# Randomized Algorithms 2015A Lecture 12 – Compressed Sensing and RIP matrices<sup>\*</sup>

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#### 1 Compressed Sensing

**Problem definition:** We wish to learn an unknown vector  $x \in \mathbb{R}^n$  through linear measurements, which means we choose a vector  $a \in \mathbb{R}^n$  and observe the inner-product  $a^T x$ .

We want to minimize m, the number of linear measurements. If they are non-adaptive, then the measurement algorithm (without decoding part) can be described as a matrix  $A \in \mathbb{R}^{m \times n}$ .

**Naive solution:** Any choice of m = n linear measurements that are linearly independent (i.e., A is invertible) is clearly sufficient (and also necessary).

**Sparsity:** We may know (by "prior information") that x is k-sparse, i.e., has at most k non-zeros. We will actually focus on almost k-sparse vector in the sense that x = x' + z where x' is sparse and z is "noise", say  $||z||_1$  is small. This is essentially a linear sketch for sparse inputs.

Exer: See if the results about sketching heavy hitters can be used here and what bounds do they imply.

Turns out that  $m = O(k \log n)$  measurements suffice, and A can be taken to be a matrix of independent Gaussians.

Algorithmic approach: Recall we are given the vector of observations, which is the product Ax. Under exact k-sparsity  $||x||_0 \le k$ , an ideal algorithm could be to solve

 $\min\{\|x^*\|_0 : Ax^* = Ax\}.$ 

In the general case, our algorithm will minimize instead the  $\ell_1$ -norm

 $\min\{\|x^*\|_1 : Ax^* = Ax\}.$ 

Exer: Verify that solving this problem (computing  $x^*$ ) can be done in polynomial time using linear programming.

<sup>\*</sup>These notes summarize the material covered in class, usually skipping proofs, details, examples and so forth, and possibly adding some remarks, or pointers. The exercises are for self-practice and need not be handed in. In the interest of brevity, most references and credits were omitted.

**Theorem 1:** Define  $E_1^k(x) = \min\{||x - x'||_1 : x' \text{ is } k\text{-sparse}\}$ . Then with probability at least 1 - 2/n over the choice of A,

$$\|x^* - x\|_2 = O(E_1^k(x)/\sqrt{k}).$$
(1)

This formalizes the scenario mentioned above, with  $E_1^k(x) = ||z||_1$ , and then the approximation to true x' depends only on magnitude of noise. In particular, if x was exactly k-sparse, then we obtain exact recovery.

The statement provides a so-called "for each" guarantee – for each  $x \in \mathbb{R}^n$ , with high probability the approximation (1) holds. We will actually prove something stronger, called "for all" guarantee – with high probability the approximation (1) holds for all  $x \in \mathbb{R}^n$ .

**RIP:** The key will be to prove that WHP A has the following property: A matrix  $A \in \mathbb{R}^{m \times n}$  satisfies the  $(k, \delta)$ -Restricted Isometry Property (RIP) if for every k-sparse vector  $x \in \mathbb{R}^n$ ,

$$(1-\delta)\|x\|_{2} \le \|Ax\|_{2} \le (1+\delta)\|x\|_{2}.$$
(2)

Remark: this condition is equivalent to requiring that for every submatrix of A a consisting of k columns, all the singular values lie in the range  $[1 - \delta, 1 + \delta]$ .

The theorem follows immediately from the following two theorems.

**Theorem 2:** For suitable  $m = O(k \log n)$ , if the entries of  $A \in \mathbb{R}^{m \times n}$  are independent Gaussians with distribution N(0, 1/k), then with property at least 1 - 2/n, matrix A is (k, 1/3)-RIP.

**Theorem 3:** If A is (25k, 1/3)-RIP then (for all x) (1) holds.

### 2 Constructing RIP matrix (Proof of Theorem 2)

#### Claim 4 (Crude Bound): WHP,

 $\forall x \in \mathbb{R}^n, \qquad \|Ax\|_2 \le n^2 \|x\|_2.$ 

The proof, based on straightforward calculation, was seen in class.

