

Gil

11/03/14

\mathcal{K} - a family of sets $\mathcal{K} = \{K_1, \dots, K_n\}$

The nerve of \mathcal{K} is a simp. complex:

$$N(\mathcal{K}) = \{S \subset [n] : \bigcap_{i \in S} K_i \neq \emptyset\}$$

Simplicial complexes, homology, related topology

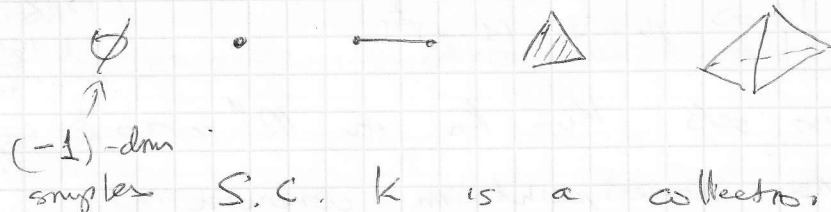
Simplex is the convex hull of aff. incl.

points, in a linear space.

If K is a convex body set, then

$\dim K = \dim \text{affine span of } K$.

$\dim \text{Simplex} = \text{Vertices} - 1$.



S.C. K is a collection of simplices:

1) if $T \in K$ and S is a face of T , then $S \in K$.

2) If $T_1, T_2 \in K$, then $T_1 \cap T_2$ is

~~a~~ the simplex spanned by

$V_*(T_1) \cap V(T_2)$, i.e. this is not allowed!



The total space of K , denoted: $|K|$ is the union of all simplices. $|K|$ is a top. space,

K is called a triangulation of $|K|$.

Abstract simp. complex K is a collection of subset of a vertex set V . with the property that $S \in K, R \subset S \Rightarrow R \in K$. ($\emptyset \in K$)

ASC \rightarrow GSC

$V = \{v_1, \dots, v_n\}$, \mathbb{R}^n , $\{e_1, \dots, e_n\}$ standard

$S \in K$, $S = \{v_{i_0}, \dots, v_{i_k}\} \Rightarrow \{e_{i_0}, \dots, e_{i_k}\}$

If $\dim K = \max \{ \dim F : F \text{ face of } K \} = d$

choose x_1, \dots, x_n pts in general position in \mathbb{R}^{2d+1}

Comments: For d -dim manifolds you can replace $2d+1$ by $2d$ (Whitney trick)

K is 1-dimensional $\Rightarrow K$ is a graph

but $K \hookrightarrow \mathbb{R}^2$ is very rare.

(Lipton, Tanjar) For $V(G) = n$ planar $G \exists U \subset V(G)$

$|U| = \sqrt{n}$, and when we remove U , every connected

component is of size $\leq \frac{2}{3}n$.

i.e. expanders are not planar

Question: Is it the case that 2-dim expanders cannot be embedded into \mathbb{R}^4 ?

K some complex $F \in K$,

$\{T \in K : T \supset F\}$, $\{T \in K : T \not\supset F\}$

this is the link of F in K , denote by $\text{link}(F, K)$.

Star of F in K is $\{T \in K : T \supset F\}$

Anti-star of F in K is $\{T \in K : T \not\supset F\}$

$\text{Star}(F, K) = F * \text{link}(F, K)$.

$$\begin{aligned} \langle \delta^+, x_V \rangle &= \sum_{e \in \mathcal{E}} \delta(e) \\ \langle \delta^-, x_V \rangle &= \sum_{e \in \mathcal{E}} \delta(e) \\ \langle \Delta \delta, x_V \rangle &= \sum_{u \in V} \langle \delta, x_u \rangle = \sum_{u \in V} \delta(u) \\ \langle \delta^+, \delta^+ \rangle &= 2 \langle \delta^+, \delta^- \rangle \end{aligned}$$

Homology

K -sc $V(K) = \{1, 2, \dots, n\}$

$R = \mathbb{Z}/2\mathbb{Z}$, chain complex ass. to K : $\bigoplus C_i(K)$

$C_i(K) =$ free R module spanned by i -faces of K .

