## LIE ALGEBRAS: LECTURE 1 16 March 2010

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## 1. Algebras

Let k be a field. An *algebra* over k (or k-algebra) is a vector space A, with a bilinear operation

$$A \times A \to A$$
$$(a,b) \mapsto a \cdot b.$$

Recall that bilinearity means that the function is linear over k in each argument, (i.e. preserves sum and multiplication by scalar).

An algebra A is called *associative* if  $a \cdot (b \cdot c) = (a \cdot b) \cdot c$  for all  $a, b, c \in A$ . An algebra A is called *commutative* if  $a \cdot b = b \cdot a$  for all  $a, b \in A$ .

Note that to describe an algebra it is enough to determine the product of elements from a vector space basis for A. It is sufficient to check associativity and commutativity of an algebra on basis elements.

**Example 1.1.** If  $K \subset K'$  are fields, then K' is an associative, commutative algebra over K. For instance,  $\mathbb{C}$  is an  $\mathbb{R}$ -algebra.

**Example 1.2.** The ring of polynomials  $k[x_1, \ldots, x_n]$  is an associative, commutative k-algebra.

**Example 1.3.** If V is a vector space,  $\operatorname{End}(V)$ , the set of (linear) endomorphisms of V is an associative algebra with respect to composition. It is not commutative if dim  $V \ge 2$ . If  $V = k^n$ , then  $\operatorname{End}(V)$  is just the algebra of  $n \times n$  matrices over k.

**Example 1.4.**  $\mathbb{R}^3$  with respect to the cross product (vector product)  $a \times b$  is an algebra. We will see that it is not commutative and not associative.

A vector subspace  $B \subseteq A$  is called a *subalgebra* if  $a, b \in B$  implies  $a \cdot b \in B$ . A vector subspace  $I \subseteq A$  is called an *ideal* if  $a \in A, x \in I$  imply  $a \cdot x, x \cdot a \in I$ .

A linear map  $f : A \to B$  of k-algebras is called a homomorphism if  $f(a \cdot b) = f(a) \cdot f(b)$  for each  $a, b \in A$ . A homomorphism is called an *isomorphism* if it is bijective.

**Lemma 1.5.** Let  $f : A \to B$  be a homomorphism of algebras. Then the image of f is a subalgebra of B. The kernel of f, Ker  $f = \{a \in A \mid f(a) = 0\}$ , is an ideal in A.

*Proof.* Let  $f(x), f(y) \in \text{Im } f$ , and  $c_x, c_y \in k$ . Then

$$c_x f(x) + c_y f(y) = f(c_x x + c_y y) \in \operatorname{Im} f.$$
  
$$f(x)f(y) = f(xy) \in \operatorname{Im} f.$$

Hence, Im f is a subalgebra of B. Let  $x, y \in \ker f$ , and  $c_x, c_y \in k$ . Then

$$f(c_x x + c_y y) = c_x f(x) + c_y f(y) = 0.$$

Let  $x \in \ker f$  and  $y \in A$ . Then

$$f(xy) = f(x)f(y) = 0$$
, and  $f(yx) = f(y)f(x) = 0$ .

Thus,  $c_x x + c_y y \in \ker f$  and  $xy, yx \in \ker f$ . Hence,  $\ker f$  is an ideal in A.  $\Box$ 

Let A be an algebra and I an ideal in A. We define the quotient A/I as follows. As a set this is the quotient of A modulo the equivalence relation

$$a \sim b \iff a - b \in I.$$

So this is the set of equivalence classes of the form a + I, where  $a \in A$ . The structure of a vector space on A/I is given by the formulas

$$(a+I) + (b+I) = (a+b) + I; \ \lambda(a+I) = \lambda a + I.$$

The algebra structure on A/I is given by the formula

$$(a+I)\cdot(b+I)_2 = a\cdot b + I.$$

One has a canonical projection homomorphism  $\rho : A \to A/I$ , defined by  $\rho(a) = a + I$ .

**Theorem 1.6.** Let  $f : A \to B$  be a homomorphism of algebras and let I be an ideal in A. Suppose that  $I \subseteq \text{Ker } f$ . Then there exists a unique homomorphism  $\overline{f} : A/I \to B$  such that  $f = \overline{f} \circ \rho$ , where  $\rho : A \to A/I$  is the canonical homomorphism. Moreover,  $\overline{f}$  is surjective iff f is surjective;  $\overline{f}$  is injective iff I = Ker f.