**Proof of theorem 2:** The proof seen in class is based on a union bound over all subsets  $T \subset [n]$  of size |T| = k; for each such T, the problem reduces to proving that for a matrix  $B \in \mathbb{R}^{m \times k}$  of independent Gaussians N(0, 1/k), with high probability

$$\forall y \in \mathbb{R}^k, \qquad \frac{2}{3} \|y\|_2 \le \|By\|_2 \le \frac{4}{3} \|y\|_2. \tag{3}$$

The latter is achieved by discretizing the unit sphere in  $\mathbb{R}^k$ , using Claim 5 below, applying on that discrete set the JL-lemma, and then extending the bound to the entire sphere. Overall, we get a failure probability  $\binom{n}{k}|P|2^{-\Omega(m)} \leq 2^{O(k\log n)-\Omega(m)} \leq 1/n$ , which proves Theorem 2.

**Claim 5:** For every  $\varepsilon \in (0,1)$  there is a set  $P \subset S$  of size  $O(1/\varepsilon)^k$  that is an  $\varepsilon$ -net of S, i.e., for every  $x \in S$  there is  $p \in P$  such that  $||p - x|| \leq \varepsilon$ .

Exer: Does the analysis above actually work for  $m = O(k \log \frac{n}{k})$ ? (This is effective to beat the trivial bound m = n when k is "large".)

Exer: Let the matrix  $A \in \mathbb{R}^{n \times n}$  have independent  $\{\pm 1\}$  entries. Prove that with high probability  $||A||_2 = \sup_{||x||_2=1} ||Ax||_2$  is at most  $O(\sqrt{n \log n})$ . (Using one more idea, it is actually possible to prove a better bound of  $O(\sqrt{n})$ .)

## 3 $\ell_1$ -decoding (Proof of Theorem 3)

To simplify notation, let  $h = x^* - x$ , and recall our goal is to bound  $||h||_2$ . WLOG order the coordinates such that

- $|x_1|, ..., |x_k|$  are all at least  $|x_{k+1}|, ..., |x_n|$ .
- $|h_{k+1}| \geq \cdots \geq |h_n|.$

Define the sets of indices

- $T_0 = \{1, \ldots, k\}$
- $T_1 = \{k+1, \dots, 26k\}$
- $T_2 = \{26k + 1, \dots, 51k\},\$

and so forth. Notice that  $|T_0| = k$  and  $|T_i| = 25k$  for all  $i \ge 1$ .

Define also  $T_{01} = T_0 \cup T_1$ , and  $\overline{T_0} = [n] \setminus T_0$ . Let  $X_T$  be the restriction of x to coordinates in the set T, and define (recall our ordering)

$$\varepsilon = E_1^k(x) = \|x_{\overline{T_0}}\|_1.$$

Recall that our goal is to bound  $||h||_2 \leq O(1/\sqrt{k})\varepsilon$ .

**Claim 6:**  $||h_{\overline{T_0}}||_1 \le ||h_{T_0}||_1 + O(\varepsilon).$ 

**Claim 7:**  $\|h_{\overline{T_{01}}}\|_2 \le \|h_{T_0}\|_2 + O(\varepsilon/\sqrt{k}).$ 

**Claim 8:**  $||h_{T_{01}}||_2 \le O(\varepsilon/\sqrt{k}).$ 

**Proof of Theorem 3:** Using triangle inequality, then Claim 7 and then 8,

$$\|x^* - x\|_2 = \|h\|_2 \le \|h_{T_{01}}\|_2 + \|h_{\overline{T_{01}}}\|_2 \le 2\|h_{T_{01}}\|_2 + O(\varepsilon/\sqrt{k}) \le O(\varepsilon/\sqrt{k}).$$

QED.

We did not cover in class the proof of the three claims above; their proof can be found in Nick Harvey's lecture notes (Lecture 8). (Claim 6 is needed to prove of Claims 7 and 8.)