uniformly sample a label for V[G] with a colliding label for V[H]
- Keep a sample with probability 1/(estimated-number-of-collisions)

- Question: Do labels describe connectivity?
- Problem: Sampling pairs of similar labels more likely (Reason why Fischer & Matsliah didn't get  $\tilde{O}(n^{7/6})$ ?)
- Use rejection sampling to uniformly sample a label for V[G] with a colliding label for V[H]
- Keep a sample with probability 1/(estimated-number-of-collisions)
- For independent endpoints, slight difference in labels shouldn't introduce too much error

- Question: Do labels describe connectivity?
- Problem: Sampling pairs of similar labels more likely (Reason why Fischer & Matsliah didn't get  $\tilde{O}(n^{7/6})$ ?)
- Use rejection sampling to uniformly sample a label for V[G] with a colliding label for V[H]
- Keep a sample with probability 1/(estimated-number-of-collisions)
- For independent endpoints, slight difference in labels shouldn't introduce too much error
- Accept if similar labels imply same connectivity most of the time

# **Final Remarks**

Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 20/22

• Is the  $2^{O(\sqrt{\log n})}$  factor necessary?

- Is the  $2^{O(\sqrt{\log n})}$  factor necessary?
- Can approximate the distance efficiently? Improve the running time?

- Is the  $2^{O(\sqrt{\log n})}$  factor necessary?
- Can approximate the distance efficiently? Improve the running time?
- Sparse graphs?
  - hyperfinite bounded-degree [Newman Sohler 2011] O(1) queries
  - arbitrary degree forests [Kusumoto Yoshida 2014] polylog(n) queries

- Is the  $2^{O(\sqrt{\log n})}$  factor necessary?
- Can approximate the distance efficiently? Improve the running time?
- Sparse graphs?
  - hyperfinite bounded-degree [Newman Sohler 2011] O(1) queries
  - arbitrary degree forests [Kusumoto Yoshida 2014] polylog(n) queries
- Unified framework for various kinds of isomorphisms? (graphs, functions, etc.)

Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 21/22

# **Questions?**

Krzysztof Onak – A Near-Optimal Algorithm for Testing Graph Isomorphism – p. 22/22