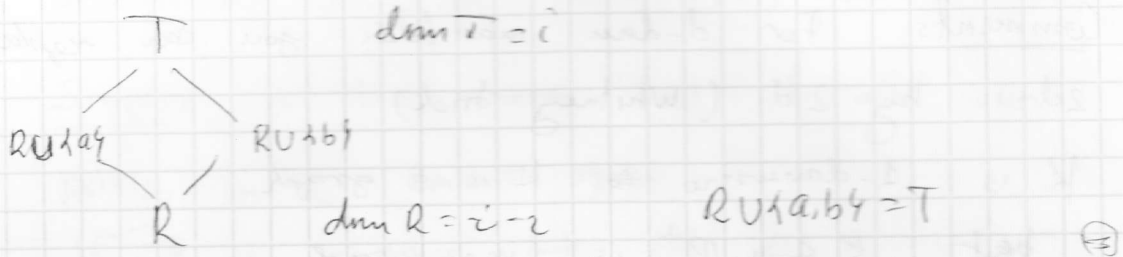
traditionally $c=0$
somehow $c=-1$

Boundary operator

$$\partial_i: C_i(K) \rightarrow C_{i-1}(K)$$

$$\partial T = \sum \{S: S \subset T, \dim S = \dim T - 1\}$$

$$\partial_{i-1} \partial_i = 0 \quad \text{sketch:}$$



cycles $Z_i(K) = \{x \in C_i(K) : \partial_i x = 0\}$

boundaries $B_i(K) = \{x \in C_i(K) : x = \partial_i y, y \in C_{i+1}(K)\}$

$$Z_i \subset B_i$$

homology $\rightarrow H_i(K) = Z_i / B_i$

For a general ring R there are two ways to define:

- ordering of vertices

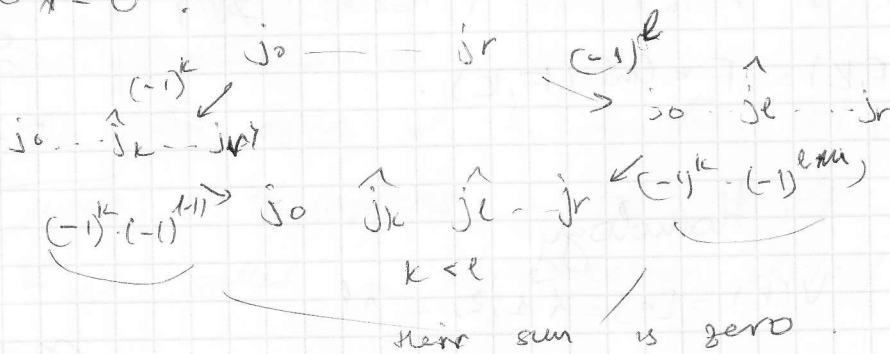
- orientation

We'll choose the ordered way:

$$T = \{j_0 < \dots < j_r\} \text{ - r-face}$$

$$\partial T := \sum_{k=0}^r (-1)^k \{j_0, \dots, \overset{\uparrow}{j_k}, \dots, j_r\}$$

$$\partial \partial T = 0$$



Given K , $H_i(K)$ is a topological invariant of K .

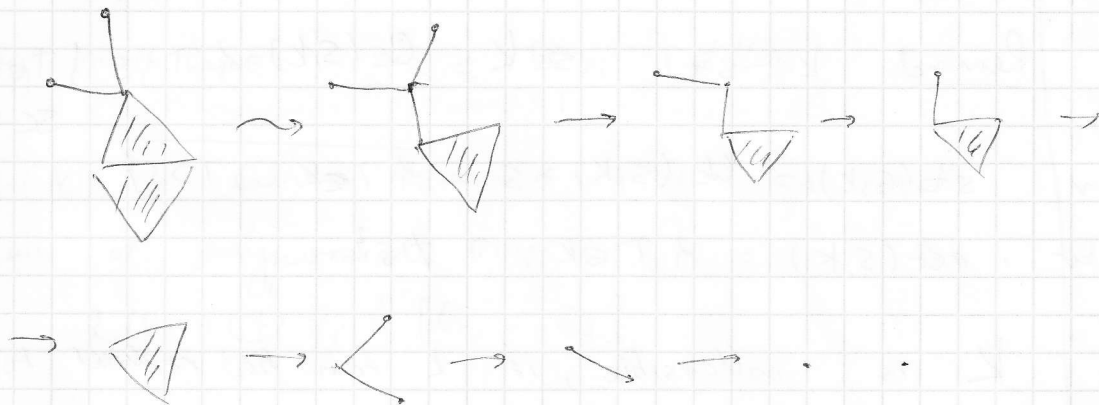
$f: X \rightarrow Y$ induces $f_*: H_i(X) \rightarrow H_i(Y)$
continuous

X contractible : $H_i(X) = H_i(\cdot)$

Collapsibility

A face F in s.c. K is free if it's contained in a unique max. face

Elementary collapse of K is the deletion of a free face of dim i and a max face contain it of dim $i+1$



K is called collapsible if it can be reduced to a point by a series of elem. collapses.

Graph is collapsible \Leftrightarrow it is a tree.

An example of a space which is contractible but not collapsible