*Proof.* To satisfy the relation  $f = \overline{f} \circ \rho$  one needs that  $\overline{f}(a+I) = f(a)$  for all  $a \in A$ . This map is well-defined since a+I = b+I implies  $(a-b) \in I \subseteq \text{Ker } f$ , hence f(a) = f(b). Now

$$\overline{f}((a+I)(b+I)) = \overline{f}(ab+I) = f(ab) = f(a)f(b) = \overline{f}(a+I)\overline{f}(b+I),$$

and similarly we obtain

$$\overline{f}((a+I)+(b+I)) = \overline{f}(a+I) + \overline{f}(b+I), \quad \overline{f}(\lambda a+I) = \lambda \overline{f}(a+I).$$

Hence,  $\overline{f}$  is a homomorphism. Clearly, the image of  $\overline{f}$  coincides with the image of f and Ker $\overline{f} = \text{Ker } f/I$ . This implies the last assertion.

An element  $e \in A$  is called a *unity* if  $e \neq 0$  and ae = ea = a for all  $a \in A$ . Such an element is unique if it exists. We require that any homomorphism between two associative algebras with unity maps unity to unity. A *representation* of an associative k-algebra A with unity is a homomorphism  $\rho: A \to \text{End}(V)$ , where V is a vector space over k and  $\rho(1) = id$ .

## 2. Lie Algebras

A Lie algebra is a vector space L over a field k, with a bilinear operation  $L \times L \to L$ , denoted  $(x, y) \mapsto [x, y]$  and called the *bracket* or *commutator* of x and y, which satisfies the following axioms, for all  $x, y, z \in L$ :

(1) [x, x] = 0 (anticommutativity), (2) [x, [y, z]] = [[x, y], z] + [y, [x, z]] (Jacobi identity).

Note that property (1) implies that [x, y] = -[y, x] for all  $x, y \in L$ . If

char  $k \neq 2$ , then this condition is equivalent to (1).

Let A be an associative algebra with bilinear operation denoted  $x \cdot y$  for  $x, y \in A$ . We can define a new operation [-, -], called the bracket of x and y, as follows:

$$[x, y] = x \cdot y - y \cdot x.$$

Then A with the operation [-, -] is a Lie algebra.

**Example 2.1.** Let V be a finite dimensional vector space over k, and denote by End(V) the set of linear transformations  $V \to V$ . Then End(V) with the bracket operation [-, -] is a Lie algebra, which we write as  $\mathfrak{gl}(V)$ . It is called the *general linear algebra*. If we choose a basis for V, we may identify  $\mathfrak{gl}(V)$  with the set of  $n \times n$  matrices over k, and we denote this by  $\mathfrak{gl}_n(k)$ . The dimension of  $\mathfrak{gl}_n(k)$  is  $n^2$ .

Any Lie subalgebra of  $\mathfrak{gl}(V)$  is called a *linear Lie algebra*. It is a known (but non-trivial) fact that every finite dimensional Lie algebra is isomorphic to some linear Lie algebra (Ado's Theorem).

**Example 2.2.** Define  $\mathfrak{sl}_n = \{x \in \mathfrak{gl}_n \mid \operatorname{Tr}(x) = 0\}$ , where  $\operatorname{Tr}(x) = \sum x_{ii}$ , the sum of the diagonal elements of the matrix x. This is a Lie algebra since for any  $x, y \in \mathfrak{sl}_n$ ,

$$\operatorname{Tr}(c_x x + c_y y) = c_x \operatorname{Tr}(x) + c_y \operatorname{Tr}(y) = 0, \text{ and}$$
$$\operatorname{Tr}([x, y]) = \operatorname{Tr}(xy) - \operatorname{Tr}(yx) = 0.$$

 $\mathfrak{sl}_n$  is called the *special linear algebera*. It has dimension  $n^2 - 1$ .

## Example 2.3.

$$\mathfrak{sl}_2(k) = \left\{ \left( \begin{array}{cc} a & b \\ c & -a \end{array} \right) \mid a, b, c \in k \right\}$$

has as a basis

$$e = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \qquad f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \qquad h = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Then one can check that

$$[h, e] = 2e,$$
  $[h, f] = -2f,$   $[e, f] = h.$ 

Let A be an k-algebra, and let  $d : A \to A$  be a linear endomorphism of A (viewing A as a vector space, i.e.  $d \in \text{End}_k(A)$ ). Then  $d : A \to A$  is called a *derivation* if the following *Leibniz rule* holds:

$$d(a \cdot b) = d(a) \cdot b + a \cdot d(b).$$

The set of all derivations of A is denoted Der(A). It is a vector subspace of End(A). Let  $d, d' \in \text{Der}(A)$ . The composition dd' is not a derivation, however the bracket, defined as [d, d'] = dd' - d'd, is a derivation (i.e  $[d, d'] \in \text{Der}(A)$ ). This can be checked by direct calculation. Der(A) is a Lie subalgebra of  $\mathfrak{gl}(A)$ .

**Example 2.4.** Suppose L = k (i.e. dim L = 1). Let us find all possible Lie brackets on L. Bilinearity and anticommutativity require:

$$[a,b] = [a \cdot 1, b \cdot 1] = ab[1,1] = 0$$
, for all  $a, b \in L$ .

A Lie algebra with a zero bracket is called a *commutative Lie algebra*, or simply *abelian*.

Fix a field k (char  $k \neq 2$ ), and let  $L = \langle e_1, \ldots, e_n \rangle$  be an n-dimensional vector space over k. In order to define a bilinear operation, it is enough to define it on  $e_i$ :

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k.$$

The coefficients  $c_{ij}^k$  are called the *structure constants* of *L*. In order for *L* to be a Lie algebra, it is enough to require that the structure constants satisfy the following equations:

$$c_{ii}^{k} = 0 = c_{ij}^{k} + c_{ji}^{k},$$
  
$$\sum_{k} (c_{ij}^{k} c_{kl}^{m} + c_{jl}^{k} c_{ki}^{m} + c_{li}^{k} c_{kj}^{m}) = 0.$$

This follows from the antisymmetry of the bracket and the Jacobi identity.

**Example 2.5.** Suppose dim L = 2. Then the Jacobi identity automatically holds. Let us find all possible non-zero brackets on L. Choose a basis  $L = \langle e_1, e_2 \rangle$ . Then one has

$$[e_1, e_1] = [e_2, e_2] = 0, \ [e_1, e_2] = -[e_2, e_1]_5, \ \text{and} \ [e_1, e_2] = y, \ \text{for some non-zero} \ y \in L_5$$

Thus, every bracket in L is proportional y. So we choose y to be on of the generators of L, say  $L = \langle x, y \rangle$  and  $[x, y] = \lambda y$ . Since L is not commutative,  $\lambda \neq 0$ . Thus, by changing variables  $x := x/\lambda$  we obtain:

(2.1) 
$$L = \langle x, y \rangle$$
 and  $[x, y] = y$ .

Therefore, we have shown that there are only two 2-dimensional Lie algebras over k up to isomorphism: a commutative Lie algebra and the one described in (2.1).

**Example 2.6.**  $\mathbb{R}^3$  with respect to the cross product  $a \times b$  is a Lie algebra. Recall that the cross product is defined by

$$(a_1, a_2, a_3) \times (b_1, b_2, b_3) = \det \left( egin{array}{ccc} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{array} 
ight).$$

It is anticommutative (i.e.  $x \times y = -y \times x$ ) and defined by the formulas

$$e_1 \times e_2 = e_3, \ e_2 \times e_3 = e_1, \ e_3 \times e_1 = e_2.$$

This algebra has no non-trivial ideals. Indeed, let I be a non-zero ideal and  $a \in I$  be a non-zero element. Let a, b, c be a basis consisting of mutually orthogonal elements. Then [a, b] is a non-zero multiple of c, and [a, c] is a non-zero multiple of b. Thus  $a \in I$  forces  $a, b, c \in I$ , that is I = L.

We call an a Lie algebra L simple if dim $(L) \ge 2$  and L has no non-trivial ideals.